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MARTIN MARIETTA

Multifrequency Eddy-Current Inspection of Seam Weld in Steel Sheath

J. H. Smith
C. V. Dodd
L. D. Chitwood



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MARTIN MARIETTA ENERGY SYSTEMS, INC.
FOR THE UNITED STATES
DEPARTMENT OF ENERGY

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MULTIFREQUENCY EDDY-CURRENT INSPECTION
OF SEAM WELD IN STEEL SHEATH

J. H. Smith, C. V. Dodd, and L. D. Chitwood

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CONTENTS

ABSTRACT	1
INTRODUCTION	1
DESCRIPTION OF PROBLEM	2
INSPECTION REQUIREMENTS	3
THEORY OF MULTIFREQUENCY EDDY-CURRENT INSPECTION	5
GENERAL PROCEDURE TO DESIGN A MULTIPLE-PROPERTY EDDY-CURRENT TEST	9
INSTRUMENTATION, EDDY-CURRENT PROBE, AND SCANNING SYSTEM	11
TEST SAMPLES	21
CALIBRATION AND TRAINING OF TEST SYSTEM	26
SCANNING THE SHEATH WELD	33
PERFORMING THE INSPECTION ON THE PRODUCTION LINE	38
INITIAL SYSTEM CHECK	40
PRECALIBRATION	43
PERFORMING THE TEST	43
POSTCALIBRATION	45
MANUAL INSPECTION FOR WELD REPAIRS	45
SUMMARY AND CONCLUSIONS	47
ACKNOWLEDGMENTS	48
REFERENCES	48
Appendix A. PROGRAM BIGRDG	51
Appendix B. PROGRAM MICMOD	63
Appendix C. PROGRAM BIGFIT	69
Appendix D. PROGRAM PLTRDG	81
Appendix E. PROGRAM SQRWLD	91
Appendix F. PROCEDURE FOR PERFORMING THE AUTOMATED MULTIFREQUENCY EDDY-CURRENT INSPECTION OF THE SHEATH WELD ON THE SUPERCONDUCTOR CABLE	123
Appendix G. PROCEDURE TO CHECK DIGITAL RECORDING SYSTEM	143
Appendix H. PROGRAM CHECK	151
Appendix I. PROCEDURE FOR PERFORMING THE MANUAL EDDY-CURRENT INSPECTION OF THE SHEATH WELD ON THE SUPERCONDUCTOR CABLE	165

MULTIFREQUENCY EDDY-CURRENT INSPECTION
OF SEAM WELD IN STEEL SHEATH*

J. H. Smith, C. V. Dodd, and L. D. Chitwood

ABSTRACT

Multifrequency eddy-current techniques were used to perform a continuous on-line inspection of the seam weld in the steel jacket for a superconducting cable. The inspection was required to detect both surface and internal weld flaws in the presence of a large, highly conductive central conductor. Raw eddy-current data were recorded on magnetic tape, and test properties such as discontinuity size and weld penetration were determined by mathematically fitting these data to coefficients developed with representative standards. A sophisticated computer-controlled scanning technique was applied, and a unique scanning device was developed to provide full coverage of the weld and heat-affected zone. The techniques used to develop this multifrequency eddy-current examination are described in this report along with the test equipment, test procedures, and computer programs.

INTRODUCTION

The Large Coil Program (LCP), a major program activity of the Fusion Energy Division at the Oak Ridge National Laboratory (ORNL), is developing and testing large coils for use as superconducting magnets in the fusion energy study. Several international companies have been contracted to build large superconducting magnet coils using different designs and materials, but adhering to the same performance specification and envelope requirements. When completed, these coils will be tested at the ORNL Large Coil Test Facility (LCTF).

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As part of the United States Large Coil Program managed by ORNL, Westinghouse and Oxford-Airco have cooperated in the design and fabrication of a large superconducting magnet that used one of the most sophisticated superconductors ever attempted. The wire manufacturing process, for example, involved two extrusions, approximately 20 heat treatments, and over 50 separate wire drawing operations. After the wire was fabricated, it was twisted into a cable containing 486 strands. The cable was wrapped with a thin Inconel foil, then a steel jacket was formed around the conductor and seam welded along its length. This jacket formed a cryogenic vacuum vessel that was required to be helium leak tight at a temperature of 4 K and a pressure of approximately 10 MPa (100 atm).

The most probable area for leaks was the seam weld; therefore, some type of nondestructive test was needed to evaluate the quality of this weld. The size and geometry of the sample and the need to perform the test continuously along the weld on a production line basis made eddy currents the most logical nondestructive testing (NDT) method to try. Studies using conventional eddy-current techniques encountered significant difficulties because of large irregular signals generated by the twisted conductor and other materials present in the cable assembly. The large background signals and the number of significant variables that changed during the test made the examination by conventional eddy-current methods virtually impossible. This problem was brought to the ORNL Nondestructive Testing Development Laboratory, where prior theoretical and experimental studies had resulted in a capability to solve multiparameter problems by use of multifrequency eddy-current techniques. This report describes the application of these techniques to inspect the weld in the steel sheath for the superconductor cable. Although available funds and time limited the amount of development for computer processing of data, a very useful system was developed.

DESCRIPTION OF PROBLEM

The problem as initially defined was to nondestructively inspect the seam weld of the type JBK-75 steel sheath or jacket surrounding a superconducting cable. This steel is an alloy steel that has properties very

similar to those of A-286 stainless steel. The cable consisted of 486 strands of wire that had been twisted and wrapped with a thin [approximately 0.05-mm (0.002-in.)] Inconel foil. Each strand of wire consisted of a copper-coated composite of 2869 filaments of 3.5- μ m Nb₃Sn. A 1.7-mm-thick (0.067-in.) steel sheet was wrapped around the cable and foil to form a butt joint, which was welded autogenously by a gas tungsten arc technique. The welded steel jacket forms a cryogenic vacuum vessel for the cable. It was required to be helium leak tight at a temperature of 4 K and a pressure of 10 MPa (100 atm). The JBK-75 steel plate was ultrasonically inspected before the sheath was formed;¹ therefore, the obvious area of concern for possible leaks was the seam weld and heat-affected zone.

INSPECTION REQUIREMENTS

The initial requirements were to inspect the seam weld and HAZ for defects or discontinuities that could cause leaks in the sheath. The test had to be performed from the outside surface of the welded sheath and in the presence of the large conducting cable. It also had to be performed at the superconductor cable assembly site (the Oxford-Airco plant in Carteret, New Jersey). Personnel there had to be trained for eddy-current testing, and written procedures were required to describe the necessary steps to perform the examination. The test also had to be performed continuously on the production line as the weld was being made. [One of the assembly requirements for the superconductor cable and sheath was that they be formed continuously for lengths up to 100 m (~328 ft).] The test was required to detect any crack oriented longitudinal to the weld and having a length of 19 mm (0.75 in.) and a depth of 0.82 mm (0.032 in.) and to detect any transverse crack having a depth of 1.62 mm (0.064 in.) and visible on the surface of the sheath. (After the multifrequency eddy-current inspection method was developed and we had determined its capabilities, additional test requirements were added.) The final test requirements were to inspect the weld and heat-affected zone for defects of the size indicated above and to inspect the weld for lack of fusion,

lack of penetration, and sag in the weld crown. The test was performed continuously for weld lengths up to 100 m with the weld moving through the inspection station at a rate of 0.6 m/min (~ 2 ft/min).

The eddy-current inspection station was located as near to the weld station as possible to allow for quick corrections when errors such as insufficient penetration or the weld beam straying off the joint were detected. Even though the sheath and weld were quenched after the weld operation, they still had a temperature above ambient when they reached the eddy-current inspection station. We therefore had to account for material property changes (e.g., electrical conductivity) due to temperature variation during the inspection. Figure 1 shows a block diagram of the major operations and the location of the various stations used to assemble the superconducting cable and sheath. Because the eddy-current system was near the gas tungsten arc welder, we also tested whether the electrical noise generated by the welding operation was picked up by the eddy-current instrumentation or the recorders. No noise problem existed, but we did use an isolation transformer in the main power line for the instrument. Later in the program we had to move the eddy-current inspection farther downstream in the assembly line because of a change in the welding procedure.

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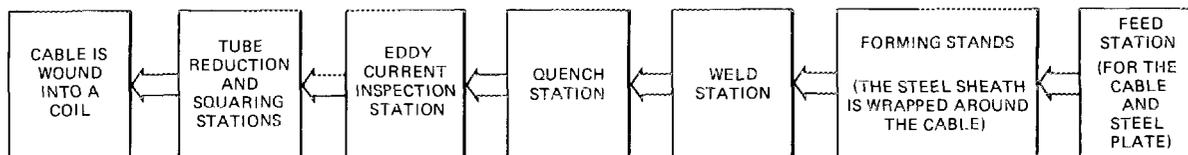


Fig. 1. Block diagram of production assembly line for the superconductor cable and sheath.

The cross section of the cable and sheath at the time of welding was round, having a diameter of about 25 mm (1 in.). The cable and sheath assembly then went through a forming operation that compacted the cable and changed the cross section to a square (21 by 21 mm). Figure 2 shows the cross sections of the two superconductor cable configurations.

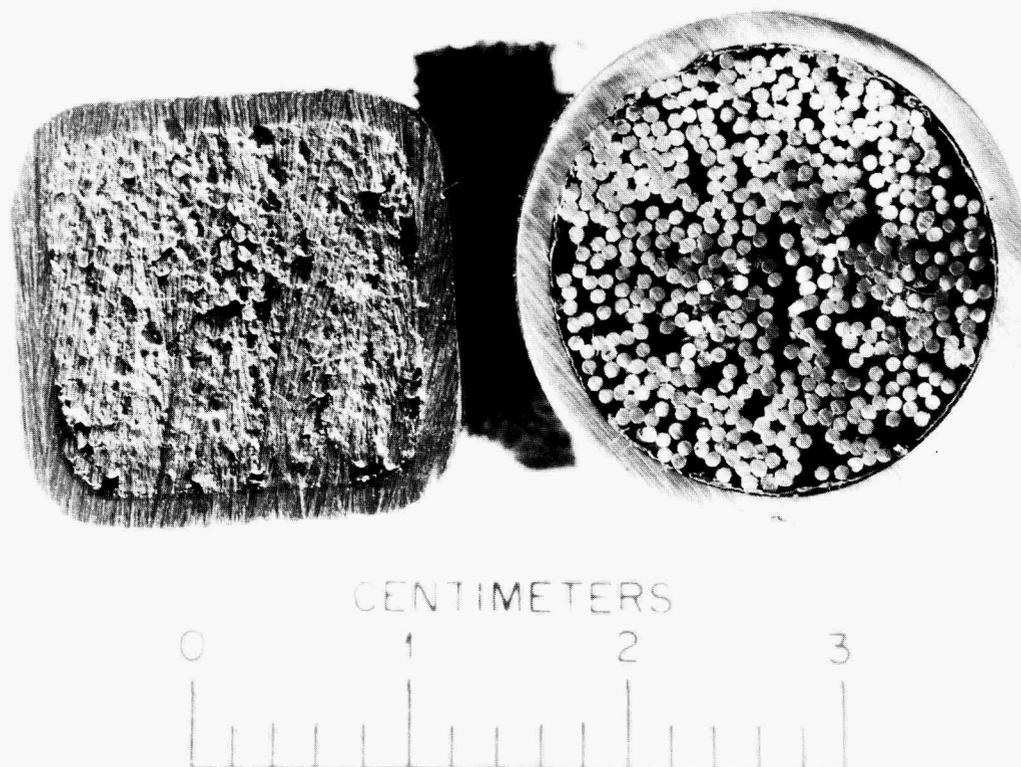


Fig. 2. Cross sections of cable. Left, after forming. Right, as welded.

The superconductor cable and sheath had a round cross section when the production line inspection was performed. Subsequent eddy-current inspections were performed on the cable and sheath with the square cross section to relocate and evaluate areas where indications had been obtained during the production test to determine if weld repairs were needed. An electromechanical circuit was developed to automatically mark areas on the superconductor sheath weld where the eddy-current signal exceeded a selected level. The areas that required weld repair were also reinspected to assure that a satisfactory weld repair had been made.

THEORY OF MULTIFREQUENCY EDDY-CURRENT INSPECTION

Many different parameters can influence eddy-current measurements; therefore the unique determination of a given sample property when other

properties also vary is usually difficult or impossible unless sufficient data are obtained to eliminate the effects of unwanted variables. In general, at least as many independent eddy-current readings must be made on a given specimen as there are properties whose variation may affect the readings. If sinusoidal eddy currents are used, one can determine no more than two quantities, such as the magnitude and phase, at a given fixed frequency. Therefore, if more than two properties need to be determined, multiple-frequency, pulsed, or swept-frequency eddy currents must be used. Since multifrequency techniques were applied to this particular problem, only that method will be considered in this report. More detailed descriptions of the use of multifrequency eddy-current techniques to solve multiple-property problems have been reported.²⁻⁴

No more than two pieces of information can be obtained from a given sample with an eddy-current instrument operating at a single frequency, for example, the magnitude and phase of the output voltage. However, many sample properties can affect the readings, and their effects are so interrelated that various combinations of the properties could produce the same pair of instrument readings. Therefore, to distinguish the actual properties from other possible combinations, one must make at least as many independent readings as there are parameters that can vary and affect the readings. This can be done by using magnitude and phase readings at N different fixed frequencies to obtain $2N$ pieces of information.

Assume that N properties, such as conductivity, permeability, lift-off or fill factor, wall thickness, and defects, may affect the readings. Let P_{ij} be an array of properties in which $j = 1, 2, \dots, N$ gives the particular property or parameter, and $i = 1, 2, \dots, M$ is the index giving the particular sample. We can write the array as

$$P_{ij} = \begin{pmatrix} P_{11} & P_{12} & \dots & P_{1N} \\ P_{21} & P_{22} & \dots & P_{2N} \\ \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \\ \cdot & \cdot & \cdot & \\ P_{M1} & P_{M2} & \dots & P_{MN} \end{pmatrix} \quad (1)$$

Let us also suppose that the set of properties P_{ij} ($j = 1, 2, \dots, N$) for the i th sample produces a set of N' independent readings R_{ik} ($k = 1, 2, \dots, N'$), where $N' > N$. We want to obtain a set of formulas such that, for the i th set of properties,

$$\begin{aligned} P_{i1} &\doteq F_1 (R_{i1}, R_{i2}, \dots, R_{iN'}) \\ P_{i2} &\doteq F_2 (R_{i1}, R_{i2}, \dots, R_{iN'}) \\ &\cdot \\ &\cdot \\ &\cdot \\ P_{iN} &\doteq F_N (R_{i1}, R_{i2}, \dots, R_{iN'}) \end{aligned} \quad (2)$$

where $i = 1, 2, \dots, M$, and the symbol \doteq indicates that the functions F_1, F_2, \dots, F_N provide only approximations to the corresponding properties. To obtain good approximations we may wish to expand the readings into polynomials, such as

$$P_{ij} \doteq F_j = \sum_{n_1=0}^{N_1} \sum_{n_2=0}^{N_2} \dots \sum_{n_{N'}=0}^{N_{N'}} C_{jn_1 n_2 \dots n_{N'}} R_{i1}^{n_1} R_{i2}^{n_2} \dots R_{iN'}^{n_{N'}} \quad (3)$$

where $N_1, N_2, \dots, N_{N'}$ are the highest powers of the readings $R_{i1}, R_{i2}, \dots, R_{iN'}$ in the polynomial. To determine all of the coefficients $C_{jn_1 n_2 \dots n_{N'}}$ (see above) for the j th property, one must have at least as many sets of readings ($i = 1, 2, \dots, M$) as there are coefficients to be determined. If M is greater than the number of coefficients to be determined, then a linear least-squares fitting program can be used to determine the set of coefficients to minimize the sum of squares

$$S_j = \sum_{i=1}^M (P_{ij} - F_j)^2 \quad (4)$$

for the j th property. This is done by a subroutine in the data-fitting program, which numbers the coefficients consecutively. The first term in the polynomial expansion F_j is the constant $C_{j00\dots0}$, which is called the "offset." It may be equal to zero.

Once the polynomial coefficients have been determined to calculate a given property with the desired accuracy, they can be used to calculate that property for an unknown sample if the properties of the unknown sample fall within the range of validity of the polynomial expansion. This is assured by fitting the polynomial to a range of variations that is at least as great as that expected for the unknown samples.

Thus, dropping the index i from Eq. (3), we can calculate the property P_j of an unknown sample from the readings $R_1, R_2, \dots, R_{N'}$ by the formula

$$P_j \doteq F_j = \sum_{n_1=0}^{N_1} \sum_{n_2=0}^{N_2} \dots \sum_{n_{N'}=0}^{N_{N'}} C_j n_1 n_2 \dots n_{N'} R_1^{n_1} R_2^{n_2} \dots R_{N'}^{n_{N'}} \quad (5)$$

After examining this formula, it appears that any desired precision can be obtained by making the polynomial large enough, and this is indeed true. If the number of sets of measured properties, M , is equal to the number of sets of linearly independent readings, N' , then a unique and exact fit can be obtained for the M values of each property by using only linear terms. However, the function F_j may fluctuate drastically between the fitted points so that intermediate values of the property would not be fitted well.

Furthermore, if each reading R_j is subject to a certain amount of random error, ΔR_j , so that the polynomial becomes

$$F_j = \sum_{n_1=0}^{N_1} \sum_{n_2=0}^{N_2} \dots \sum_{n_{N'}=0}^{N_{N'}} C_j n_1 n_2 \dots n_{N'} (R_1 \pm \Delta R_1)^{n_1} (R_2 \pm \Delta R_2)^{n_2} \dots (R_{N'} \pm \Delta R_{N'})^{n_{N'}} \quad (6)$$

then we see that the random errors, particularly in the terms involving high powers, may lead to considerable error. The worst possible combination of errors, in which all the errors in the value of the property are in the same direction, will be called the "DRIFT." In the curve-fitting program used to fit the experimental data, the worst possible combination of errors produced by changes of 0.01% in each magnitude and 0.01° in each phase are calculated and printed as the DRIFT, since errors of this amount are characteristic of current eddy-current equipment.

Because most material properties will not oscillate rapidly in a limited range of any given parameter, cubic or higher powers of the readings are rarely necessary or even useful to fit a given property.

Details on the linear least-squares curve-fitting procedure have been given.²⁻³ The coefficients $C_{jn_1n_2\dots n_N}$ in Eq. (3) are determined by a subroutine in the data fitting program used to minimize the sum of squares in Eq. (4).

GENERAL PROCEDURE TO DESIGN A MULTIPLE-PROPERTY EDDY-CURRENT TEST

The overall design of a multiple-property eddy-current test involves two efforts, an analytical study and an experimental study of the given problem. The analytical study is theoretical; it involves only the use of our laboratory minicomputer and appropriate software, and no actual instrument hardware or test standards are required. Appropriate computer programs have been written at ORNL to allow this study. The analytical study can be described in three steps.

1. Eddy-current instrument readings (magnitude and phase) are theoretically calculated with the minicomputer for a number of different frequencies and for a range of values for the test properties that are anticipated to vary.

2. The minicomputer is then used to perform a least-squares fitting of user-selected polynomials (constructed from the theoretically calculated magnitude and phase readings) to obtain the various desired properties.

3. The fit error (how well the chosen polynomial can be used to calculate the specified property) is determined. The drift error is also determined [how much the calculated property will change for small changes in the signal readings (magnitude and phase)].

The above three steps are repeated for different probe designs and frequency combinations until the drift errors are minimized or are acceptable for the given test conditions.

An analytical study is helpful to determine the correct probe design and frequency values to provide optimum test results. The analytical study is not absolutely essential, but it is very useful to determine the

feasibility of the examination, and it can be used to predetermine the accuracy for measuring any particular property and the allowable tolerances in the instrumental parameters.

An analytical study was not performed for this particular examination problem because of critical deadlines in the fabrication schedule for the superconductor cable. Essentially we used our experience, engineering judgment, and a few experimental measurements to determine the best combination of frequencies and coil design to use. In fact, the first selected coil design did not meet all the test requirements, and a different coil was selected for the final test.

Once the analytical study has been completed and the coil design and operating frequencies have been selected, the next step in designing a multiple-property eddy-current test is to perform the experimental study as follows.

1. The optimum instrumentation is constructed or assembled from existing modules, and the optimum probe is obtained. The instrument is assembled, it is adjusted to the desired frequencies, and calibration standards that cover the range of expected property variations are obtained. Obtaining a representative set of test samples is one of the most important and most difficult tasks associated with solving any non-destructive examination problem. This particular study was not atypical. The test requirements changed several times before a final solution was obtained, and the changes required new, different, or additional test samples to be fabricated. Rather than belabor these problems in this report, we will discuss only the test samples that were used to obtain the final solution to the problem.

2. The test instrumentation is calibrated, and a set of data (magnitude and phase readings) that represents the concerned property variations is made from the test samples. These data are recorded with a minicomputer, averages and standard deviations are calculated, and the data are stored in the computer's memory.

3. A least-squares fit is made of the selected properties to the polynomials containing the actual magnitude and phase readings recorded in step 2. This is accomplished by use of the minicomputer and the software

developed at ORNL. Various selected polynomials are constructed from the actual experimental readings, and the properties of interest are fit to these polynomials. The fit and drift errors are calculated to determine how well the particular property can be determined.

4. When the optimum or a sufficiently accurate fit is obtained, the coefficients for the polynomial representing the selected property determination are recorded and stored on a programmable read-only memory (PROM) chip. The PROM chip containing the coefficients is placed in the microcomputer circuit for the multiple-frequency eddy-current (MFEC) instrument. Selected properties to be measured can now be calculated from actual magnitude and phase readings by the microcomputer system in the MFEC instrument.

5. The final step is to field test the inspection system on site by examining test samples and other representative samples and calculate the desired properties, to evaluate how well the test system will perform in the actual environment that will be used.

INSTRUMENTATION, EDDY-CURRENT PROBE, AND SCANNING SYSTEM

The three-frequency eddy-current instrument used for this study is shown in Fig. 3. A block diagram of the instrument is shown in Fig. 4. This instrument will simultaneously measure both the magnitude and phase of the eddy-current signal at three different frequencies: 20, 200, and 500 kHz. The eddy-current instrument can record raw data readings and then calculate the specified properties with an internal microcomputer. The instrument can also interface with a larger minicomputer to permit more complicated data analyses, such as least-squares fitting. This instrument was developed at ORNL, and a thorough description has been provided.⁵

The extended module in Fig. 3 contains the NDT-COMP9A microcomputer, the analog-to-digital converter, the digital-to-analog converter, and the transceiver unit. The NDT-COMP9A is a self-contained, eight-bit microcomputer system designed specifically for experiment control and data analysis with the modular eddy-current instrument. The unit has 16 K of

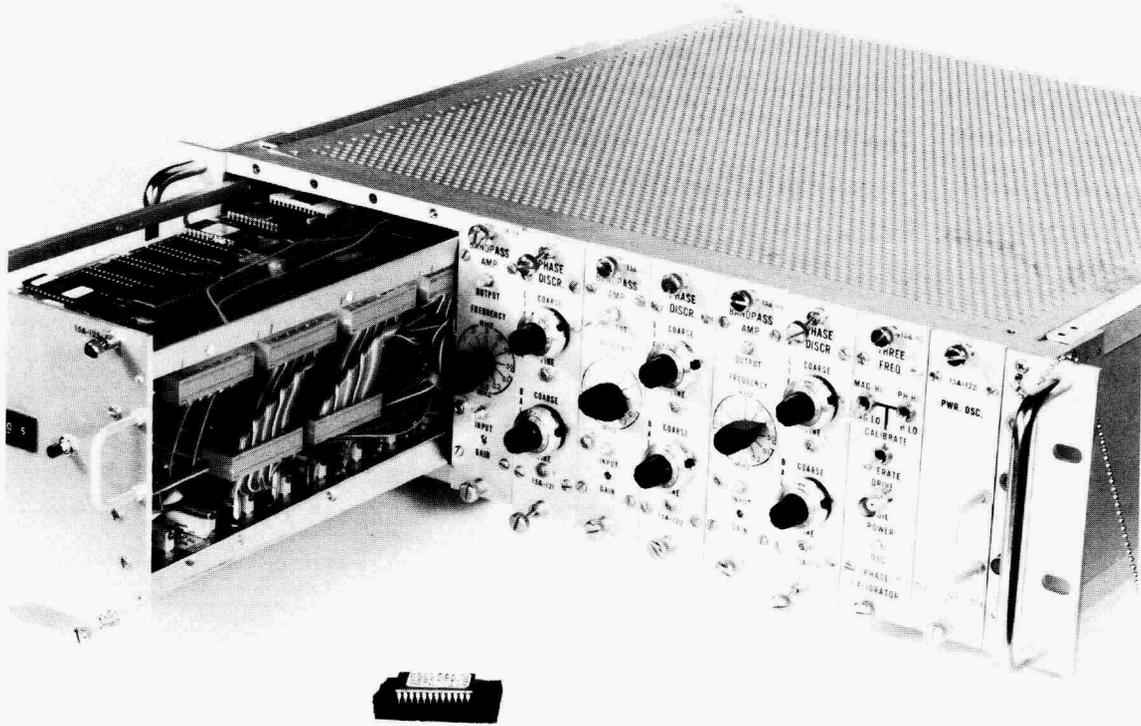


Fig. 3. Three-frequency eddy-current instrument.

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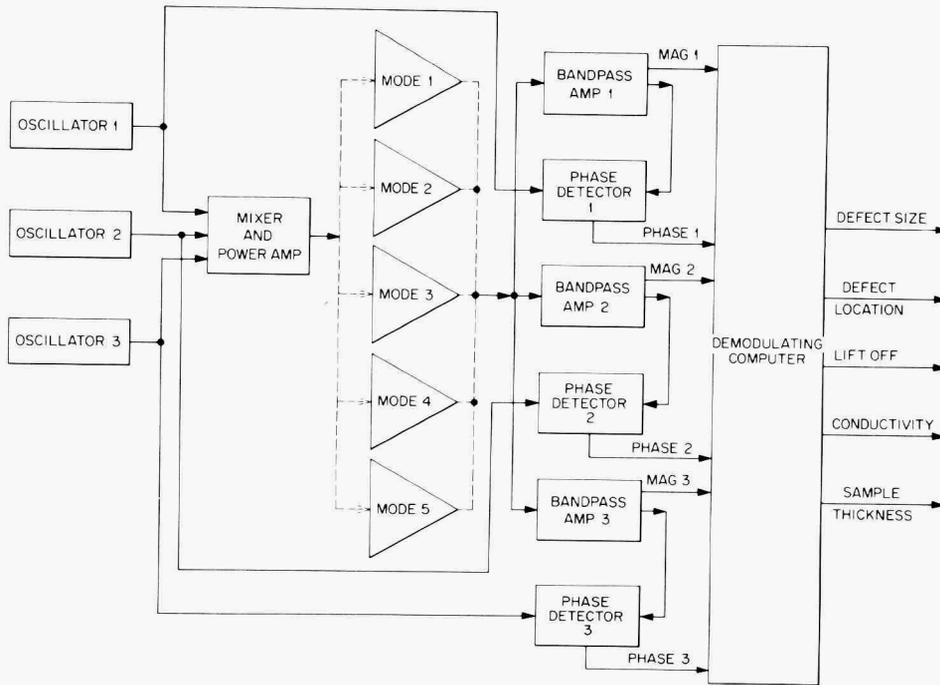


Fig. 4. Block diagram of three-frequency eddy-current instrument.

read-only memory and random access memory. It can perform 32-bit, floating-point mathematical operations in hardware and it has a sophisticated input-output structure for instrumentation control. The NDT-COMP9 microcomputer was also developed at ORNL, and details are provided.⁶

A small PROM chip lies in front of the instrument in Fig. 3. This chip has a 2-K byte memory capacity and is used to store the polynomial coefficients (used to determine material property values) in the microcomputer and the program for control of the test, data gathering, and evaluation. The chips are physically located in the top of the microcomputer.

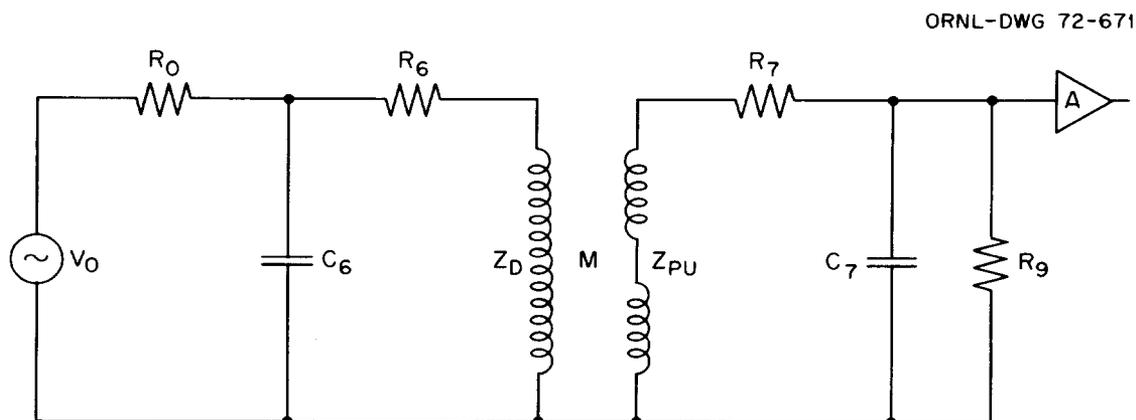
The minicomputer (MODCOMP IV), used for most of the data analyses for tests performed in the laboratory, is shown in Fig. 5. The minicomputer can store and operate on much larger quantities of data. For example, the polynomial coefficients used to develop material properties from the eddy-current readings are developed with the minicomputer and are transferred to the microcomputer by the PROM chips.

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Fig. 5. MODCOMP IV minicomputer.

The eddy-current coil design is selected to be able to detect the types of defects or to measure the properties desired. It must be small enough to provide the sensitivity required by test specifications, yet large enough to provide an area of coverage to allow the test to be performed in the time frame allowed. A flat pancake-type coil having a mean radius of 2.11 mm (0.083 in.) was used for this examination. The eddy-current probe actually contained driver and pickup coils arranged in a reflection mode. Figure 6 shows a simplified circuit diagram for a reflection-type probe. Details concerning reflection coils are reported elsewhere.⁷ The eddy-current probe used for this examination can be seen in Fig. 7. (The probe is the cylinder located in the laboratory scanning fixture.) A nominal 25-mm-diam (1-in.) superconductor cable and sheath sample is located under the lower end of the probe. The flat eddy-current coils are located in the end of the eddy-current probe, just above the superconductor sample.



- V_0 DRIVING VOLTAGE
- R_0 SERIES RESISTANCE IN THE DRIVING CIRCUIT
- C_6 SHUNT CAPACITANCE OF THE DRIVING CIRCUIT
- R_6 D.C. RESISTANCE OF THE DRIVER COIL
- Z_D IMPEDANCE OF THE DRIVER COIL
- M MUTUAL IMPEDANCE BETWEEN THE DRIVER AND PICK-UP COILS
- Z_{PU} IMPEDANCE OF THE PICK-UP COILS
- R_7 D.C. RESISTANCE OF THE PICK-UP COILS
- C_7 SHUNT CAPACITANCE OF THE PICK-UP CIRCUIT
- R_9 AMPLIFIER INPUT IMPEDANCE

Fig. 6. Simplified circuit diagram for an eddy-current reflection-type probe.

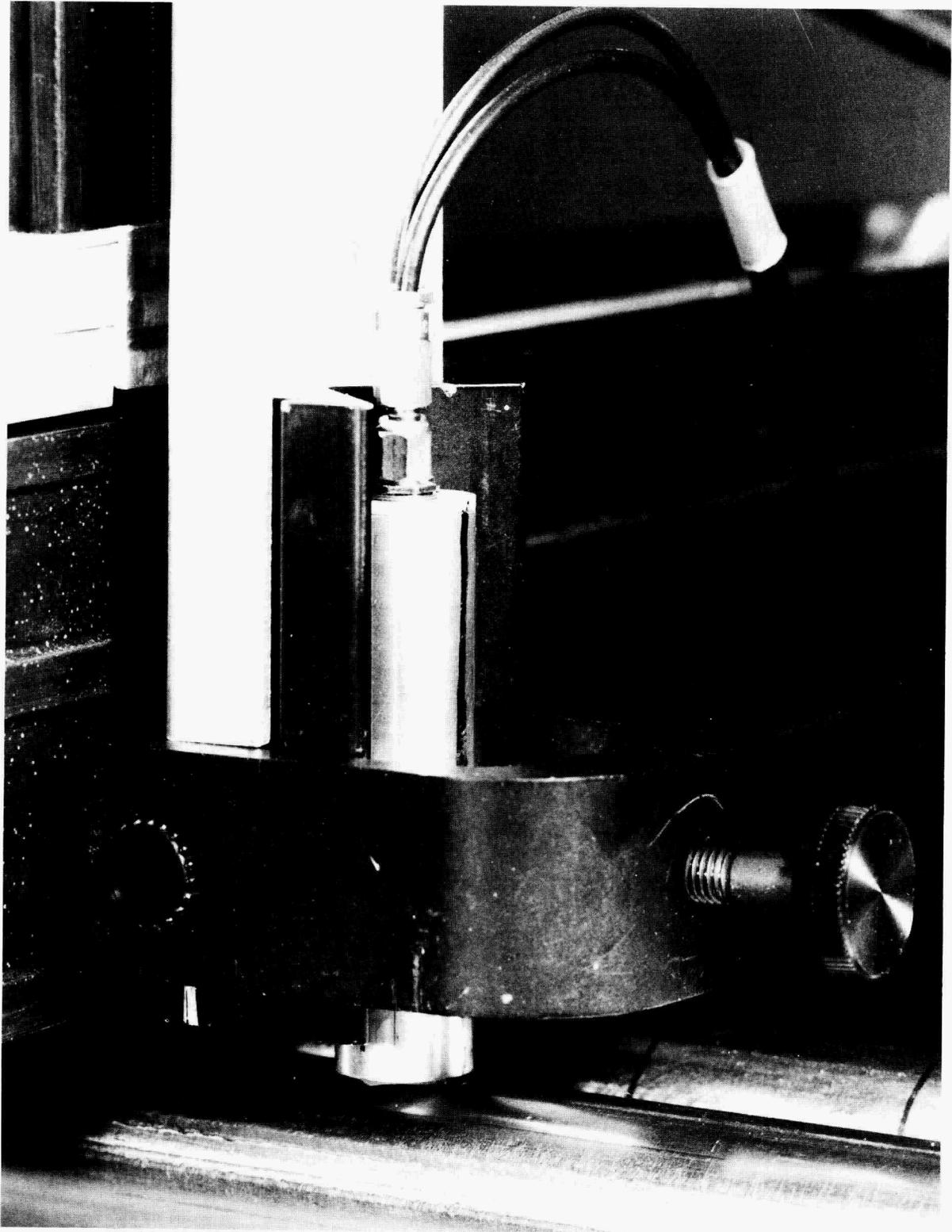


Fig. 7. Eddy-current probe.

The three-axis (xyz) scanning system used to examine the sheath welds in the laboratory is shown in Figs. 8 and 9. The scanning motion can be controlled by the operator using the teletypewriter keyboard (Fig. 10), or the control can be programmed into the computer. The stepping motors that control each axis of motion are driven by voltage pulses, and data are recorded in incremental bytes during scanning.

Figure 11 shows three of the output devices used to record data in the laboratory, a video display, a five-channel strip-chart recorder, and a Versatec printer-plotter. Two other output devices used were the line printer and the magnetic tape recorder shown at the left in Fig. 5.

Figure 12 shows the instrument package that was assembled to perform the tests on site. The components in the cabinet (from top to bottom) are (1) the three-frequency eddy-current instrument, (2) a six-channel strip-chart recorder, (3) a keyboard and video terminal, (4) a power supply and speed control for the scanning drive, (5) a remote control box used with

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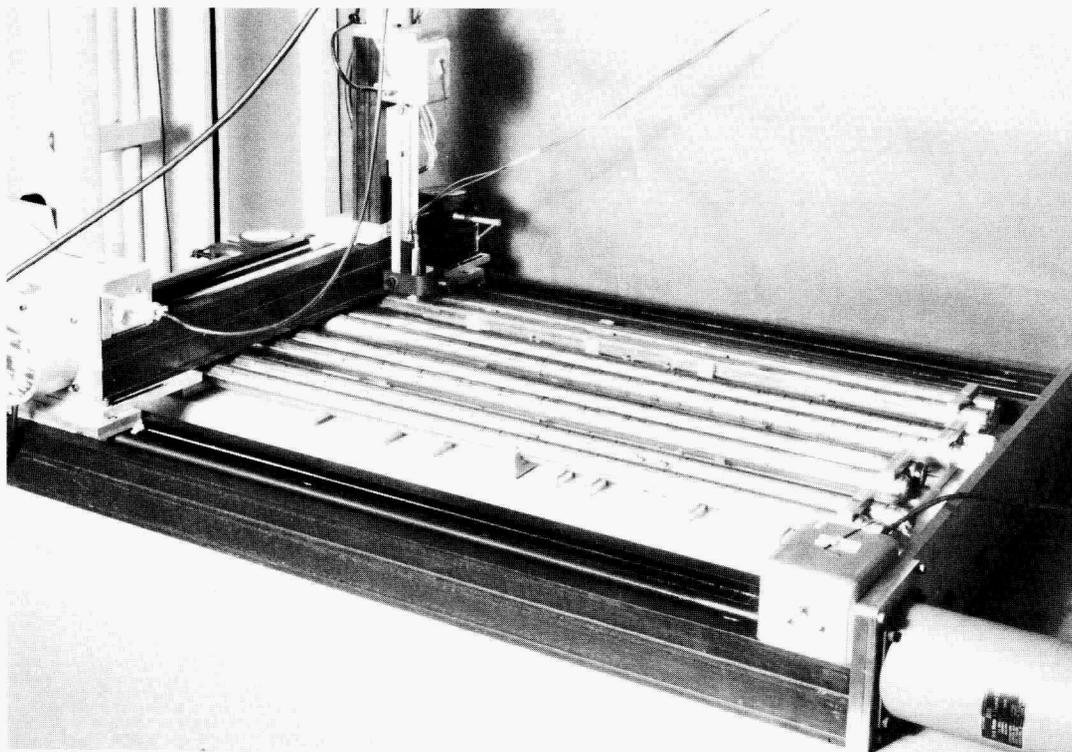


Fig. 8. Three-axis scanning fixture.

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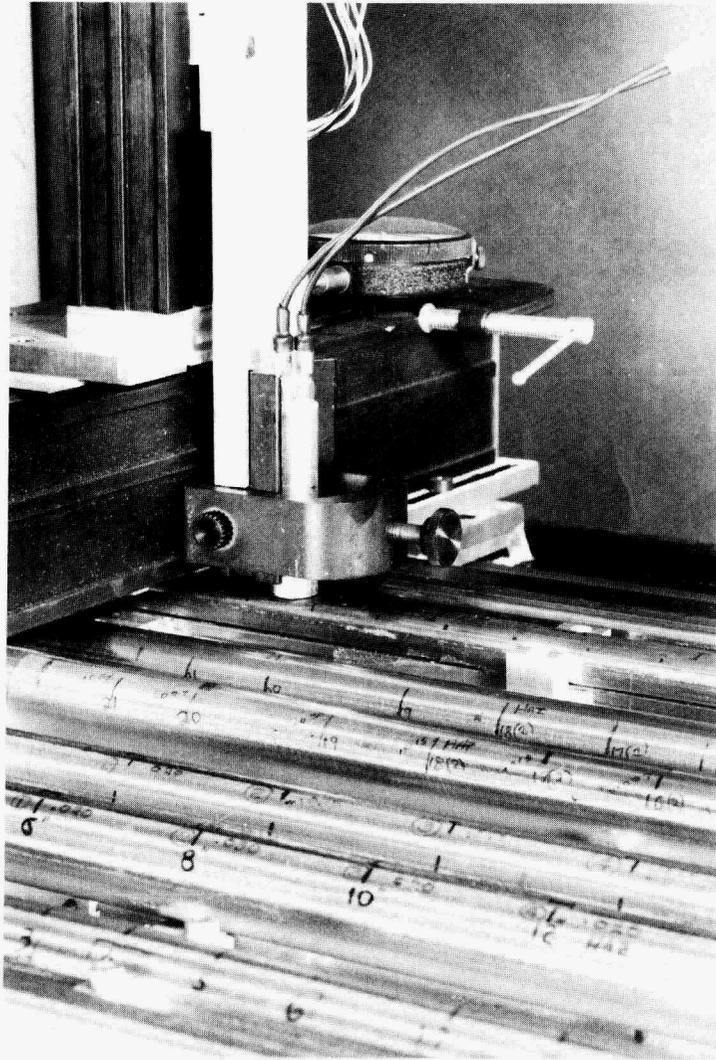


Fig. 9. Close-up of three-axis scanning fixture.

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Fig. 10. Keyboard and video display.



Fig. 11. Output devices (keyboard-video, strip-chart recorder, and Versatec printer-plotter).

the microcomputer to select different test conditions, (6) a magnetic tape recorder and buffer, and (7) a transceiver unit to link the microcomputer and output devices.

Figure 13 shows the sheath weld scanner at the test site. This device will be described in more detail later in this report. The marking device, used to identify areas on the sheath weld where significant eddy-current indications were obtained, is oriented about 45° to the scanner.

Two views of a hand-held manually operated scanning device in position on a superconductor cable are shown in Fig. 14. This device was used to accurately relocate the areas where significant indications were obtained and to reinspect local areas where weld repairs were made.

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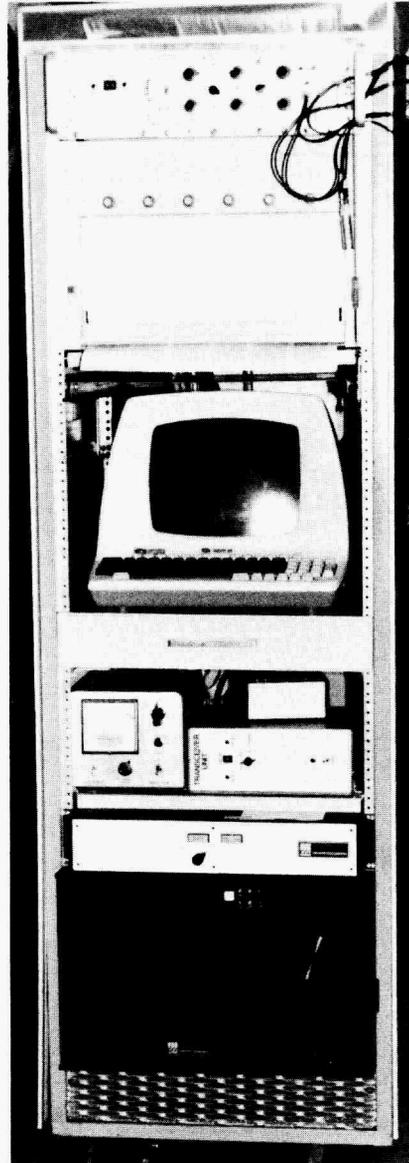


Fig. 12. Field instrument package used at Oxford-Airco.

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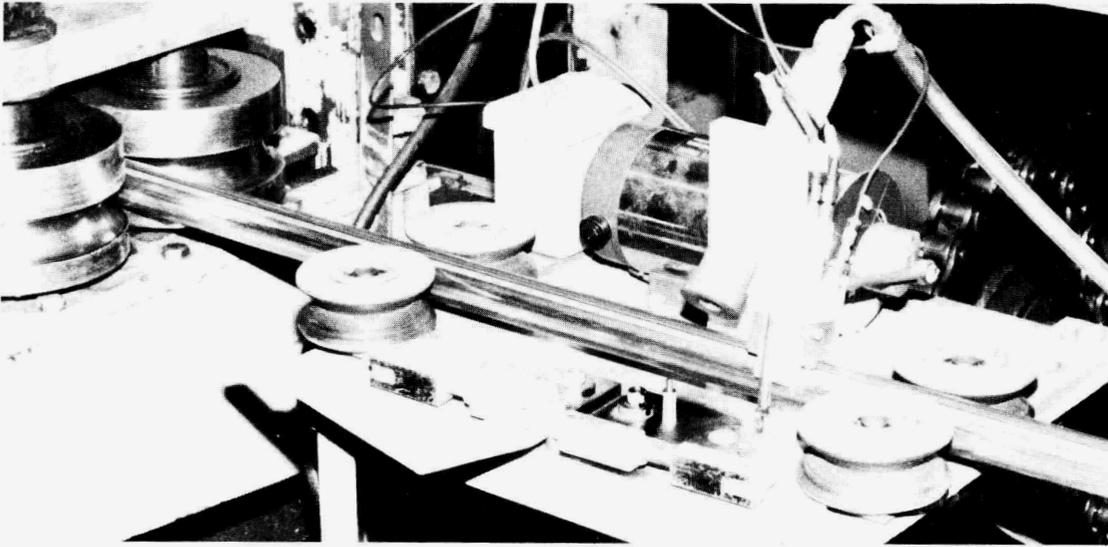


Fig. 13. Sheath weld scanner used at Oxford-Airco.

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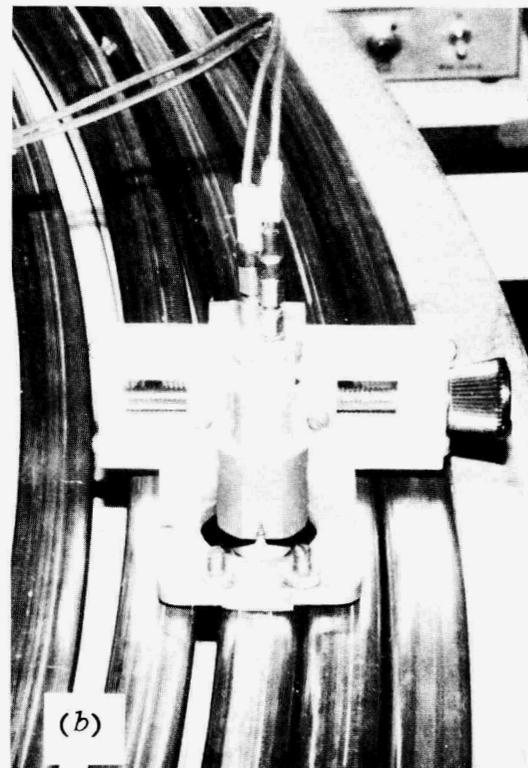
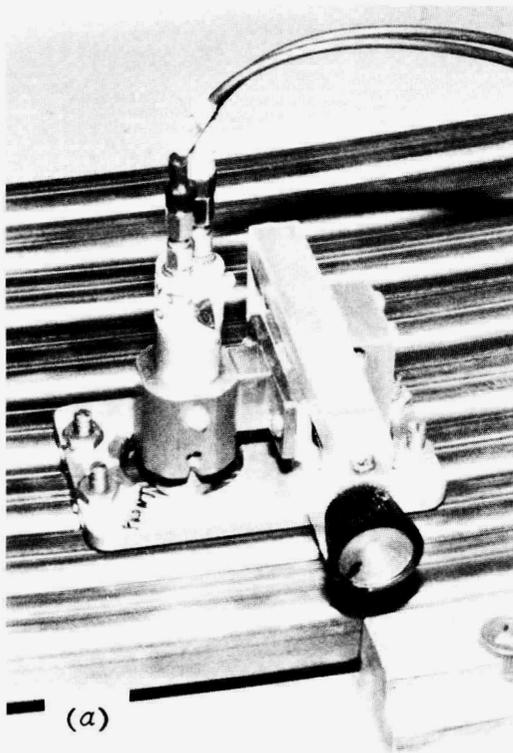


Fig. 14. Two views of the manual scanner used at Oxford-Airco.

TEST SAMPLES

The eight test samples used in this study can be seen in Figs. 8 and 9. Each sample was approximately 0.8 m long (31 in.) and about 25 mm (1 in.) in diameter or thickness. Six samples had a round cross section and two had a square cross section. The two cross sections, illustrated in Figs. 2 and 9, represent different stages in the production of the superconductor cable. The production, on-line eddy-current examination was performed while the cable had a round cross section. The final inspection for weld repairs was performed on the superconductor after it had a square cross section.

Several different types of manufactured discontinuities, such as longitudinal and transverse notches, holes, and V-grooves, were placed in the weld and heat-affected zones on both the inner and outer surfaces of the steel sheath. Figure 15 shows the locations and orientations of some of the discontinuities. The manufactured discontinuities were selected to produce eddy-current signals similar to those produced by the properties we were trying to measure. The holes and notches were used for defect

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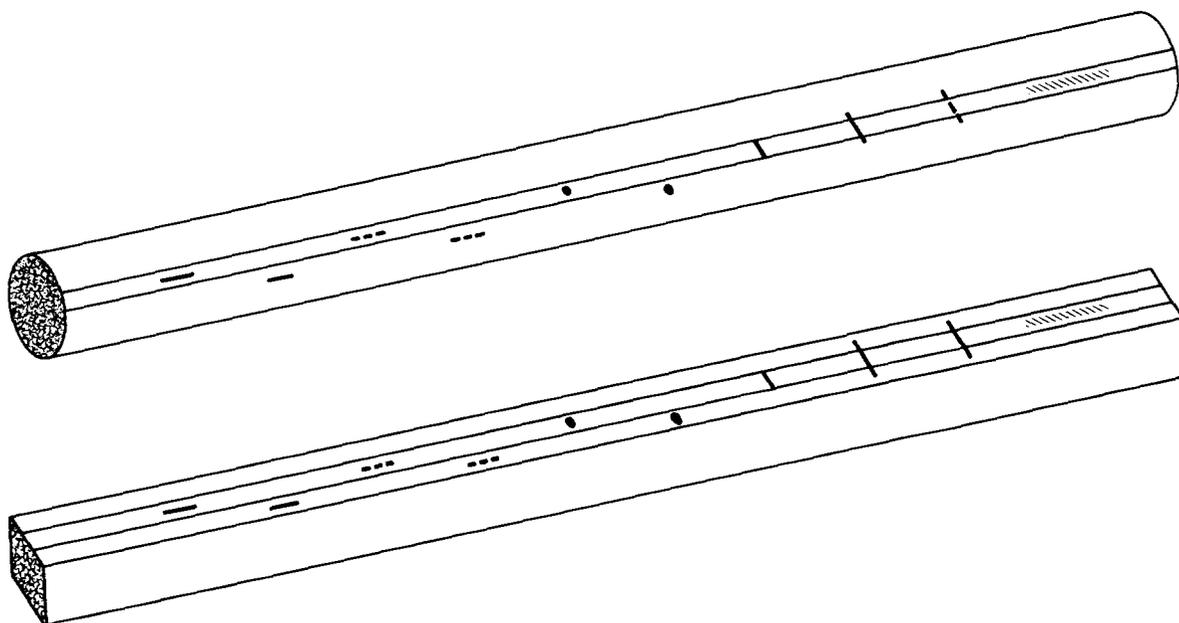


Fig. 15. Locations of manufactured discontinuities in the superconductor sheath weld test samples.

examination. The notches had nominal depths of 0.25, 0.51, and 0.76 mm (0.010, 0.020, and 0.030 in.) and were made by electrodischarge machining. The holes had nominal diameters of 0.18 mm (0.007 in.) and were drilled through the wall. V-grooves were milled in the root area of the weld to simulate lack of weld penetration. The test samples were fabricated in pairs with each pair being essentially identical. Tables 1 through 4 describe the various manufactured discontinuities in the test samples. Samples C and D (Table 4) have a square cross section and represent the final configuration of the superconductor cable. Sample C contained five areas on the weld where weld repairs had been made. Each area was approximately 76 mm (3 in.) long.

A brief identification system was developed for the various manufactured discontinuities in the test samples. This identification was used on data sheets, in computer programs, and in some figures in this report. Examples of discontinuity identities are ILW20, OTZ30, and HW7. Notches have a five-character identification number and holes a three-character number. The first character of a notch identification is either an I or an O, representing the inner or outer surface location of the notch. The second character is an L or T (longitudinal or transverse), and it represents the orientation of the notch with respect to the major axis of the weld. The third character is either W or Z, representing the location of the notch in the weld or in the heat-affected zone. The last two characters are numbers that represent the nominal depth of the notch in 25.4- μm (0.001-in.) increments. The first character of a hole identification is H for hole. The second character is W or Z (weld or heat-affected zone), representing the location of the hole, and the last digit or digits represent the diameter of the hole in 25.4- μm (0.001-in.) increments. All holes were drilled through the sheath (or weld) wall.

We discovered after doing quite a lot of work on the test samples that the material adjacent to the manufactured discontinuities in some of the test samples had become magnetic. These areas were not highly magnetic, and their field strengths could be measured only by using sensitive equipment such as a Hall effect device or an eddy-current instrument. We were mildly surprised because the JBK steel is a high-alloy steel that is

Table 1. Manufactured discontinuities in superconductor sheath weld test samples 1 and 2

Number	Type ^a	Surface	Location	Dimensions [mm (in.)]	
				Length	Depth
1	Longitudinal notch	Inner	Weld	6.35 (0.250)	0.51 (0.020)
2	Longitudinal notch	Inner	Weld	6.35 (0.250)	0.76 (0.030)
3	Transverse notch	Inner	Weld and HAZ	6.35 (0.250)	0.51 (0.020)
4	Longitudinal notch	Inner	HAZ	6.35 (0.250)	0.51 (0.020)
5	Longitudinal notch	Inner	HAZ	6.35 (0.250)	0.76 (0.030)
6	Hole		HAZ	0.18 (0.007)	Through wall
7	Hole		Weld	0.18 (0.007)	Through wall
8	Transverse notch	Inner	Weld and HAZ	6.35 (0.250)	0.76 (0.030)

^aTransverse notches extend across weld into the heat-affected zone (HAZ).

Table 2. Manufactured discontinuities in superconductor sheath weld test samples 3 and 4

Number	Type	Surface	Location	Dimensions [mm (in.)]	
				Length	Depth
1	V-groove	Inner	Weld	76.2 (3.0)	0.25 (0.010)
2	V-groove	Inner	Weld	76.2 (3.0)	0.51 (0.020)
3	V-groove	Inner	Weld	76.2 (3.0)	0.76 (0.030)
4	Wall thinning	Inner	Weld and HAZ	38.1 (1.5)	15%
5	Wall thinning	Inner	Weld and HAZ	38.1 (1.5)	25%
6	Wall thinning	Inner	Weld and HAZ	38.1 (1.5)	35%

Table 3. Manufactured discontinuities in superconductor sheath weld test samples A and B

Number	Type ^a	Surface ^b	Location	Dimensions [mm (in.)]	
				Length	Depth ^b
1	Longitudinal notch	Inner	Weld	6.35 (0.250)	0.25 (0.010)
2	Longitudinal notch	Inner	Weld	6.35 (0.250)	0.51 (0.020)
3	Longitudinal notch	Inner	Weld	6.35 (0.250)	0.76 (0.030)
4	Transverse notch	Inner	Weld and HAZ	6.35 (0.250)	0.51 (0.020)
5	Hole	T	Weld	1.65 (0.065)	T
6	Hole	Outer	Weld	1.65 (0.065)	1.52 (0.060)
7	Longitudinal notch	Inner	HAZ	6.35 (0.250)	0.25 (0.010)
8	Longitudinal notch	Inner	HAZ	6.35 (0.250)	0.51 (0.020)
9	Longitudinal notch	Inner	HAZ	6.35 (0.250)	0.76 (0.030)
10	Hole	T	HAZ	1.65 (0.065)	T
11	Longitudinal notch	Outer	Weld	6.35 (0.250)	0.25 (0.010)
12	Longitudinal notch	Outer	Weld	6.35 (0.250)	0.51 (0.020)
13	Longitudinal notch	Outer	Weld	6.35 (0.250)	0.76 (0.030)
14	Transverse notch	Outer	Weld and HAZ	6.35 (0.250)	0.51 (0.020)
15	Transverse notch	Both	Weld and HAZ	6.35 (0.250)	0.66 (0.026)
16	Transverse notch	Both	Weld and HAZ	6.35 (0.250)	0.66 (0.026)
17	Longitudinal notch	Both	Weld	6.35 (0.250)	0.38 (0.015)
18	Longitudinal notch	Both	HAZ	6.35 (0.250)	0.38 (0.015)
19	Longitudinal notch	Outer	Weld	19.0 (0.750)	0.76 (0.030)
20	Transverse notch	Outer	Weld and HAZ	12.7 (0.500)	0.61 (0.024)
21	Transverse notch	Outer	Weld and HAZ	3.18 (0.125)	1.63 (0.064)

^aTransverse notches extend across weld into the heat-affected zone (HAZ).

^b_T = through wall.

Table 4. Manufactured discontinuities in superconductor sheath weld test samples C and D

Number	Type ^a	Surface ^b	Location	Dimensions [mm (in.)]	
				Length	Depth ^b
1	Transverse notch	Outer	Weld and HAZ	6.35 (0.250)	0.25 (0.010)
2	Longitudinal notch	Outer	Weld	6.35 (0.250)	0.25 (0.010)
3	Transverse notch	Inner	Weld and HAZ	6.35 (0.250)	0.76 (0.030)
4	Longitudinal notch	Inner	HAZ	6.35 (0.250)	1.02 (0.040)
5	Transverse notch	Outer	Weld and HAZ	6.35 (0.250)	0.51 (0.020)
6	Longitudinal notch	Outer	Weld	6.35 (0.250)	0.51 (0.020)
7	Transverse notch	Inner	Weld and HAZ	6.35 (0.250)	0.51 (0.020)
8	Hole	T	HAZ	0.15 (0.006)	T
9	Longitudinal notch	Inner	Weld	6.35 (0.250)	0.76 (0.030)
10	Longitudinal notch	Inner	Weld	6.35 (0.250)	1.02 (0.040)
11	Longitudinal notch	Outer	HAZ	6.35 (0.250)	0.25 (0.010)
12	Longitudinal notch	Outer	HAZ	6.35 (0.250)	0.51 (0.020)
13	Transverse notch	Inner	Weld and HAZ	6.35 (0.250)	0.51 (0.020)
14	Longitudinal notch	Inner	Weld	6.35 (0.250)	0.51 (0.020)
15	Hole	T	Weld	0.15 (0.006)	T
16	Longitudinal notch	Inner	HAZ	6.35 (0.250)	0.51 (0.020)
17	Longitudinal notch	Inner	HAZ	6.35 (0.250)	0.76 (0.030)
18	V-groove	Inner	Weld	25.4 (1.0)	0.25 (0.010)
19	V-groove	Inner	Weld	25.4 (1.0)	0.51 (0.020)
20	V-groove	Inner	Weld	25.4 (1.0)	0.76 (0.030)

^aTransverse notches extend across weld into the heat-affected zone (HAZ).

^b_T = through wall.

very similar to the 300-series stainless steels and should have been non-magnetic. In fact, no magnetic effects could be detected with the typical gaussmeter used in machine shops. The electrodischarge-machining processes used to cut the notches in the weld had apparently changed the metallurgical structure and the properties of the steel in the small areas where discontinuities were located. The result was that the signals the eddy-current instrument received from these discontinuities were a combination of geometrical and magnetic effects. The signals were larger than normal, and the error was due to the magnetic effect. A very light chemical etch of the samples alleviated the magnetic problem, and after etching we reinspected the samples using a saturating magnetic field around the eddy-current probe and the discontinuity being measured. No adverse effects were caused by the problem, except for a short delay in the completion of the program to establish the test, but the sensitivity of the eddy-current inspection could have been adversely affected if we had not discovered the magnetic effects surrounding some of the discontinuities.

CALIBRATION AND TRAINING OF TEST SYSTEM

An experimental study (discussed earlier in the theory section) was performed in the laboratory to train the computer to determine the specified properties from the available magnitude and phase readings. The basic steps required to complete this study were to produce a data file, record a data set, mathematically fit the data, develop mathematical coefficients for the fit, and then store the coefficients for later use. Details of how these steps were performed are discussed in this section of the report.

To produce a representative data set, we fabricated a set of test samples that had known property variations of the type and over the range that we wished to measure. These samples are described in an earlier section of this report. We then arranged them in a three-axis (xyz) scanning system so that the necessary measurements could be made to produce the data set. Figures 8 and 9 show the eight test samples assembled in the

scanning fixture. Leveling bars can be seen under the samples in the figure. We needed to level the samples so they could be scanned at known, uniform, fixed lift-off values to compensate for the lift-off variations that occurred during the production line inspection. (The large lift-off variations were due primarily to changes in the weld crown reinforcement.) The eddy-current probe was mounted on the z -axis slide, and lift-off variation was controlled with the z -axis motion. The samples were aligned so the x -axis motion scanned the eddy-current probe down the length of the sample along the major weld axis. The y -axis motion moved the probe across the samples and was used to select the area to be scanned (weld or heat-affected zone) and to select the sample to be scanned.

After the samples had been arranged in the scanner, a "scan data file" was produced. A scan data file contains the coordinates of the test samples and the areas on the sample where we wish to record eddy-current readings. (The samples are physically measured, and the resultant data are typed into the computer data file.) This file then supplies the coordinates that the computer uses to direct the scanner to move the eddy-current probe to the areas where readings are recorded. The data file also contains additional information about the properties being measured, such as the dimensions of the manufactured discontinuities, thickness of the samples, and lift-off values. The computer later uses this information to identify or describe the specific properties. The properties evaluated for this study were defect size and location, weld thickness, and lift-off.

The next step in the experimental study was to modify an existing computer program to direct the minicomputer to record a data set from the specific test samples. This program utilized the coordinates and other information provided by the data file just discussed. In general, the modifications to the program were to correct the array sizes for data storage, provide information about the specific eddy-current instrumentation and coil being used, and update the instrument calibration values. Our basic computer program for recording data is referred to as a "READ" program. The name of the program is BIGRDG, and for this particular test the modified version was dubbed "SUPRDG" (superconductor read). A copy of BIGRDG is included in Appendix A. This program controls the scanning

system, maintains a calibration check on the eddy-current system, records and averages the data (typically three independent sets of data are recorded), and stores the data on a random access data (RAD) file. The microcomputer in the eddy-current instrument actually records the data readings from analog-to-digital converters, and the readings are then transferred to the minicomputer through a handshake arrangement between the two computers. A computer program called MICMOD controls this operation. A copy of of this program is included in Appendix B. The program was written in machine language and was stored on one of the PROM chips in the microcomputer (see Fig. 3).

It is essential that the eddy-current test system be properly calibrated when these data are recorded. If this step is properly conducted, a representative data set will be obtained, and no further data recording will be required. However, changes in the production procedure (such as changing materials or the welding technique) or changes in the test specifications could necessitate the recording of additional or new data sets.

A data set can consist of a large number of readings of magnitude and phase. These data require a relatively large amount of memory space (typically about 1 megabyte), and they must be stored in an orderly manner for easy retrieval. We can store a data set of this size in our (MODCOMP IV) minicomputer, but it occupies most of the available "free" memory space and therefore limits some of the other capabilities of the computer. Because of this we usually store these large sets of data on a disk or magnetic tape until we are ready to use them.

After we obtained the data set, the next step was to perform a least-squares mathematical fit of the data to select the polynomial that best determines the specified properties from the magnitude and phase readings recorded in the data set. The fitting was done with the minicomputer and a slightly modified version of another computer program called BIGFIT. This program is our basic FITTING software and was also developed at ORNL. A copy of BIGFIT is included in Appendix C. The modified version of the BIGFIT program used for this study was entitled SUPFIT (superconductor fit). This program allows the type of polynomial to be user selected from

the computer keyboard. The operator can select linear or nonlinear polynomials of various degrees, with or without offsets, for fitting the data. In addition, he can examine the effects of other parameters on the results by including or excluding these data in the fits. Whenever a mathematical fit is made, the computer calculates the fit error (how well the specified property was determined) and the drift error (how small changes in the magnitude and phase readings will affect the property determination). Once the optimum mathematical fit to the data is established, the computer will calculate the coefficients for the terms in the polynomial that represent that fit. These coefficients are then stored in the minicomputer's memory until we are ready to transfer them to the microcomputer in the eddy-current instrument.

Whenever a satisfactory mathematical fit is obtained, it is usually experimentally evaluated before the coefficients are transferred to the microcomputer. This evaluation is accomplished by scanning the test samples, recording the eddy-current readings, and using the polynomial and associated coefficients to calculate the desired property as the test is being conducted. The computer program that controls this operation is a modified version of the program PLTRDG. A copy of PLTRDG is included in Appendix D. A hard copy of the test results is normally obtained (in the form of a plotted curve or tabular printout) from the Versatec printer-plotter.

For example, Fig. 16 shows a plot of the raw data readings (magnitude and phase) that were recorded for each test frequency as the eddy-current probe was scanned over the sheath weld for a 381-mm (15-in.) length of superconductor test sample 1. The six curves represent the magnitude and phase readings recorded for each of the three frequencies. These are the data recorded in the "data set" just discussed. In this particular case it is difficult to select signals that distinctly relate to the manufactured discontinuities placed in the sheath. Figure 17 is a plot of the data obtained when the same weld was scanned and the selected property of discontinuity size was calculated by the computer from raw data identical with that obtained in Fig. 16. The calculations were made by matching the raw data readings to the appropriate polynomial using coefficients that

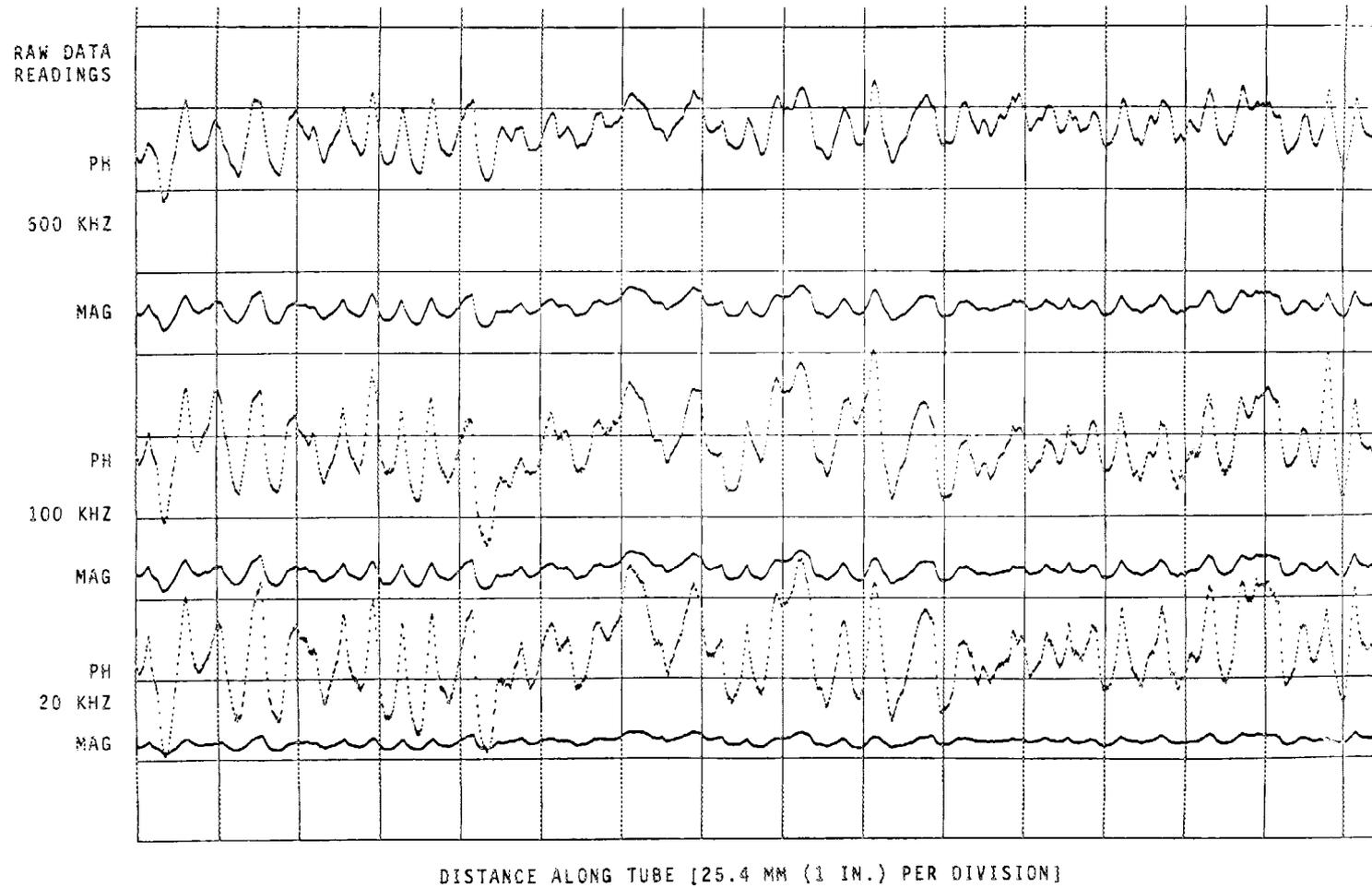


Fig. 16. Raw data readings from a superconductor sample containing only inside-surface discontinuities.

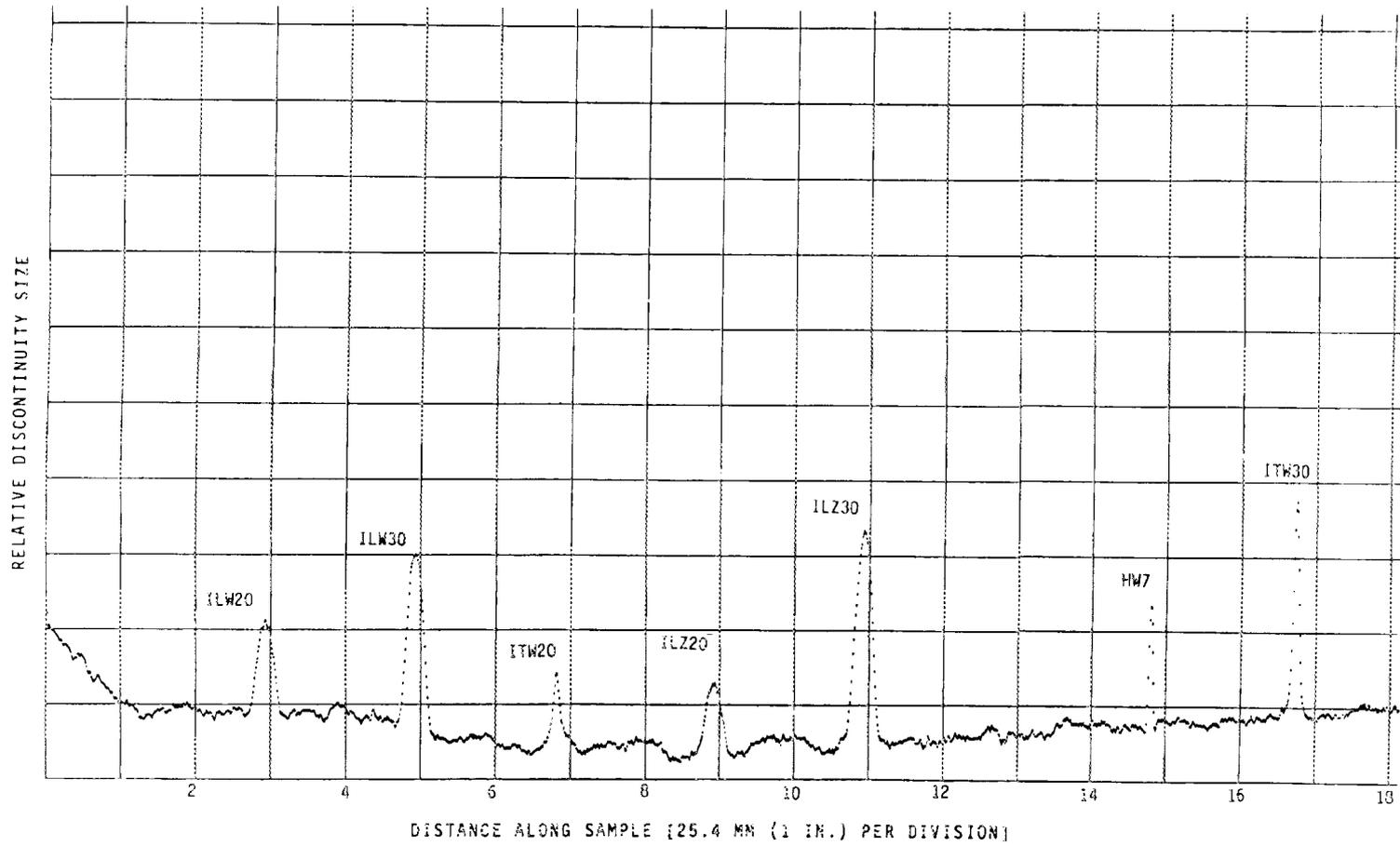


Fig. 17. Calculated data showing relative discontinuity size after the sample was etched (round cross section).

were developed earlier. The respective discontinuity is identified above each signal. (These identities are explained in the section on test samples.) The distinct signals in Fig. 17 represent the various manufactured discontinuities in sheath weld test sample 1 (see Table 1). Comparing Fig. 17 and Table 1, it may be noted that no signal exists in Fig. 17 for the hole in the heat-affected zone. This is because we scanned the weld area, and the eddy-current probe area of coverage does not extend to the heat-affected zone. These data (Figs. 16 and 17) provide a dramatic illustration of the results that can be obtained by combining and mathematically fitting the eddy-current (magnitude and phase) data obtained with three frequencies.

After we completed the calibration and training of the multifrequency eddy-current test system in the laboratory, we developed mathematical coefficients for the various properties that we wanted to monitor, such as lift-off, wall thickness, and defect size and location. Some of our results, especially those related to defect size, appeared a little ambiguous, so we did some additional investigating. Many of the samples containing discontinuities manufactured by electrodischarge machining (EDM) were slightly magnetic in the specific area where the discontinuities were located. The JBK steel is similar to the 300 series stainless steels. It is normally nonmagnetic, but apparently the EDM techniques had changed the magnetic permeability of the material in the vicinity of the discontinuities. The change was so small that it could not be sensed by typical magnetic detection devices, but a sensitive eddy-current instrument can easily detect changes of this magnitude. The end result was that erroneous signals had been obtained from some discontinuities; therefore the mathematical coefficients developed for defect size were also in error. Not all the samples were affected; for those that were, the entire sample was not affected, only the small areas containing some of the discontinuities. For this reason, only those eddy-current signals that represented defect size were in error. We made sure that no changes such as these occurred in the production cables, and we corrected the problem by removing the magnetic variation in the samples and refitting the data to a new polynomial. We removed the magnetic changes by acid-etching the samples to

remove a very small amount of material from the surface and then inspected the samples in the presence of a saturating magnetic field. (The saturating field reduces the effects of changes in the magnetic permeability of the material.) Using these techniques we developed a new set of coefficients that represented the superconductor sheath weld in the normal (unmagnetized) condition that occurred at the production site. As a result of the new mathematical fit, the amplitudes of the signals from some of the discontinuities were reduced, but the detection capability was not affected.

SCANNING THE SHEATH WELD

The eddy-current probe was selected to meet two criteria; it had to have sufficient sensitivity to detect the defects specified and it had to cover 100% of the weld and heat-affected zone. In general, with other parameters being fixed, the sensitivity to small defects and the area of coverage of a pancake type eddy-current coil vary, respectively, inversely and directly with the diameter of the coil. The largest eddy-current coil that we had available that met the sensitivity requirements for this examination had a mean radius of 2.11 mm (0.083 in.). When field decay and other nonlinearities are considered, the effective area of coverage for this coil is about 2 mm (0.08 in.). Test specifications required that we inspect the sheath weld and both heat-affected zones. The minimum width that we were required to scan to provide inspection coverage from one heat-affected zone to the other was 8.13 mm (0.320 in.). We could not use a larger coil because of the reduced test sensitivity, so we were faced with two choices. We could use multiple probes (four or five) to scan the weld and heat-affected zone simultaneously, or we could develop a scanning fixture to move a single probe across the weld and heat-affected zone. The multiple probe technique would have required a multiplexer or multiple instrumentation to record the data and would have been relatively complicated and more expensive to develop. In addition, we had a very tight time schedule for developing the test method, so we decided to use the single probe and build a scanning device.

The basic problem was to scan the eddy-current probe mechanically back and forth across the weld and heat-affected zones as the weld moved linearly past the probe (see Fig. 18); however, the problem was not as simple as just providing the mechanical motions. We had to synchronize the probe motion with the weld movement and data recording to assure complete coverage during the inspection, maintain a relatively constant lift-off between the probe and sheath, and synchronize the weld and probe motions with the data recording system to maintain positive identification of the defect location. In addition, we were limited by the electronics in our test system (analog-to-digital converter and microcomputer) to recording only about 80 readings per second.

During production fabrication the steel sheath is formed and welded around the superconductor cable for lengths of up to 100 m. This process is conducted continuously at a speed of about 0.61 m/min (2 ft/min). The weld is 5.1 mm (0.200 in.) wide. To include the heat-affected zones, we needed to inspect at least 1.52 mm (0.060 in.) on either side of the weld for a total width of coverage of 8.13 mm (0.320 in.) (see Fig. 18). The

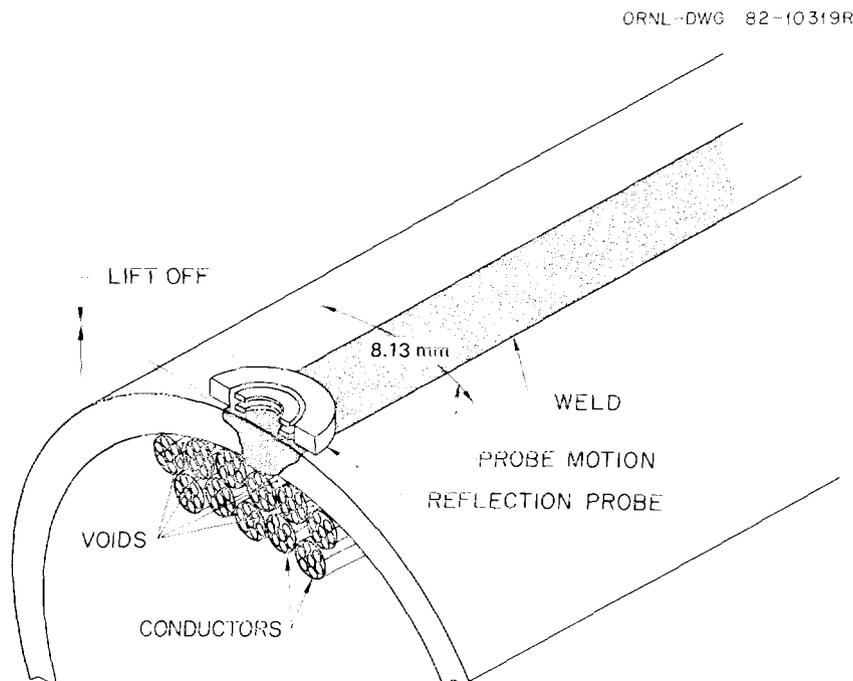


Fig. 18. Sketch of probe over sheath weld.

area of coverage of the eddy-current probe was 2 mm (0.08 in.), so we decided that five readings across the width would be sufficient to cover the weld and both heat-affected zones with some overlap.

We also had to decide what path or scanning pattern we wanted the eddy-current probe to make as it scanned the weld and heat-affected zones. The options were sine wave, saw tooth, and square wave. Our final choice was a sine wave (see Fig. 19) because it was relatively easy to produce and it best fit the method used to output the data.

A crankshaft-type drive was used to move the probe back and forth as the superconductor sheath weld passed underneath the probe in a linear direction. The resultant motion of the eddy-current probe relative to the sheath was sinusoidal. Two views of the scanning device that was designed and built at ORNL are shown in Fig. 20. The spring-loaded Teflon V-block

ORNL-DWG 85-1810

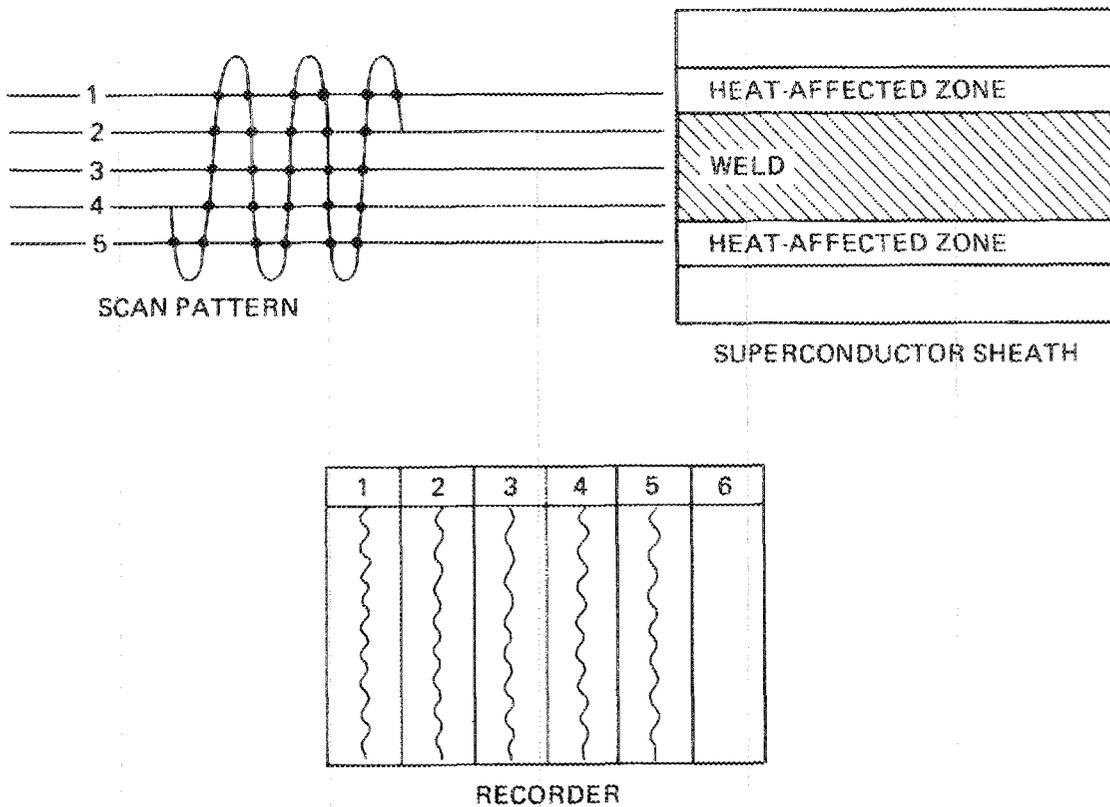
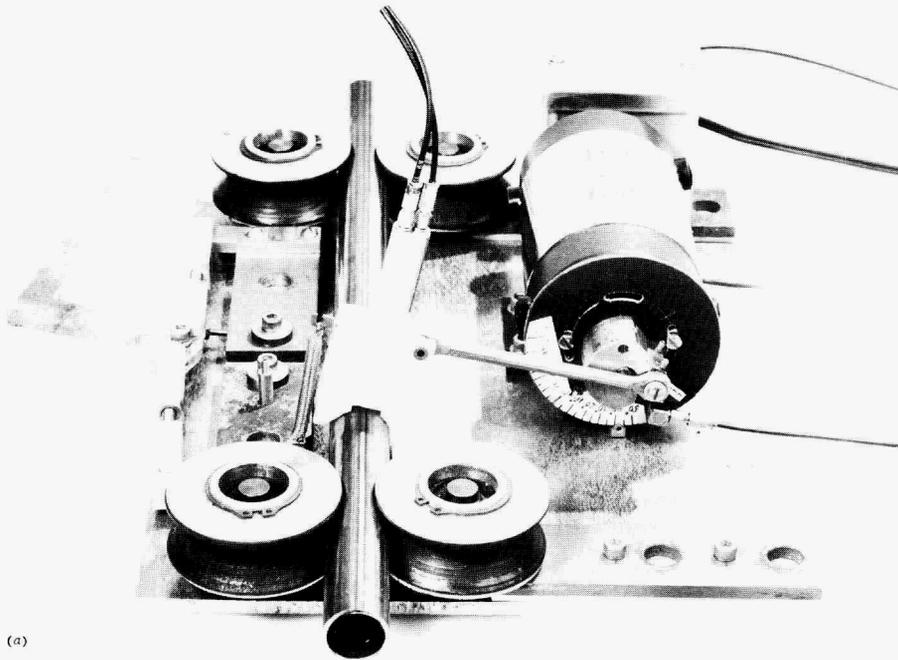


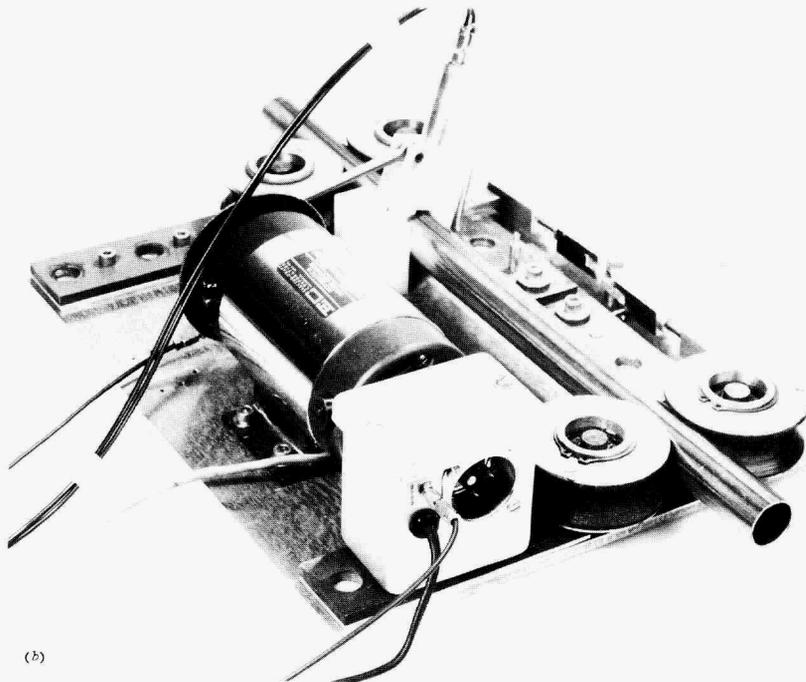
Fig. 19. Sine scan path and eddy-current read location.

Y-181449



(a)

Y-181448



(b)

Fig. 20. Sheath weld scanner.

caused the eddy-current probe to follow an arc path over the sheath weld and to maintain a relatively constant lift-off during the inspection. The eddy-current probe did not contact the part during this inspection, but lift-off was minimized. The weld crown reinforcement varied as much as 1.0 mm (0.040 in.) above the base metal, so we placed a hard plastic wear plate over the end of the eddy-current probe to protect the coil during the inspection. The effect on the data of the variations in lift-off due to changes in the weld crown reinforcement was accounted for when we trained the computer on the test samples.

The electrical outlet in Fig. 20(b) supplied power to the marking pen. Electric power to the pen was controlled by the microcomputer using a solid state relay. The system was adjusted to cause the pen to mark areas on the superconductor sheath where discontinuity signals exceeded a preset level.

Rather than record random readings as the eddy-current probe oscillated back and forth across the weld and heat-affected zones, the readings were taken at specific predetermined locations across the weld width. This is illustrated in Fig. 19. Five eddy-current readings were recorded at fixed longitudinal axes each time the probe traversed the weld. A total of ten readings were recorded for each cycle traveled by the probe. The locations of the readings were controlled by computer software and a synchronized pulse generated by the drive motor crankshaft. Readings 1 and 5 were always made in the heat-affected zones, and readings 2, 3, and 4 were taken in the weld area. The next consecutive set of five readings was taken in reverse order along the same corresponding longitudinal axes. These readings were stored in designated arrays in the microcomputer, and corresponding values for consecutive sets of readings were averaged before the data were transmitted to the output devices. This process was repeated for the entire test. The data for each individual axis (three in the weld and two in the HAZ) were fed to the first five channels on the six-channel strip-chart recorder shown in Fig. 12. The data on each channel of the strip-chart recorder then effectively represented a scan down the longitudinal axis where the individual readings were recorded. The first five channels were set to display discontinuities, and the sixth channel was adjusted to indicate the worst

case of lack of weld penetration. Worst case refers to the minimum penetration for a given sine wave path of the eddy-current probe. To restate, the depth of weld penetration was monitored for each of the first five channels of data, and the channel exhibiting the minimum depth of weld penetration was displayed on channel 6 of the strip-chart recorder.

The entire recording process and data handling were controlled by the microcomputer in the eddy-current instrument and the computer program SQRWLD. This versatile computer program, included in Appendix E, will be described in more detail in the next section of this report. Figure 21 shows a segment of the strip chart from the analog recorder containing the six scans.

All raw data (magnitude and phase readings for three frequencies) were stored on magnetic tape by the recorder shown in Fig. 12. The six-channel strip-chart recorder displayed the data that we wanted to observe as the test was being conducted. The magnetic tape could be replayed through the microcomputer to reproduce the six channels of strip-chart data, or, by selecting other polynomial coefficients (via memory locations in the computer), we could calculate other properties from the raw data and display the results on the analog recorder.

PERFORMING THE INSPECTION ON THE PRODUCTION LINE

The superconductor cable was assembled in continuous lengths of up to 100 m. A block diagram of the basic operations is shown in Fig. 1. Rolls of the 486-strand twisted cable and the type JBK steel strip were stored at the feed station. The wire and cable were simultaneously fed through the forming stands, where rollers shaped and wrapped the steel strip to form a sheath around the twisted cable. The butt joint, created at the top of the steel sheath, was then welded autogenously by a gas tungsten arc technique. The weld and cable were quenched and fed through the eddy-current inspection station at a speed of 0.61 m/min (2 ft/min). The multifrequency eddy-current inspection of the sheath weld was performed continuously for the entire length of the cable. A procedure, included as Appendix F of this report, was written at ORNL to describe in detail the

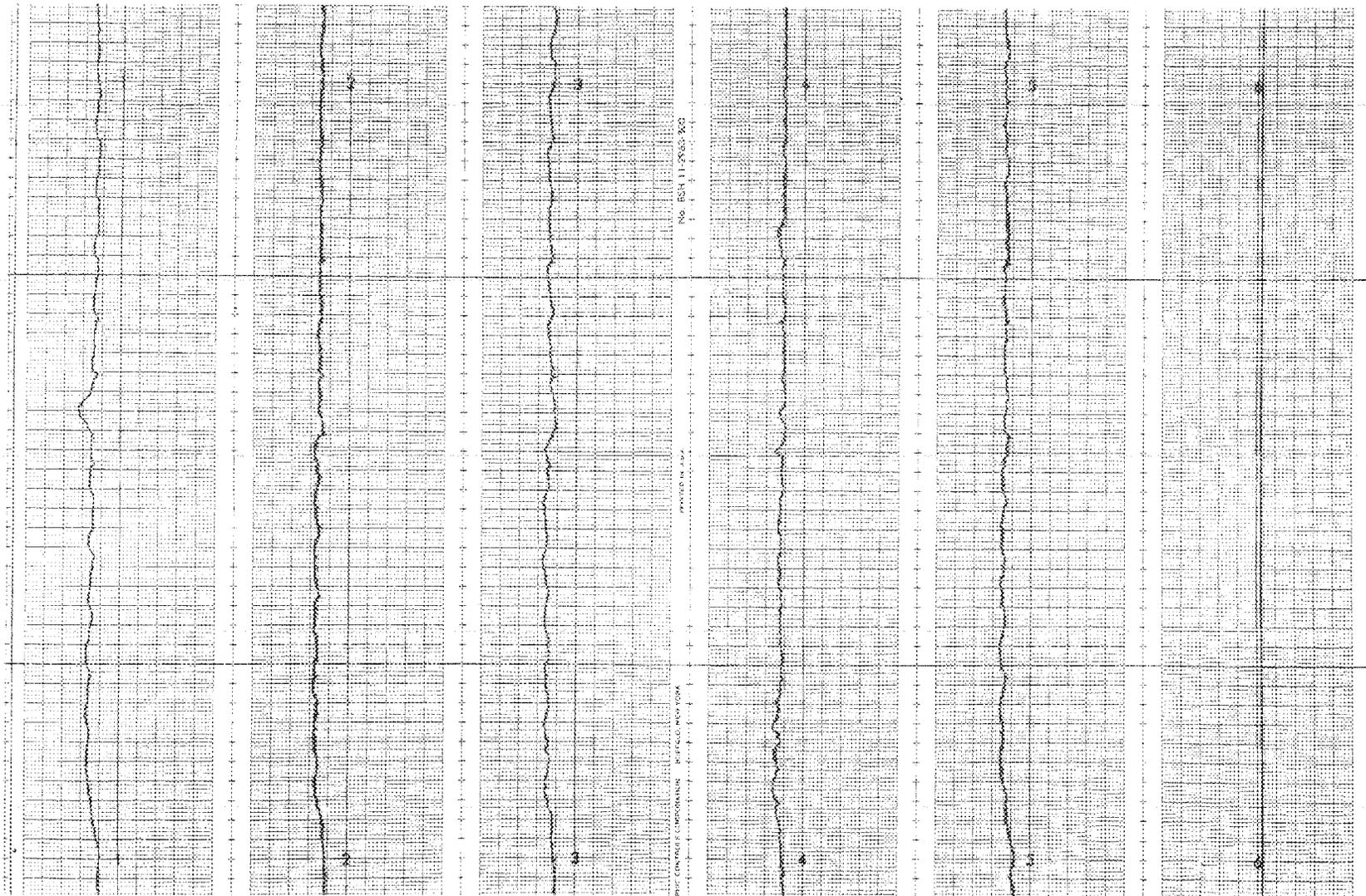


Fig. 21. Example of six-channel strip-chart recording. Channels 1 through 5 indicate discontinuities when they occur in the sheath weld or HAZs. Channel 6 indicates the lack of penetration in the weld. Channels 1 and 5 represent the two HAZs, and channels 2, 3, and 4 represent the weld.

steps necessary to perform the eddy-current inspection. The basic steps were (1) initial check of the system, (2) precalibration, (3) test, and (4) postcalibration. These steps are described in general as follows.

The system checks and calibrations and the data recording and display were controlled with the microcomputer by a program called SQRWLD. A copy of this program is included in Appendix E. The program was written in machine language and was stored on two of the PROM chips located in the microcomputer (see Fig. 3). The operator would set up the equipment and place the test piece or a standard in the scanning device. He would then select the action to be performed by operating a remote switch to a designated position. The SQRWLD program would then take command and make sure that the necessary steps were taken to perform that action. Some of these steps included prompts on the video display defining actions for the operator to take. The eight major actions that could be selected by the operator through the remote control switches were (1) run the main program, (2) read tape, (3) read standard tube, (4) display raw readings, (5) display calculated readings, (6) perform and display calibrations, (7) inspect square conditions, and (8) calibrate the digital or analog converters and recorder. In addition, the program controlled the synchronized data recording with the scanning device. (A synchronization pulse was generated for each revolution of the drive motor crankshaft.)

INITIAL SYSTEM CHECK

The first step is to apply power to all electrical instruments and allow a sufficient warm-up time for the equipment to stabilize. During this warm-up period, the operator makes several checks to ensure that the instruments are working properly and that all systems are ready for the inspection. For example, all electrical connections and switches are checked. The analog (strip-chart) recorder ink and paper supply are checked. General checkouts are made of both recorders (analog and magnetic tape) and the eddy-current probe scanner. In addition, the microcomputer is used to perform the following system checks on command by the operator.

The multifrequency eddy-current instrument contains a calibration module that can be used along with the microcomputer to check the operation

of the analog portion of the eddy-current instrument. This step is controlled by the computer program SQRWLD. Simulated eddy-current signals of known values are generated by the calibration module and fed through the amplifiers, phase detectors, and analog-to-digital converters to the microcomputer. These signals are separated into their magnitude and phase components and are displayed on the video terminal. The operator can determine from these magnitude and phase values whether or not any adjustments or corrections are needed in the analog portion of the eddy-current instrument.

The operation of the analog recorder is checked by a series of voltage steps received from the microcomputer through a digital-to-analog converter. This step is also controlled by the computer program SQRWLD. The voltage steps are recorded in a staircase pattern on the analog recorder, as shown in Fig. 22. If the voltage steps cause the recorder pens to move the correct number of increments in the proper direction on the recorder, the system is ready for use. If not, adjustments are made.

The following check was not part of the original test package but was added later because of problems encountered by recording the raw data on magnetic tape at the production site. A technique was developed to check the entire digital recording system. The microcomputer was programmed to generate a set of hexadecimal numbers by counting from 0000 to FFFF. These numbers were transmitted through the transceiver unit and tape buffers and recorded on the magnetic tape. To check the tape, the numbers were then read back from tape and through the buffers and transceiver, compared with the original count in the microcomputer, and then displayed on the video terminal. By comparison of numbers in the microcomputer and the resulting video display, the operator can determine whether the digital recording system is working properly, and, if not, he can localize the problem areas. The procedure for performing this check is in Appendix G. The computer program that generated the hexadecimal number set and controlled the operation was called CHECK. A copy of that program is included in Appendix H. The program was written in machine language and stored on one of the PROM chips in the microcomputer (see Fig. 3).

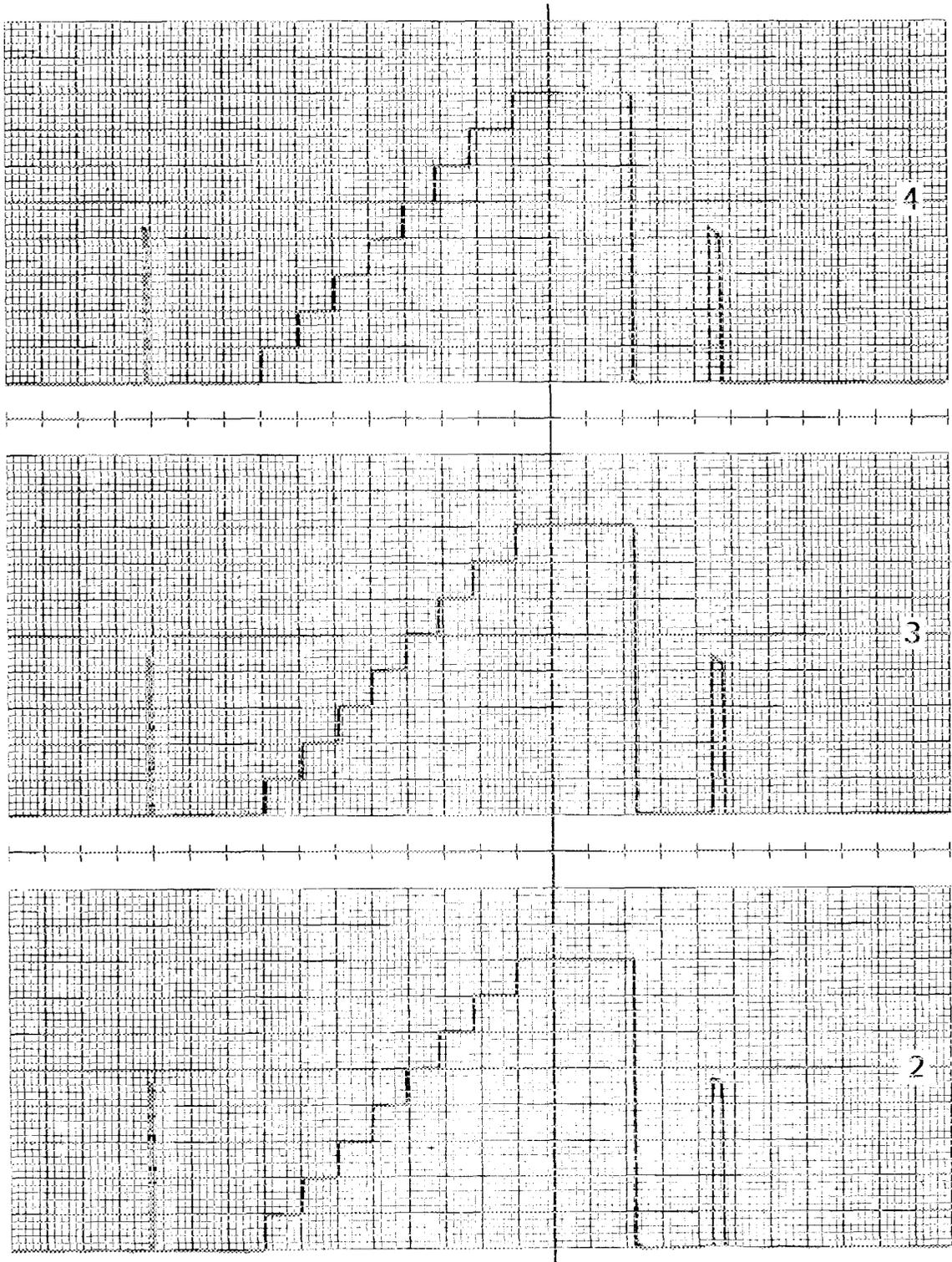


Fig. 22. Step voltage calibration record (strip chart).

PRECALIBRATION

After the eddy-current test system has completed the proper warm-up and stabilization and all systems have been verified, the following pre-test calibration checks were performed.

Three different sheath weld test samples were manually pulled through the sheath weld scanner and inspected. The three test samples were identified as A, 1, and 4, and they are described respectively in Tables 3, 1, and 2. (These are the same samples that were used to develop this test in the laboratory.) Three channels of strip-chart data representing only the sheath weld area made during a check of weld test sample 1 at the Oxford-Airco site are shown in Fig. 23. The predominant discontinuity indications can be seen on channel 3 (the center channel). This scan was made down the center of the weld. Scans 2 and 4 were made down the edges of the weld. Transverse notches should be detected by both scans, but the longitudinal notches may or may not be detected because of the limited area of coverage of the eddy-current probe. The discontinuities are identified above the indications on channel 3. These data can be compared with Fig. 17, which represents a single scan of the same sample performed in the laboratory at ORNL. The data from these pretest calibrations were recorded on the analog recorder and were compared with previous data for the same samples to make sure that the test sensitivity and repeatability were satisfactory. The strip-chart recordings were identified and maintained for reference.

PERFORMING THE TEST

The sheath weld scanner was placed on the superconductor cable in the production line assembly. Some initial checks were made, and, in coordination with other functions such as welding, the assembly operation was started. The assembly (welding, forming, inspection, and shaping) then ran continuously until the desired length of the superconductor cable had been fabricated and wound into a large coil. The average continuous inspection time to complete the coil assembly was about 3 h. The raw data (magnitude and phases for three frequencies) were recorded on magnetic tape, and calculated data (discontinuities and lack of weld penetration) were displayed on the strip-chart recorder. The strip-chart data were

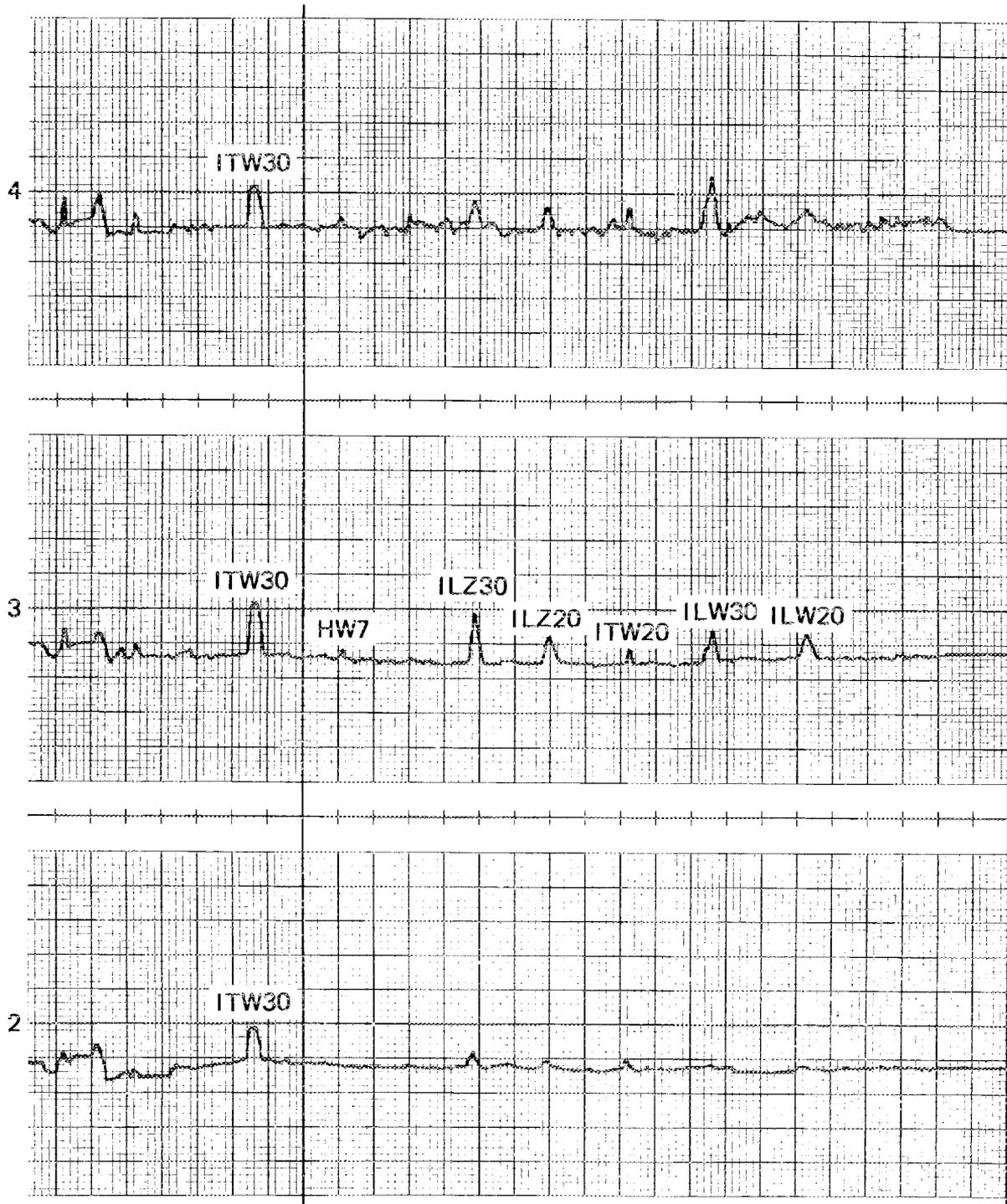


Fig. 23. Strip-chart recording, test calibration (sample 1).

observed during the inspection and were found to be very beneficial to the welder to help maintain alignment of the weld joint. Since we could not stop the superconductor cable for a complete evaluation of each eddy-current indication as it was obtained, we installed a marker pen on the sheath weld scanner. Whenever an eddy-current indication was obtained that exceeded a preset reference level, the microcomputer extended the marker pen (by operating a solid state relay), and an ink mark was placed on the steel sheath in the vicinity of the discontinuity that caused the indication. These areas were later reinspected with the manual scanner to determine whether weld repair was needed.

POSTCALIBRATION

After the completion of the production line inspection, a posttest calibration was performed on the MFEC system. The three weld test samples described under the pretest were rechecked, and the data were compared with the pretest data to make sure that no significant changes had occurred in the test system. These data were identified and recorded on both analog and digital recorders.

After the postcalibration, the data on the tapes (strip chart and magnetic) were reexamined by a manual scanning technique to determine what areas, if any, needed to be reinspected. A more thorough investigation could be made with the manual technique, and the discontinuity could be pinpointed more accurately for repair, if needed. The hand evaluation provides more information about the discontinuity than does the regular production scan. This will be discussed in more detail in the next section.

MANUAL INSPECTION FOR WELD REPAIRS

After the production line inspection of the superconductor sheath weld was completed, those areas where significant eddy-current indications had been obtained needed reinspection. (The number of significant eddy-current indications was typically fewer than ten per production run.) The general areas where the indications occurred could be determined by two techniques, by examining the recorded data and by looking for ink marks on

the steel sheath. In all cases the strip-chart recordings were reexamined, and a second inspection was performed to examine the area causing the indication to determine if weld repair was necessary.

The technique for inspecting for weld repairs was similar to that for the production line inspection. The major difference was that a hand-held manual scanning device was used, and sheath weld sample D (having a rectangular cross section) was used for the pre- and postcalibration inspections. The data obtained during the manual inspection were recorded on the analog recorder but not recorded on magnetic tape.

The manual scanning setup is shown in Fig. 24. The same instrumentation and eddy-current probe were used with both scanning devices. A time lapse usually occurred between the completion of a production run and the inspection for weld repair; therefore, the four basic procedural steps

CYN-5923



Fig. 24. Manual scanner and instrument.

were normally repeated: (1) initial system check, (2) precalibration, (3) perform test, and (4) postcalibration. The manual inspection procedure was very similar to the production line procedure, and many of the steps were duplicated. The inspection procedure in Appendix I describes the steps necessary to perform the manual inspection for weld repair.

The initial system check was identical except that a few switches were changed on the control box and microcomputer to select different software for the analog data analysis. The manually controlled motion of the eddy-current probe produced only a single scan of raw eddy-current data along one axis of the sheath weld. These data were recorded, analyzed by the microcomputer, and displayed on four channels of the strip-chart recorder. Channels 1 through 4 on the recorder represented, respectively, discontinuities on the outer surface, lift-off, discontinuities on the inner surface, and lack of weld penetration. The operator made as many scans of the suspect area on the weld as were necessary to relocate the indication obtained during the production run. The area was then thoroughly examined to determine if a weld repair was necessary and to determine the size of the area to be repaired. The weld repair was made by locally grinding the weld to remove the bad area and then rewelding. After the weld repair had been completed, the manual eddy-current inspection was repeated to determine if the repair was successful.

The manual inspection was also used to relocate the copper leader and trailer that were swaged to each end of the conductor of the superconductor cable. These areas were not visible after assembly because they were encased by the steel sheath, but their precise location (for removal) was easily accomplished with the eddy-current inspection system.

SUMMARY AND CONCLUSIONS

We have shown that multifrequency eddy-current techniques can be used to selectively suppress the large signals generated by a large central conductor and perform the continuous on-line inspection of a seam weld in a steel sheath. A unique scanning device was developed to provide full inspection coverage for the seam weld and heat-affected zones. The raw

eddy-current data were recorded on magnetic tape, and properties such as discontinuity size and location as well as lift-off and lack of weld penetration could be determined from these data. The various properties were determined by applying the appropriate mathematical fits to the raw data by use of a microcomputer. The coefficients for these mathematical fits were predetermined by the use of test samples in the laboratory. This study provided another example of how multiple-parameter problems can be solved by the use of multifrequency eddy-current techniques. Further significant improvements could (and should) be made through development of additional computer-based data processing for decision making (e.g., via pattern recognition). Limitations in available funding restricted the amount of data processing development to only the minimum required.

This successful test was applied on the welding line of the Oxford-Airco plant and assured the welding quality of the superconducting cable used in the large coil superconducting magnet made by Westinghouse.

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Appendix A

PROGRAM BIGRDG

A data file must be established to use this program. The program BIGRDG reads the property and positioning data from the data file through the logical input device (LID). It controls the mechanical scanners and the multifrequency eddy-current (MFEC) instrument to position the eddy-current coil at the specified coordinates on the test sample(s) and then reads and records the magnitude and phase data for each frequency. These magnitude and phase data are stored along with the corresponding property data provided in the data file. Subroutines provide the ability to calibrate the equipment prior to beginning the run. A brief summary of the program follows.

<u>Lines</u>	<u>Actions</u>
1-34	Information and definition of parameters.
35-50	Assign dimensions.
50-58	Define data files.
59-70	Assign data values.
71-90	Print title, time and date.
91-156	Coil, instrument, and test properties are recorded from the data file.
157-165	Property values and positioning data are read from the data file.
166-185	The pretest instrument calibration is performed.
186-196	Voltage readings are recorded from the eddy-current coil (usually placed at a reference position on the standard test sample).
197-214	Initialization and setup for the start of the test.
215-252	Actual eddy-current readings (magnitude and phase) are taken.
253-260	The scanner is returned to the initial or start position.
261-270	The posttest instrument calibration check is made.
271-277	The eddy-current readings are averaged, and standard deviations are calculated.
278-300	The data are stored on the designated RAD file.

<u>Lines</u>	<u>Actions</u>
301-365	Job statistics, calibration readings, and the eddy-current readings are printed out on the line printer.
366-EOP	The subroutine "POSITION" (written in FORTRAN and machine language) is used to control the scanners or positioners that move the eddy-current coil to the areas on the test sample specified by the coordinates in the data file.

```

1      PROGRAM DIGRDG
2 C      (1 JUNE 1981)
3 C
4 C THIS PROGRAM READS MAGNITUDE AND PHASE DATA AT DIFFERENT
5 C FREQUENCIES, USING THE PHASE SENSITIVE INSTRUMENT AND THE
6 C MECHANICAL SCANNER. IT IS DESIGNED FOR LARGE ARRAYS OF READINGS
7 C TOO LARGE FOR THE NORMAL READING AND FITTING ROUTINES.
8 C THE MAGNITUDE AND PHASE DATA IS STORED AFTER EACH SET OF PROPERTIES
9 C THE PROPERTY AND POSITIONING DATA IS READ FROM DEVICE LID.
10 C
11      REAL*8 TITLE(3)
12      REAL*6 NPROBE, NCADLE, INSTNO, POWDSC, PICKAM, PHADET, COIL
13      DIMENSION XNEW(3), IDAY(3), ITIM(3), IDY(3), ITH(3)
14 C
15 C LI=LOGICAL INPUT TERMINAL(FROM OPERATOR)
16 C LID=LOGICAL INPUT TERMINAL(MAY BE ASSIGNED TO A DISK FILE)
17 C LOT=LOGICAL OUTPUT TERMINAL(TO OPERATOR)
18 C LPT=LINE PRINTER(OUTPUT) TERMINAL
19 C MAG=INDEX TO TURN ON THE SATURATING MAGNET(=0 IF NONE USED)
20 C NSET=NO OF SETS OF READINGS THAT WILL BE TAKEN
21 C NCHS=NUMBER OF CHANNELS
22 C NFF=NUMBER OF FREQUENCIES
23 C LNF=2*NFF
24 C NF=FREQUENCY INDEX
25 C NAXIS=NUMBER OF AXIS THAT ARE POSITIONED
26 C NSTOP=INDEX TO STOP THE INSTRUMENT READINGS
27 C NFILIM=FILE LIMIT ON LINES IN FILE 37, THE DATA FILE
28 C NP=PROPERTY INDEX
29 C NPROPM=MAX NUMBER OF PROPERTIES THAT MAY VARY
30 C NPT=TOTAL NUMBER OF SETS OF PROPERTY VALUES FOR A COMPLETE
31 C SET OF READINGS=NO SAMPLES+NO DEFECTS
32 C NPHCAL=NUMBER OF PHASE CALIBRATIONS
33 C NMSCAL=NUMBER OF MAGNITUDE CALIBRATIONS
34 C NCAL=NPHCAL+NMSCAL=TOTAL NUMBER OF CALIBRATION READINGS
35 C
36 C DIMENSION FREQ(NFF), PICKAM(NFF), PHADET(NFF), PHASW(NFF)
37 C DIMENSION TMAG(NPT, NFF), PHASE(NPT, NFF), PROP(NPT, NPROPM)
38 C DIMENSION SUNCAL(2*NFF, NCAL), SSCAL(2*NFF, NCAL), SDVCAL(2*NFF, NCAL)
39 C DIMENSION VOLTS(2+2*NFF), RDGC(2+2*NFF, NCAL), OLRDGC(2+2*NFF, NCAL)
40 C DIMENSION PRONAM(NPROPM), POST(NPT, NAXIS)
41 C DIMENSION TOPSET(2+2*NFF), TSLOPE(2+2*NFF)
42 C
43      DIMENSION FREQ(3), PICKAM(3), PHADET(3), PHASW(3)
44      DIMENSION TMAG(1250, 3), PHASE(1250, 3), PROP(1250, 6)
45      DIMENSION SUNCAL(6, 4), SSCAL(6, 4), SDVCAL(6, 4)
46      DIMENSION VOLTS(6), VOLSTD(6), RDGC(6, 4), OLRDGC(6, 4)
47      DIMENSION PRONAM(6), POST(1250, 2)
48 C DIMENSION TOPSET(6), TSLOPE(6)
49      COMMON/83/COIL, RBAR, R1, R2, XL, ZL, RLIM, R6, R7, TNR, TNP, ZLDR, ZLPU, X
50 C
51 C ***CAUTION***BE SURE ENOUGH SPACE HAS BEEN ALLOCATED ON RAD FILE 37
52 C FOR WRITING ALL THE RECORDS OUTPUT BY THIS PROGRAM. NUMBER OF
53 C RECORDS IN THIS DEFINE STATEMENT(NFILIM-FIRST * IN PARENTHESES)
54 C SHOULD EQUAL AT LEAST 4*NPT. THE SECOND SHOULD BE .GE. 2+4*NFF
55 C +2*NPROPM.
56 C
57      DEFINE FILE 37(1500, 40, U, IREC)
58      DEFINE FILE 29(00, 32, U, NCOIL)

```

```

59 C
60 DATA LI/1/,LID/9/,LOT/5/,LPT/6/,NCHS/6/,NFILIM/1500/,MSET/3/
61 DATA TITLE/' TUBING CALIBRATION DATA '/,BLANKS/' '/
62 DATA ITIMS/64/,MAG/0/,NPHCAL/2/,NHRCAL/2/
63 DATA NAXIS/2/,NPT/1000/,NPROPM/6/
64 C DATA TUFSET/2.27,-1.4992,1.01,-1.32,-.47935,-.70,2*0./
65 C DATA TSLOPE/-.1575,.0906,-.0646,.1034,-.0265,.0596,2*0./
66 INLINE
67 LDI,3 *0057 RESET,S1 LO, INTERRUPT,S2 HI,0101/0111
68 ODD,3,6 OUTPUT TO PORT 36
69 FINI
70 C
71 C PRINT TITLE AND DATE
72 C
73 10 WRITE (LOT,20) TITLE
74 20 FORMAT(1X,3A0)
75 30 FORMAT(1H )
76 CALL DATE(IDAY)
77 CALL TIME(ITIM)
78 IT=IDAY(1)-1900
79 IDAY(1)=IDAY(2)
80 IDAY(2)=IDAY(3)
81 IDAY(3)=IT
82 WRITE(LOT,40) IDAY,ITIM
83 40 FORMAT(' DATE ',2(I2,1H/),I2,' TIME ',2(I2,1H/),I2)
84 INLINE
85 LDI,3 *0067 INTERRUPT,S1 LO,RESET,S2 HI,0110/0111
86 ODD,3,6 OUTPUT TO PORT 36
87 FINI
88 WRITE(LOT,50)
89 50 FORMAT(' TYPE IN THE FOLLOWING DATA AS REQUESTED. ')
90 C
91 C INPUT DESCRIPTION OF EXPERIMENTAL APPARATUS
92 C
93 WRITE(LOT,60)
94 60 FORMAT(' PROBE #: ')
95 READ(LID,70)NPROBE
96 70 FORMAT(A6)
97 C
98 C THE COIL PROPERTIES ARE CALLED FROM FILE 29.
99 C
100 CALL CIRCOL(LI,LOT,NPROBE)
101 C
102 WRITE(LOT,80)
103 80 FORMAT(' SERIAL #: ')
104 READ(LID,*)NSER
105 WRITE(LOT,90)
106 90 FORMAT(' DRIVER SERIES RESISTANCE: ')
107 READ(LID,*)R0
108 WRITE(LOT,100)
109 100 FORMAT(' DRIVER SHUNT CAP: ')
110 READ(LID,*)CAPDR
111 WRITE(LOT,110)
112 110 FORMAT(' PICK-UP SHUNT RESISTANCE: ')
113 READ(LID,*)R9
114 WRITE(LOT,120)
115 120 FORMAT(' PICK-UP SHUNT CAP: ')
116 READ(LID,*)CAPPU

```

```

117      WRITE(LOT,130)
118 130   FORMAT(' CABLE I.D. #: ')
119      READ(LID,70)NCABLE
120      WRITE(LOT,140)
121 140   FORMAT(' LENGTH OF CABLE: ')
122      READ(LID,*)CABLEL
123      WRITE(LOT,150)
124 150   FORMAT(' CAPACITANCE OF CABLE: ')
125      READ(LID,*)CCABLE
126      WRITE(LOT,160)
127 160   FORMAT(' EDDY CURRENT INSTRUMENT #: ')
128      READ(LID,70)INSTNO
129      WRITE(LOT,170)
130 170   FORMAT(' POWER OSC I.D.: ')
131      READ(LID,70)POWOSC
132      C
133      C INPUT FREQUENCY VALUES
134      C
135      WRITE(LOT,190)
136 190   FORMAT(' NO. OF FREQUENCIES:')
137      READ(LID,*)NFT
138      WRITE(LOT,200)
139 200   FORMAT(' INPUT THE VALUE OF EACH FREQ SEPARATED BY A SPACE: ',/)
140      READ(LID,*)(FREQ(NF),NF=1,NFT)
141      WRITE(LOT,210)(FREQ(NF),NF=1,NFT)
142 210   FORMAT(' INPUT THE FOLLOWING DATA,6 CHAR WITH A SPACE BETWEEN',/,
143 * ' FREQUENCY:',10X,10(1PE9.2))
144      WRITE(LOT,220)
145 220   FORMAT(' PICK-UP AMP I.D.: ')
146      READ(LID,230)(PICKAM(NF),NF=1,NFT)
147 230   FORMAT(10(A6,1X))
148      WRITE(LOT,240)
149 240   FORMAT(' PHASE DETECTOR I.D.: ',)
150      READ(LID,230)(PHADET(NF),NF=1,NFT)
151      WRITE(LOT,250)
152 250   FORMAT(' 180-DEG SW(OFF/ON): ')
153      READ(LID,260)(PHASW(NF),NF=1,NFT)
154 260   FORMAT(10(A3,1X))
155      READ(LID,270)(PRONAM(NPR),NPR=1,NPROPM)
156 270   FORMAT(6(A4,1X))
157      C
158      C READ PROPERTY VALUES AND LOCATION DATA FOR THE POSITIONERS FROM LID
159      C
160      DO 300 NP=1,NPT
161      READ(LID,*)((PROP(NP,NPR),NPR=1,NPROPM),(POST(NP,NAX),NAX=1,
162 *NAXIS))
163 300   CONTINUE
164 690   ASSIGN 773 TO HSTATE
165      C
166      C THIS SECTION TAKES THE CALIBRATION READINGS.
167      C
168      INLINE
169      LDI,3          #0077          S1 L0,RESET,INTERUPT,S2 H1,0111/0111
170      ODD,3,6       OUTPUT TO PORT 36
171      FINI
172      MSE=0
173 700   WRITE(LOT,710)
174 710   FORMAT(' CALIBRATION READINGS: ')

```

```

175 750 CALL CALMIC(RDGC,NCHS,NSTOP)
176 IF(NSTOP.NE.0.AND.NSE.EQ.0) GO TO 750
177 LNF=2*NFT
178 NCAL=NPHCAL*NMGCAL
179 DO 770 NF=1,LNF
180 DO 770 NC=1,NCAL
181 OLRDGC(NF,NC)=RDGC(NF,NC)
182 770 CONTINUE
183 GO TO NSTATE
184 C
185 C END OF SECTION WHICH TAKES CALIBRATION READINGS
186 C
187 C TAKE READINGS ON NOMINAL STANDARD FOR VOLSTD(I) READINGS
188 C
189 773 WRITE(LOT,775)
190 775 FORMAT(' INSERT PROBE INTO STANDARD TUBE')
191 WRITE(LOT,920)(BLANKS,II,II, II=1,NFT)
192 WRITE(LOT,30)
193 780 CALL RDGMIC(VOLSTD,NCHS,ITIMS,NRET,NSTOP,0,8)
194 WRITE(LOT,950)(VOLSTD(NF),NF=1,LNF)
195 IF(NSTOP.NE.0.) GO TO 780
196 WRITE(LOT,785)
197 785 FORMAT(' SET UP SCANNER AND CALIB STANDARD,PRESS FOOT SW TO GO')
198 787 CALL RDGMIC(VOLTS,NCHS,ITIMS,NRET,NSTOP,0,0)
199 IF(NSTOP.NE.0.) GO TO 787
200 C ZERO ARRAYS THAT WILL CONTAIN SUMS OF THE PHASE & MAG READINGS,
201 C SUMS OF CALIBRATION READINGS, AND SUMS OF SQUARES OF EACH
202 C
203 790 CONTINUE
204 DO 800 NF=1,NFT
205 DO 800 NP=1,NPT
206 TMAG(NP,NF)=0.
207 PHASE(NP,NF)=0.
208 800 CONTINUE
209 DO 810 NF=1,LNF
210 DO 810 NC=1,NCAL
211 SUMCAL(NF,NC)=OLRDGC(NF,NC)
212 SSCAL(NF,NC)=OLRDGC(NF,NC)*OLRDGC(NF,NC)
213 810 CONTINUE
214 C
215 C THIS SECTION TAKES THE ACTUAL PHASE & MAGNITUDE DATA READINGS
216 C
217 DO 1150 MSE=1,MSET
218 NCOUNT=0
219 NRET=1
220 DO 900 NP=1,NPT
221 WRITE(LOT,900)NP,(PROP(NP,NPR),NPR=1,NPROPN)
222 900 FORMAT(1X,I4,3X,6(1X,F8.5))
223 C
224 C POSITION SAMPLES BEFORE TAKING READINGS
225 C
226 DO 910 NAX=1,NAXIS
227 XNEW(NAX)=POST(NP,NAX)
228 910 CONTINUE
229 CALL POSITION(XNEW,NAXIS)
230 MAXCH=2*(NFT-1)+1
231 WRITE(LOT,920)(BLANKS,II,II, II=1,NFT)
232 920 FORMAT(3X,10(A1,'MAG(',II,')',4X,'PH(',II,')',5X))

```

```

233      WRITE(LOT,30)
234 930    CALL RDGMIC(VOLTS,NCHS,ITIMS,NRET,NSTOP,0,0)
235      WRITE(LOT,950)((VOLTS(JJ),VOLTS(JJ+1)),JJ=1,MAXCH,2)
236 950    FORMAT(1H+,10(F9.4,2X))
237      IF(MAG.EQ.1)CALL RDGMIC(VOLTS,NCHS,12,NRET,NSTOP,MAG,0)
238      CALL SATMAG(0)
239      NRET=0
240      DO 980 NF=1,NFT
241          TMAG(NP,NF)=TMAG(NP,NF)+VOLTS(2*NF-1)
242          PHASE(NP,NF)=PHASE(NP,NF)+VOLTS(2*NF)
243 980    CONTINUE
244      ASSIGN 1000 TO NSTATE
245      GO TO 700
246 1000   CONTINUE
247      DO 1130 NF=1,LNF
248          DO 1130 NC=1,NCAL
249              SUMCAL(NF,NC)=SUMCAL(NF,NC)+OLDRDGC(NF,NC)
250              SSCAL(NF,NC)=SSCAL(NF,NC)+OLDRDGC(NF,NC)*OLDRDGC(NF,NC)
251 1130   CONTINUE
252 1150   CONTINUE
253      C
254      C RETURN POSITIONER TO XNEW(II)=0.0 SO THAT POSITIONS CAN BE CHECKED
255      C
256          DO 1160 NAX=1,NAXIS
257              XNEW(NAX)=0.0
258 1160   CONTINUE
259          CALL POSITION(XNEW,NAXIS)
260      C
261      C BEFORE STOPPING, ADD FINAL SET OF CALIBRATION READINGS TO CUMULATIVE
262      C SUM & CALCULATE AVERAGES & STANDARD DEVIATIONS
263      C
264 1190   DO 1250 NF=1,LNF
265          DO 1250 NC=1,NCAL
266              SUMCAL(NF,NC)=SUMCAL(NF,NC)/(FLOAT(MSET)+1)
267              SDVCAL(NF,NC)=SQRT(ABS((SSCAL(NF,NC)-SUMCAL(NF,NC)*SUMCAL(NF,NC)
268                  *FLOAT(MSET+1))/FLOAT(MSET)))
269 1250   CONTINUE
270      C
271      C CALCULATE AVERAGES & STANDARD DEVIATIONS OF READINGS
272      C
273          DO 1290 NF=1,NFT
274              DO 1290 NP=1,NPT
275                  TMAG(NP,NF)=TMAG(NP,NF)/(FLOAT(MSET))
276                  PHASE(NP,NF)=PHASE(NP,NF)/(FLOAT(MSET))
277 1290   CONTINUE
278      C
279      C STORE ALL INFORMATION IN DIRECT ACCESS FILE #37 ON DISK
280      C
281          IREC=1
282          WRITE(37*IREC) TITLE,IDAY,ITIM
283          WRITE(37*IREC) HPROBE,NSER,R0,CAPDR,R9,CAPPU,NCABLE,
284          * CABLEL,CCABLE,INSTNO,POWOSC
285          WRITE(37*IREC) NFT,NPT,NPROPM,NPHCAL,NMGCAL
286          WRITE(37*IREC)((FREQ(NF),PICKAM(NF),PHADET(NF),PHASW(NF)),
287          *NF=1,NFT)
288          WRITE(37*IREC)(PRONAM(NPR),NPR=1,NPROPM)
289          DO 1295 NF=1,LNF
290              WRITE(37*IREC)(SUMCAL(NF,NC),NC=1,NCAL)

```

```

291 1295 CONTINUE
292 WRITE (37'IREC) (VOLSTD(NF),NF=1,LNF)
293 DO 1300 NP=1,NPT
294 WRITE (37'IREC) ((TMAG(NP,NF),PHASE(NP,NF),NF=1,NFT),(PROP(NP,
295 *NPR),NPR=1,NPROPM))
296 1300 CONTINUE
297 IF(IREC.GE.NFILIM) WRITE(LOT,1330)
298 1330 FORMAT(' LIMIT OF FILE 37 IS EXCEEDED.')
299 C
300 C END OF SECTION WHICH WRITES DIRECT ACCESS FILE
301 C PRINT SUMMARY OF JOB STATISTICS ON LPT
302 C
303 WRITE(LPT,1335)
304 1335 FORMAT(1H1,20X)
305 WRITE(LPT,1340) IDAY,ITIM
306 1340 FORMAT(' TUBRDG: DATE ',2(I2,1H/),I2,' TIME ',2(I2,1H/),I2)
307 WRITE(LPT,1350) NPROBE,NSER
308 1350 FORMAT(' PROBE NO.:',A6,5X,' SERIAL NO.:',I5)
309 WRITE(LPT,1360) R0,CAPDR
310 1360 FORMAT(' DRIVER SERIES RESISTANCE:',F10.1,5X,' DRIVER SHUNT CAP.:',
311 * E12.4)
312 WRITE(LPT,1370) R0,CAPPU
313 1370 FORMAT(' PICK-UP SHUNT RESISTANCE:',F10.1,5X,' PICK-UP SHUNT CAP.:',
314 * ,E12.4)
315 WRITE(LPT,1380) NCABLE,CADLEL,CCABLE
316 1380 FORMAT(' CABLE I.D. NO.:',A6,5X,' LENGTH:',F10.1,5X,' CAP.:',
317 * E12.4)
318 WRITE(LPT,1390) INSTHU
319 1390 FORMAT(' EDDY CURRENT INSTRUMENT NO.:',A6)
320 WRITE(LPT,1400) POWOSC
321 1400 FORMAT(' POWER OSC I.D.',A6)
322 WRITE(LPT,1410) (FREQ(NF),NF=1,NFT)
323 1410 FORMAT('/',10X,' FREQUENCY:',10(1PE12.4,5X))
324 WRITE(LPT,1420) (PICKAN(NF),NF=1,NFT)
325 1420 FORMAT(' PICK-UP AMP I.D.:',7X,10(A6,9X))
326 WRITE(LPT,1430) (PHADET(NF),NF=1,NFT)
327 1430 FORMAT(' PHASE DETECTOR I.D.:',4X,10(A6,9X))
328 WRITE(LPT,1440) (PHASU(NF),NF=1,NFT)
329 1440 FORMAT(' 180 PHASE SWITCH:',8X,10(A6,12X))
330 C
331 C PRINT CALIBRATION READINGS
332 C
333 1600 CONTINUE
334 WRITE(LPT,1650) NPHCAL,NMGCAL
335 1650 FORMAT(1H0,' AVERAGES & STANDARD DEVIATIONS OF CALIBRATION ',
336 * ' READINGS:',I3,' MAG',I3,' PHA'/)
337 WRITE(LPT,1660) (FREQ(NF),NF=1,NFT)
338 1660 FORMAT(3(10X,1PE12.4))
339 WRITE(LPT,1670) (NF,NF,NF=1,NF=1)
340 1670 FORMAT(5X,3(5X,' MAG',I1,6X,' PHA',I1,1X))
341 DO 1700 NC=1,NCAL
342 WRITE(LPT,30)
343 WRITE(LPT,1680) ((SUMCAL(NF,NC)),NF=1,LNF)
344 1680 FORMAT(5X,6(F10.4))
345 WRITE(LPT,1690) ((SDVCAL(NF,NC)),NF=1,LNF)
346 1690 FORMAT(' S.D.',6(F10.4))
347 1700 CONTINUE
348 C

```

```

349 C READINGS FROM NOMINAL SAMPLE
350 C
351 WRITE(LPT,1745)
352 1745 FORMAT(' READINGS FROM NOMINAL TUBE SAMPLE')
353 WRITE(LPT,1600)(VOLSTD(NF),NF=1,LFNF)
354 C
355 C PRINT OUT READINGS AND PROPERTIES
356 C
357 WRITE(LPT,1750)(NF,NF,NF=1,NFT),(PRONAM(NPR),NPR=1,NPROPM)
358 1750 FORMAT(1X,'PSET',3(' MAG',11,' PHA',11),6(4X,A4,1X))
359 DO 1800 NP=1,NPT
360 WRITE(LPT,1760)NP,((TMAG(NP,NF),PHASE(NP,NF),NF=1,NFT),(PROP(NP,
361 *NPR),NPR=1,NPROPM))
362 1760 FORMAT(1X,I4,12(F9.4))
363 1800 CONTINUE
364 STOP JOB
365 END
366 C
367 SUBROUTINE POSITION(XNEW,NAXIS)
368 C
369 C POSITION VERSION 4/15/81
370 C DETERMINES THE NEW LOCATION FOR 3 DIFFERENT POSITIONERS AND FROM
371 C THE OLD LOCATION,THE NUMBER OF STEPS NEEDED TO REACH THE NEW
372 C LOCATION.THEN ISSUE THE NUMBER OF PULSES TO GO TO THE NEW LOCATION
373 C
374 INTEGER*2 REG(8),NCOUNT,NAX
375 DIMENSION XOLD(3),XNEW(3),NSTEPS(3)
376 DATA XOLD/3*0.0/,STEPSZ/0.00025/
377 DO 20 IAXIS=1,NAXIS
378 NSTEPS(IAXIS)=(0.5*STEPSZ+XNEW(IAXIS)-XOLD(IAXIS))/STEPSZ
379 XOLD(IAXIS)=XOLD(IAXIS)+FLOAT(NSTEPS(IAXIS))*STEPSZ
380 20 CONTINUE
381 C
382 C
383 1 DO 200 NAX=1,NAXIS
384 IF(NSTEPS(NAX).EQ.0)GO TO 190
385 REG(1)=0
386 IF(NSTEPS(NAX).GE.0)GO TO 10
387 REG(1)=8
388 NSTEPS(NAX)=-NSTEPS(NAX)
389 10 CONTINUE
390 C
391 C SIGN SET IN REG(1);CONVERT NSTEP TO BCD IN REG(2)-REG(6)
392 C
393 DO 30 NRG=2,6
394 REG(NRG)=NSTEPS(NAX)/10000
395 NSTEPS(NAX)=(NSTEPS(NAX)-10000*REG(NRG))*10
396 30 CONTINUE
397 C
398 C DATA FOR OUTPUT IN REG(NRG);OUTPUT TO APPROPRIATE CONTROLLER
399 C
400 NCOUNT=NAX-1
401 INLINE
402 LDI,1 0 ZERO REGISTER 1,USE AS INDEX,COUNTER
403 LDM,2 NCOUNT LOAD THE CONTROLLER SELECT CHANL
404 LLS,2,4 LOGICAL LEFT SHIFT REG2,4 PLACES
405 ADM,2,1 REG ADD SIGN TO REGISTER 2
406 MBL,2,2 SHIFT BYTE LEFT

```

```

407      ADI,2      #00FF      LEAVE CALIBRATE BITS ,COUNTER HI
408      ODD,2,3      OUTPUT REG 2 TO MODAC PORT 33
409      LOP5      IDD,3,1      INPUT PORTS1 INTO REG3
410      TBRB,3,15      LOP5      STAY IN LOOP UNTIL BUSY GOES HI
411      LBRB,4,14      LOP6      BIT14 IN REG 4 HI,XFER TO LOP5
412      LOP1      IDD,4,1      INPUT PORT 31 TO REG 4
413      LOP6      ABR,1,15      INCREMENT REGISTER 1
414      LDM,2,1      REG      LOAD BUS VALUE INTO REG 2
415      MBL,2,2      SHIFT BYTE IN REG 2 TO LEFT
416      ADI,2      #00FF      TAKE INDEX BIT HI,LEAVE CALIBRATE HI
417      LOP2      IDD,3,1      INPUT PORT 31 INTO REG 3
418      TBRB,3,15      LOP4      JUMP TO ERROR LOOP IF NOT BUSY
419      XOR,3,4      EXCLUSIVE OR REG 3&4,RESULT IN 3
420      TOR,3,3      TAKE ONE'S COMPLIMENT OF REG 3
421      TBRB,3,14      LOP2      BIT 14=0 WHEN DATA STROBE SWITCHES
422      ODD,2,3      OUTPUT REG 2 TO MODAC PORT 33
423      CRI,1      6      COMPARE REG 1 TO 6
424      BLNS,0      LOP1      BRANCH BACK IF REG 1.LT.6
425      LOP4      LDI,2      #B0FF      LOAD ALL HI INTO 2
426      ODD,2,3      SEND ALL OUTPUTS HI
427      LOP3      IDD,3,1      INPUT PORT 31 TO REG 3
428      TOR,3,3      TAKE ONE'S COMPLIMENT OF REG 3
429      TBRB,3,15      LOP3      BRANCH BACK IF BUSY
430      FINI
431      190 CONTINUE
432      200 CONTINUE
433      C
434      C      CHECK FOR POSITION FINISHED
435      C      HANG HERE UNTIL ALL POSITIONS ARE REACHED
436      C
437      300 CONTINUE
438      JSTEP=0
439      DO 400 NAX=1,NAXIS
440      NCOUNT=NAX-1
441      INLINE
442      LDM,2      NAX      LOAD THE COUNTER SELECT CHANL
443      LDI,3      #B0FF      LOAD ALL HI INTO 3,TO RD BUSY
444      ODD,3,3      OUTPUT TO PORT 33,READ BUSY,OVERFLOW
445      IDD,4,1      READ BUSY,OVERFLOW INTO REG4
446      RLS,4,1      DUMP BUSY BY SHIFT
447      LOP7      RLS,4,1      LINK OVERFLOWCHNL BIT LEAST SIGNIFICANT
448      SBRB,2,15      LOP7      DECREMENT NAX,XFER BACK IF .NE.0
449      ETI,4      #FFFE      DUMP ALL BUT LEAST SIGNIFICANT BIT
450      LDM,2      NCOUNT      LOAD THE COUNTER SELECT CHANL
451      LLS,2,6      LOGICAL LEFT SHIFT REG2,6 PLACES
452      ADI,2      #B00F      LEAVE CALIBRATE BITS HI
453      ODD,2,3      OUTPUT REG 2 TO MODAC PORT 33
454      IDD,5,1      INPUT COUNT HD INTO REG 5
455      STMD,4      KSTEPS      STORE COUNT POSITION IN MEMORY
456      LDI,2      #B0FF      SEND PROPER OUTPUTS HI
457      ODD,2,3      RESET PORT 33
458      FINI
459      JSTEPS=(XOLD(NAX)+.5*STEPS2)/STEPS2
460      350 NSTEPS(NAX)=JSTEPS -KSTEPS
461      360 JSTEP=JSTEP+NSTEPS(NAX)-KSTEPS(NAX)
462      400 CONTINUE
463      IF(JSTEP.GT.2)WRITE(S,410)
464      410 FORMAT(' TRANSLATOR ERROR ')

```

```
465         IF (JSTEP.GT.2)GO TO 1
466     420 CONTINUE
467         RETURN
468         END
TOTAL RECORDS WRITTEN = 489/ 74
EXIT
$QVR CI 4
SEND LIST
```


Appendix B

PROGRAM MICMOD

The program MICMOD (written in machine language) coordinates operations between the microcomputer in the multifrequency eddy-current (MFEC) instrument and the laboratory computer (MODCOMP IV). Actual eddy-current data are recorded from the analog-digital converters by the microcomputer on command from the MODCOMP computer. The data are then transferred to the MODCOMP through the handshake arrangement. The microcomputer will take readings from either the probe or the instrument calibrator on command from the MODCOMP.

```

1          TITLE 'MICROD PROGRAM VERSION 9 APRIL 81'
2          NAME   MICROD
3          LIST   D,G,O,T
4          MLIST  I,M,S,T
5          ;
6          ;
7          ; PROGRAM TO READ THE ADCONVERTORS ON COMMAND FROM THE
8          ; MODCOMP AND THEN TRANSFER DATA TO THE MODCOMP IN A
9          ; HANDSHAKING MANNER. THE 92 LINE IN THE MODCOMP FOLLOWS
10         ; THE REC LINE IN THE MICROCOMPUTER
11         ;
12         ; ORG 0000H          START PROGRAM IN SECOND PRUN.
13         ; SYMBOL DEFINITIONS
14         ;
15         ; DEFINE PORT ADDRESSES
16         ;
17         PORT1      EQU 07FH          PORT 1 CONTROL WORD ADDRESS
18         PORT1A     EQU 074H          PORT1A ADDRESS
19         PORT1B     EQU 075H          PORT1B ADDRESS
20         PORT1C     EQU 076H          PORT1C ADDRESS
21         PORT2      EQU 0EFH          PORT 2 CONTROL WORD ADDRESS
22         PORT2A     EQU 0E6H          PORT2A ADDRESS
23         PORT2B     EQU 0E7H          PORT2B ADDRESS
24         PORT2C     EQU 0E8H          PORT2C ADDRESS
25         PORT3      EQU 0DFH          PORT3 CONTROL WORD ADDRESS
26         PORT3A     EQU 0D6H          PORT3A ADDRESS
27         PORT3B     EQU 0D7H          PORT3B ADDRESS
28         PORT3C     EQU 0D8H          PORT3C ADDRESS
29         APDATA     EQU 07EH          ARITHMETIC PROCESSOR DATA PORT
30         ;
31         ; MATH SUBROUTINES FOR THE COMP 9 ARE STORED AS PUBLIC. ANY ROUTINE
32         ; CAN BE CALLED USING AN 'EXTRN' STATEMENT.
33         ;
34         ;EXTRN      ADDS,ASIN,ATAN,ATANA,BIDEC,DIDECF
35         ;EXTRN      CHDB,CHDBA,CHDF,CHFA,CHFS,CHSSA,COS,COSA
36         ;EXTRN      DADD,DADDA,DADD,DDIV,DDIVA,DDIVB,DECFD
37         ;EXTRN      FMUL,FMAA,FMULB,FNUU,FNUUA,FNUUB,DCUB,DSUBA,DSUBB
38         ;EXTRN      EXP,EXP1B,FADD,FADDN,FADD,FDIV,FDIVA,FDIVB
39         ;EXTRN      FIXD,FXDA,FXS,FXSA,FLTD,FLTA,FLTS,FLTA
40         ;EXTRN      FMUL,FMAA,FMULB,FSUB,FSUBA,FSUBB,LH,LHA,LOG,LOGA
41         ;EXTRN      NDAD,POFD,POPS,PTOD,PTOS,PUPI,PUR,PURA,PURB
42         ;EXTRN      SADD,SADDA,SADD,SDIV,SDIVA,SDIVB,SH,SHA
43         ;EXTRN      SML,SMAL,SMLB,SMU,SMUA,SMUB,SECT,SECTA
44         ;EXTRN      SUB,SOBA,SUBB,TAN,TANA,TOS2,TOS4
45         ;EXTRN      WRTD,WRTA,NCAD,NCAS
46         ;EXTRN      CROMT,COPDT,GETCH,PRINT,PRINTP,EPRINT,FPRINT,ZERO
47         ;EXTRN      GETM,CO,ROUT,ECHO,GETCH,GETX
48         ;
49         ;CONSTANTS ARE SET
50         NRDB       EQU 03H          NRDB=2*NRN=NUMBER OF RDUS PER CHANNEL=1
51         ;
52         NCRN       EQU 02H          NCRN=NUMBER OF CHANNELS TO BE READ
53         PRT1O      EQU 000H          PRT1O=CONTROL WORD FOR PORT1 OUTPUT MODE
54         PRT1I      EQU 000H          PRT1I=CONTROL WORD FOR PORT1 INPUT MODE

```


109	0061	E6 07		INI 07H	SET STATUS BITS
110				ISHOWT - DATA SUBTRACTION ROUTINE, STARTING WITH CHANNEL 1, READS NO OF	
111				CHANNELS IN C, WITH NO OF READINGS PER CHANNEL IN B (UP TO	
112				1000). SUM OF THE DATA WILL BE IN NACH -A + (A*CH. NO.)	
113				(A*CH. NO.) STORED AS NACH1, NACH2, NACH3, NACH4 BYTES EACH	
114	0062	01 10 00		CLMPT	HL LOADED WITH LAST DIT DATA ADDRESS
115	0063	05		FLCH 0	COPY OF DICE #0 STORED ON STACK
116	0067	79		NOV 0,0	NUMBER OF CHANNELS LOADED INTO A
117	0068	07		ADD 0	
118	0069	07		ADD 0	
119	006A	4F		NOV 0,0	NO. OF CHANNELS IN A
120	006B	0F		NSA 0	NO. OF CHANNELS IN REG C
121	006C	0F 00 00	E	CALL ZERO	A REGISTER ZEROED
122	006F	01		FLCH 0	ZERO NCH FROM HL TO HLAC
123	0070	11 00 00		FLCH 0	NO OF CHANNELS (REG C) * TIMES/CH (B) RES
124	0075	21 10 00		CALL B,NACH1+05H	LOAD 04 INTO DE
125	0076	05		FLCH 0	HL LOADED WITH FIRST DIT DATA ADDRESS
126	0077	3E 00		CHLUP	AND COPY STORED ON STACK AGAIN
127	0078	91		NOV 0	TOTAL NUMBER OF CHANNELS IN A
128	007A	CD 0E 00		CALL ADDS	NCH = TOTAL NO. - CHS COUNT IN REG C
129	007D	CD 00 00	E	CALL B,NACH	MAKE AD CCH RDG, ANSWER OR AP TOP OF STACK
130	0080	CD 00 00	E	CALL TOLP	02 DIT FIXED ADD TO DATA AT HL, HL=HL-3
131	0083	10		NOV 0	AP TOP OF STACK STORED IN NACH AT HL
132	0084	09		NOV 0	DE CND POINTS TO HL, POINTS TO NEXT ADDR
133	0085	03 77 00		CALL CHLUP	STANDARD LOOP (SUBTRACT)
134	0086	01		NOV 0	JUMP BACK TO LARGEST LOOP IF NOT FINISHED
135	0088	00		NOV 0	RESTORE DC FROM STACK
136	008A	C2 70 00		NOV 0	INCREMENT THE NUMBER OF ADDS/CHANNEL
137	008D	09		CALL CHLUP	GO BACK TO THE SUB LOOP IF NOT FINISHED
138				NOV 0	
139				NOV 0	SELECTS THE INCREMENT NUMBER THAT IS IN NACH, KEYS THE
140				NOV 0	IN DIT WITH THE CONVERTOR, HAS 00 ZERO AND RETURNS WITH
141				NOV 0	A POSITIVE 00 DIT VALUE REMAINS ON THE TOP OF THE STACK,
142	008E	00 00		NOV 0	FOR DIGITAL ALGEBRAIC CODES TO DIGITAL CONVERTER.
143	0090	03 F0		CALL B,NACH	IN 00L NO. CODES ON 00L, 00L ON ADC
144	0092	00 F4		NOV 0	SET CH. SWITCH TO CH. 10.
145	0094	03 7E		NOV 0	LOW ORDER BYTE IS BROUGHT IN AND
146	0096	00 F0		NOV 0	STORE ON ARITHMETIC PROCESSOR STACK.
147	0098	00 0F		NOV 0	HIGH ORDER BYTE IS BROUGHT IN.
148	009A	03 7E		NOV 0	A HIGHEST ORDER BITS ARE LUMPED
149	009C	00 F0		NOV 0	STORE ON ARITHMETIC PROCESSOR STACK.
150	009E	00 7E		NOV 0	AND 00L, 00L ON
151	009F	00 7E		NOV 0	STORE ON ARITHMETIC PROCESSOR STACK.
152	00A1	10 10		NOV 0	STORE ON ARITHMETIC PROCESSOR STACK.
153	00A3	00 F0		NOV 0	STORE DATA IN REGISTER CONVERTORS
154	00A5	00		NOV 0	AND TO PAPER
155				NOV 0	RETURNS WITH POS. ANSWER ON HP STACK.
156				NOV 0	
157				NOV 0	HERE ARE THE 00L COPY LINES OF THE DIGITAL
158				NOV 0	ALGEBRAIC REGISTER TO 00L, ALL CONVERTOR CODES LOW
159				NOV 0	AND FROM THE REGISTER CONVERTOR CAN BE READ FOR
160				NOV 0	THE DIT'S VALUE.
161	00A8	00 F0		NOV 0	STORE POSITIVE DATA AND ZERO ONLY
162	00AB	00 70		NOV 0	AND ALL DIT EXCEPT 0

163	00AA	C2	A6	00	JNZ ADSUS	STAY IN LOOP UNTIL BUSY LINE LOW	
164	00AD	C9			RET	START BIT WILL GO LO WHEN DATA CH READ	
165					;DELAY 2 FREQ. - GENERATES A TIME DELAY,DEPENDING ON THE CONSTANT LOADED		
166					;INTO BC, * CYCLES = 20*FFFF/(BC)		
167	00AE	E5			DELAY	PUSH H	SAVE THE CONTENTS OF HL AND
168	00AF	21	00	00		LXI H,0H	ZERO HL
169	00B2	09			LOPSM	DAD B	ADD BC TO THE CONTENTS OF HL
170	00B3	D2	02	00		JNC LOPSM	STAY IN LOOP UNTIL HL OVERFLOWS.
171	00B6	E1				POP H	THEIR ORIGINAL VALUES
172	00B7	C9				RET	AND RETURN.
173					:		
174					:		
175					:	WRMOD	WRITES RAW READINGS TO MODCOMP
176					:		
177	00B8	01	12	3C	WRMOD	LXI B,RAWDATA	BC IS STARTING ADDR OF RAW DATA
178	00B8	11	25	3C		LXI D,RAWDATA+15H	DE CONTAINS END ADDR OF RAW DATA
179	00BE	3E	06			MVI A,006H	SELECT MODCOMP,SET UP TO TOGGLE REC LINE
180	00C0	D3	F5			OUT PORT10	SEND TO PORT10
181	00C2	0A			WRMODL	LDAX B	LOAD BYTE ADDR BY B INTO A
182	00C3	D3	F4			OUT PORT1A	SEND TO PORT1A
183	00C5	CD	D4	00		CALL STBMLO	STROBE FIRST HALF OUT,RET WHEN MOD RDGS
184	00C8	0A				LDAX B	LOAD NEXT HALF OF ADC WORD
185	00C9	D3	F4			OUT PORT1A	SEND TO PORT
186	00CB	CD	E5	00		CALL STBMHI	STROBE 2ND HALF,RET WHEN MOD ACCEPTS
187	00CE	03				INX B	INCREMENT B TWICE
188	00CF	03				INX B	SKIP ZEROS IN RAM
189	00D0	D2	C2	00		JNC WRMODL	STAY IN LOOP UNTIL DONE
190	00D3	C9				RET	
191					:		
192					:	STBMLO	STROBE REC LO,HANG UNTIL S2 FOLLOWS
193					:		
194	00D4	3E	00		STBMLO	MVI A,00H	STROBE REC LINE LOW
195	00D6	D3	EE			OUT PORT2C	
196	00D8	D8	EC		LOLOOP	IN PORT2A	LOOK AT S2
197	00DA	E6	20			ANI 020H	TEST TO SEE IF MODCOMP HAS READ DATA
198	00DC	C2	D0	00		JNZ L0LOOP	STAY IN LO LOOP UNTIL S2 (2AS) IS LO
199	00DF	03				INX B	INCREMENT BC RAM ADDR COUNTER
200	00E0	7B				MOV A,E	TEST TO SEE IF BC.GT.DE
201	00E1	91				SUB C	SUBTRACT BC FROM DE,GET A BORROW WHEN
202	00E2	7A				MOV A,D	BC.GT.DE(CARRY IS SET)
203	00E3	98				SBB B	
204	00E4	C9				RET	
205					:		
206					:	STBMHI	STROBE REC HI,HANG UNTIL S2 FOLLOWS
207					:		
208	00E5	3E	10		STBMHI	MVI A,10H	STROBE REC LINE HI
209	00E7	D3	EE			OUT PORT2C	
210	00E9	D8	EC		HILOOP	IN PORT2A	LOOK AT S2
211	00EB	E6	20			ANI 020H	TEST TO SEE IF MODCOMP HAS READ DATA
212	00ED	CA	E9	00		JZ HILOOP	STAY IN HI LOOP UNTIL S2 (2AS) IS HI
213	00F0	03				INX B	INCREMENT BC RAM ADDR COUNTER
214	00F1	7B				MOV A,E	TEST TO SEE IF BC.GT.DE
215	00F2	91				SUB C	SUBTRACT BC FROM DE,GET A BORROW WHEN
216	00F3	7A				MOV A,D	BC.GT.DE(CARRY IS SET)

```

217 00F4 00          END D
218 00F5 00          NET
219
220 00F6          END

```

```
ASSEMBLER ERRORS = 0
```

SYMBOL TABLE

A	0007	ADBUS	00A0	ADRDR	000E	APDATA	007E
B	0000	C	0001	CHLOP	0077	CHSD	E 0000
CHSDA	E 0001	CHSF	E 0000	CHSPR	E 0003	CHSC	E 0004
CHSSA	E 0005	CO	E 0000	COPT	E 0000	CS	E 0000
COSA	E 0007	CROUT	E 0007	D	0002	DADD	E 0000
DADDA	E 0009	DADDD	E 000A	DDIV	E 0000	DDIVA	E 0000
DDIVB	E 000D	DECD	E 000E	DELIV	0000	DHDL	E 000F
DMULA	E 0010	DMULD	E 0011	DRUU	E 0012	DRUR	E 0013
DMUUB	E 0014	DSUB	E 0015	DSUBR	E 0016	DSUBD	E 0017
E	0003	ECHO	E 0002	EMPT	E 000C	ENP	E 0018
EXP10	E 001A	EXPA	E 0019	FRDD	E 001B	FADDA	E 001C
FADDB	E 001D	FDIV	E 001E	FRIM	E 001F	FDIVB	E 0020
FIXD	E 0021	FIXDR	E 0022	FIXS	E 0023	FIMDR	E 0024
FLTD	E 0025	FLTDR	E 0026	FLYS	E 0027	FLTDR	E 0028
FMUL	E 0029	FMULA	E 002A	FMULD	E 002D	FRINT	E 002D
FSUB	E 002C	FSUBR	E 002D	FSUBD	E 002E	GETCH	E 0033
GETCM	E 0032	GETHX	E 0034	GETRI	E 003F	H	0004
HILoop	00E9	L	0000	LI	E 002F	LNA	E 0030
LOG	E 0031	LOGR	E 0030	LOLOOP	0000	LOSP1	0014
LOPSM	00D2	N	0006	LRAD	E 0033	LRDRY	N 0000
NCHA	0000	HMOUT	E 0001	NRDR	0001	OLDR	0028
POPD	E 0034	POPS	E 0030	PORT1	0007	PORT1B	00F4
PORT1B	00F5	PORT1C	00F0	PORT2	000F	PORT2B	00EC
PORT2B	00ED	PORT2C	00EE	PORT3	000F	PORT3B	000C
PORT3B	00DD	PORT3C	00DE	PRINT	E 0036	PRINTB	E 003B
PRT11	0099	PRT10	0000	PRTSB	0000	PSU	0000
PTOD	E 003C	PTGS	E 0007	PEPI	E 0006	PSR	E 003D
PWSA	E 003A	PURD	E 0030	RADAR	0010	RADLP	0000
ROUND1	0041	SADD	E 0030	SADR	E 0030	SADD	E 003E
SDIV	E 003F	SDIVA	E 0042	SDIVB	E 0043	SDV	E 0042
SINA	E 0043	SNDRY	0073	SDRYP	007C	SIAL	E 0044
SNJLA	E 0045	SNJLB	E 0047	SDRY	E 0047	SDRVA	E 0045
SMUUB	E 0049	SP	0000	SDRYT	E 0049	SDRTA	E 004C
SSUB	E 004C	SSUBR	E 004D	SDRDL	E 004E	SDRCK	S 0000
STUMHI	00E0	STLRD	0000	TDI	E 004F	TDI	E 0050
TUS2	E 0051	TOS4	E 0000	ULJLD	0000	UNJLD	0000
URT2	E 0053	URTA	E 0000	ULJL	E 0000	URD	E 0050
ZERO	E 005E						

Appendix C
PROGRAM BIGFIT

The program BIGFIT performs a mathematical (least squares) fit to the data set obtained with the program BIGRDG. The program also calculates the fit error, a measure of how well the fit matches the data and vice-versa, and the drift error, an estimation of how small variations in eddy-current signal will affect the property determination. The operator selects the type of mathematical fit to be performed and the program calculates the coefficients for that fit. On operator command, the coefficients are stored in a designated memory location. The coefficients are later programmed into a PROM chip for use in the multifrequency eddy-current (MFEC) instrument's microcomputer. A brief summary of the program follows.

<u>Lines</u>	<u>Actions</u>
1-27	Information and definition of parameters.
28-61	Assign dimensions.
62-74	Define data files.
75-79	Assign data values.
80-87	Determine time and date.
88-108	Read test equipment, property, and calibration data recorded by BIGRDG program.
109-114	Print time and date.
115-118	Read eddy-current coil properties from the appropriate file.
119-172	Operator selects (via computer prompts) the property to be fitted and the type of mathematical fit to be performed.
173-183	Read the eddy-current data (magnitude and phase) recorded by BIGRDG.
184-211	The properties to be fitted and the data points used in the fitting process are selected and/or modified by the statements in this section of the program. Then a least-squares fit of the eddy-current readings to the selected properties is made by the subroutine "ALSQS."

<u>Lines</u>	<u>Actions</u>
212-243	The properties to be fit and the data points used in the fitting process are selected and/or modified by the statements in this section (similar to lines 184-211), and the fit error and maximum drifts are calculated.
244-260	The polynomial for the mathematical fit is calculated.
261-302	On command, the entire fit is printed out.
303-323	On command, the coefficients and other information are written on the designated data file.
324-333	Properties are calculated from the eddy-current readings (magnitude and phase) and displayed on the video terminal.
334-356	The eddy-current readings (magnitude and phase) are expanded (via the polynomial) into property readings.
357-375	New readings can be made from the eddy-current instrument to check the mathematical fit obtained.
376-406	This section provides a means to stop the program action by operating a foot switch.
407-432	Test equipment and property data (recorded by BIGRDG) are printed out on the logical output unit (LOU).
433-448	Calibration data (recorded by BIGRDG) are printed out on the LOU.
449-464	The actual eddy-current readings (recorded by BIGRDG) and properties are printed out on the LOU.

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1      PROGRAM BIGFIT
2      C      (20 JUNE 1982)
3      C      PROGRAM TO PERFORM A LEAST SQUARES FIT TO DATA READ INTO A DISK
4      C      FILE BY BIGRDG PROGRAM AND THEN PERFORM CONTINUOUS BACK CALCULATIONS
5      C      USING INSTRUMENT READINGS THAT ARE MADE BETWEEN EACH DISPLAYED SET.
6      C
7      C      IRDPRM=MAXIMUM NUMBER OF COEFFICIENTS IN EXPANSION
8      C      LITEK=LOGICAL INPUT UNIT (1=TTY)
9      C      LOTEK=LSI OUTPUT UNIT FOR PROMPTING AND DISPLAY
10     C      LOU=LOGICAL OUTPUT UNIT FOR PERMANENT RECORD
11     C      NCHS=NUMBER OF DATA CHANNELS
12     C      NCOED=FILE VARIABLE FOR MIC-COMP DATA=1ST CALO DATA BYTE HEX OR DEC
13     C      NFILIM=FILE LIMIT ON LINES IN FILE 37, THE DATA FILE
14     C      NF=FREQUENCY INDEX
15     C      NPT=NUMBER OF FREQUENCIES
16     C      LNF=2*NPT
17     C      NP=PROPERTY INDEX
18     C      NPROPM=MAXIMUM NUMBER OF PROPERTIES CALCULATED(=6 NOW)
19     C      NPT=TOTAL NUMBER OF SETS OF PROPERTY VALUES FOR A COMPLETE
20     C      SET OF READINGS=NO SAMPLES+NO. DEFECTS
21     C      NPTT=VALUE OF NPT READ FROM FILE 30
22     C      NPHCAL=NUMBER OF PHASE CALIBRATIONS
23     C      NMGCAL=NUMBER OF MAGNITUDE CALIBRATIONS
24     C      NCAL=NPHCAL*NMGCAL=TOTAL NUMBER OF CALIBRATION READINGS
25     C      NPRINT=PRINT AND TRANSFER INDEX.
26     C      NSTOP=INDEX TO STOP THE INSTRUMENT READINGS
27     C      MAG=INDEX TO TURN ON THE SATURATING MAGNET(=0 IF NONE USED)
28     C
29     REAL L2,L4,L3,L5,L6
30     REAL*6 NPROBE,NCABLE, INSTNO,POWDC,PICKAM,PHADET,COIL
31     REAL*0 TITLE(3)
32     C      DIMENSIONS THAT ARE NOT CHANGED:
33     C      DIMENSION ITIM(3),IDAY(3),NCONV(4)
34     C      DIMENSION VOLTS(12),VOLSTD(6),OFFSET(6),CGAIN(6),STDV(6)
35     C
36     C      DIMENSIONS THAT ARE CHANGED:
37     C      ** DIMENSION READNG(NPT+1,IRDPRM+1),PRO(NPT),POLARY(IRDPRM+1,5)
38     C      DIMENSION PROP(1,NPROPM),TMDFT(NPT),PHDFT(NPT),JPOL(6,NPT,NPROPM)
39     C      DIMENSION COE(IRDPRM),COEF(IRDPRM,NPROPM)
40     C      DIMENSION RDG1(1,IRDPRM),,NPOL(6,NPT)
41     C      DIMENSION JOFSET(NPROPM),JRDPR(NPROPM)
42     C      DIMENSION PROPTY(NPROPM),PRONAM(NPROPM),FREQ(NPT),GAIN(NPT)
43     C      DIMENSION TMAG1(1,NPT),PHASE1(1,NPT)
44     C      DIMENSION PICKAM(NPT),PHADET(NPT),PHASW(NPT)
45     C      DIMENSION SUMCAL(NCHS,NCAL),SDVCAL(NCHS,NCAL)
46     C      DIMENSION RDGC(NCHS,NCAL),RDGB(NCHS,NCAL)
47     C      DIMENSION TOFSET(NCHS),TSLOPE(NCHS)
48     C
49     C      THE APPROPRIATE NUMBERS SHOULD BE INSERTED IN THE FOLLOWING
50     C      DIMENSION STATEMENTS; COMMENTED STATEMENTS MARKED ** MANDATORY
51     C
52     DIMENSION READNG(325,16),PRO(324),POLARY(16,5),PROP(1,6)
53     DIMENSION TMDFT(3),PHDFT(3),JPOL(6,3,6),COE(15),COEF(15,6)
54     DIMENSION RDG1(1,15),NPOL(6,3),JOFSET(6),JRDPR(6)
55     DIMENSION PROPTY(6),PRONAM(6),FREQ(4),GAIN(4)
56     DIMENSION TMAG1(1,3),PHASE1(1,3)
57     DIMENSION PICKAM(3),PHADET(3),PHASW(3)
58     DIMENSION RDGC(6,4),RDGB(6,4)

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59 C   DIMENSION TOPSET(6),TCLOPE(6)
60 C
61 C   COMMON/03/COIL,RDAR,R1,R2,KL,EL,RLIM,R6,R7,THDR,THPU,ZLDR,ZLPU,X
62 C
63 C   FILE 29 CONTAINS THE COIL DATA.
64 C   DEFINE FILE 29(00,32,U,NO01L)
65 C
66 C   FILE 37 CONTAINS THE EXPERIMENTAL MEASUREMENTS MADE USING TUBRDG
67 C   DEFINE FILE 37(1500,40,U,IRED)
68 C
69 C   FILE 21 WILL CONTAIN THE COEFFICIENTS OF THE FITS.
70 C   DEFINE FILE 21(30,100,U,ICDEF)
71 C
72 C   FILE 31 WILL STORE THE COEFFICIENT DATA FOR THE MICROCOMPUTER.
73 C   DEFINE FILE 31(0192,4,U,ICOED)
74 C
75 C   DATA THAT MAY NEED TO BE CHANGED:
76 C   DATA NPT/324/,NPRINT/0/,LOU/0/,LITEK/1/,LOTEK/5/,NFILIM/1500/
77 C   DATA IRDPKH/15/,IR/1/,NCHS/0/,ITINS/32/,NPROPM/1/,NPROPT/1/
78 C   DATA STOP/'STOP'/,BLANKS/'  '/,MWHIT/1/,ICOED/2100/,ICDEF/1/
79 C
80 C   DATA OFFSET/6*0.0/,CCAIN/6*1./
81 C   INLINE
82 C   LDI,3          #0057          RESET,S1 LO,INTERUPT,S2 HI,0101/0111
83 C   ODD,3,C          OUTPUT TO PORTC
84 C   FINI
85 C   CALL TIMECK(LOU,'BIGFIT')
86 C   FIND (37'IRED)
87 C   NCOED=NCOED+1
88 C
89 C   NCOED INCREMENTED(PROH ADDRESSES START AT 0,TUBFIT ADDRS AT 1)
90 C   READ INFORMATION IN DIRECT ACCESS FILE #37 ON DISK
91 C
92 C   IRED=1
93 C   READ(37'IRED) TITLE, IDAY, ITIH
94 C   READ(37'IRED) NPROBE,MSER,R0,CAPDR,R9,CAPPU,NCABLE,
95 C   ::          CCABLE,INSTHO,PCWOSC
96 C   READ(37'IRED) NPT,NPTT,NPROPM1,NPHCAL,NMOCAL
97 C   READ(37'IRED) ((FREQ(NF)),PICKAM(NF),PHADET(NF),PHASW(NF)),
98 C   *NF=1,NFT)
99 C   READ(37'IRED) (PROHAM(NPR)),NPR=1,NPROPN)
100 C   NCAL=NPHCAL*NMOCAL
101 C   LNF=2*NFT
102 C   DO 100 NF=1,LNF
103 C   READ(37'IRED) (RDGB(NF,NC)),NC=1,NCAL)
104 C   100 CONTINUE
105 C   READ NOMINAL STANDARD VOLTAGES
106 C
107 C   READ(37'IRED) (VOLSTD(NF)),NF=1,LNF)
108 C
109 C   THE DATE AND TIME ARE PRINTED
110 C
111 C   WRITE (LOU,140) IDAY, ITIH
112 C   140 FORMAT (' CALIBRATION DATA TAKEN ', 2(12,1H/), 12,
113 C   1 ' TIME ', 2(12,1H/), 12,/)
114 C
115 C   COIL DATA IS READ FROM FILE
116 C

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117 CALL CIRCOL(LITEK,LOTEK,NPROBE)
118 GO TO 630
119 C
120 C LEAST SQUARES DESIGN SECTION.
121 C
122 C SELECT PROPERTY TO BE FITTED AND SET UP PROPERTY ARRAY.
123 C
124 300 MSET=NPT
125 MSET1=MSET+1
126 IF(NPROPT.GT.NPROPM) GO TO 860
127 310 WRITE(LOTEK,320)(NPR,PRONAM(NPR),NPR=1,NPROPM)
128 320 FORMAT(' SELECT NUMBER OF THE PROPERTY TO BE FITTED:',
129 *'/,6(I3,1X,A4),' ? ')
130 READ(LITEK,*)NPROP
131 IF(NPROP.GT.NPROPM)NPROP=NPROPM
132 350 WRITE(LOTEK,360)
133 360 FORMAT(' TYPE 1 IF THERE IS OFFSET; 0 IF NO OFFSET:',/)
134 READ(LITEK,*) JOFSET(NPROPT)
135 IOFSET=JOFSET(NPROPT)
136 IRDPR=IOFSET
137 370 WRITE(LOTEK,380)
138 380 FORMAT(' SELECT THE NUMBER OF THE FUNCTION TYPE, POLYNOMIAL',
139 *' DEGREE, & * OF '/,
140 *' CROSS TERMS FOR EACH MAGNITUDE & PHASE')
141 WRITE(LOTEK,390)
142 390 FORMAT(' FUNCTION TYPE:1=LINEAR 2=LOG 3=EXP 4=INV ')
143 400 WRITE(LOTEK,160)
144 160 FORMAT(1X)
145 WRITE(LOTEK,410)
146 410 FORMAT(25X,'FCTN POL * CROSS'/,25X'TYPE DEG TERMS')
147 DO 450 NF=1,NFT
148 DO 440 NC=1,2
149 NCC=NC*3
150 NCP=NCC-1
151 NCF=NCP-1
152 IF(NC.EQ.1) WRITE(LOTEK,420) FREQ(NF)
153 IF(NC.EQ.2) WRITE(LOTEK,430) FREQ(NF)
154 420 FORMAT(' MAG AT ',1PE12.6,' HZ ')
155 430 FORMAT(' PHA AT ',1PE12.6,' HZ ')
156 READ(LITEK,*)
157 *JPOL(NCF,NF,NPROPT),JPOL(NCP,NF,NPROPT),JPOL(NCC,NF,NPROPT)
158 C JPOL(3,NF,NPROPT)=0
159 IRDPR=IRDPR+JPOL(NCP,NF,NPROPT)+JPOL(NCC,NF,NPROPT)
160 JRDPR(NPROPT)=IRDPR
161 NPOL(NCF,NF)=JPOL(NCF,NF,NPROPT)
162 NPOL(NCP,NF)=JPOL(NCP,NF,NPROPT)
163 NPOL(NCC,NF)=JPOL(NCC,NF,NPROPT)
164 440 CONTINUE
165 450 CONTINUE
166 IRDPR1=IRDPR+1
167 IF(IRDPRM.LT.JRDPR(NPROPT))WRITE(LOTEK,460)
168 IF(IRDPRM.LT.JRDPR(NPROPT))GO TO 630
169 460 FORMAT(' ERROR: * OF TERMS IN POLARY EXCEEDS DIMENSION')
170 JROW=IRDPRM+1
171 CALL POLTYP(POLARY,JROW,IRDPR,NPOL,G,NFT,2,IOFSET,LOTEK)
172 C
173 C EXPAND THE RAW READINGS INTO IRDPR READINGS.
174 C

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175      470 DO 400 NF=1,NFT
176          TMDFT(NF)=0.
177          PHDFT(NF)=0.
178      490 CONTINUE
179          IREC=7+LNF
180          NR=1
181          DO 450 NP=1,NPTT
182          READ(37+IREC)((TMAG1(1,NF),PHASE1(1,NF),NF=1,NFT),(PROP(1,
183      *NPR),NPR=1,NPROPM))
184      C
185      C      THE PROPERTIES CAN BE SET AND MODIFIED IN THIS SECTION
186      C
187      C      PROP(1,4)=PROP(1,4)-PROP(1,2)
188      C      PROP(1,1)=PROP(1,1)-PROP(1,2)
189      C      PROP(1,2)=PROP(1,2)-RLIMARDAR
190      C
191      C      IF THIS PROPERTY IS NOT TO BE USED TRANSFER TO 490
192      C
193          IF (PROP(1,6).GT.0.11.OR.PROP(1,6).LT.-0.11)GO TO 490
194      C      IF (PROP(1,2).GT.0.001.AND.PROP(1,3).LT.0.020)GO TO 490
195      C      IF (PROP(1,6).LT.-0.000)GO TO 490
196      C      IF (PROP(1,6).GT.-0.040)GO TO 490
197      C      IF (ABS(PROP(1,6)+1.000).GT.0.0001)GO TO 490
198      C      IF (PROP(1,3).EQ.0.0)GO TO 490
199      C      IF (ABS(PROP(1,6)).GT.0.155)GO TO 490
200          CALL RDGEXP(RDG1, TMAG1, PHASE1, NPOL, IOFSET, TMDFT, PHDFT,
201      *1, IRDPR1, 1, NFT, 1, 1, 1, 1)
202          PRO(NR)=PROP(1,NPROP)
203          DO 405 IRD=1, IRDPR1
204          READNG(NR, IRD)=RDG1(1, IRD)
205      485 CONTINUE
206          NR=NR+1
207      490 CONTINUE
208      C
209      C      DO THE LEAST SQUARES FIT OF THE READINGS TO THE PROPERTIES.
210      C
211          CALL ALSQS(READING, PRO, COE, RSOS, MSET, IRDPR, MSET1)
212      C
213      C      CALCULATE THE DIFFERENCES IN THE FIT AND THE MAXIMUM DRIFTS.
214      C
215      500 SSDRIF=0.
216          SSDIFF=0.
217          IF (NPRINT.EQ.2)WRITE (LOTOK, 510)PRONAM(NPROP)
218          IF (NPRINT.EQ.2)WRITE (LOU, 510)PRONAM(NPROP)
219      510 FORMAT(2X,A4,7X,' CAL ',10X,'DIFF',6X,'DRIFT')
220          IREC=7+LNF
221          NR=1
222          DO 570 NP=1,NPTT
223          DRIFT=0.
224          READ(37+IREC)((TMAG1(1,NF),PHASE1(1,NF),NF=1,NFT),(PROP(1,
225      *NPR),NPR=1,NPROPM))
226      C
227      C      TRANSFER TO 570 IF PROPERTY IS NOT THE ONE WE WANT
228      C
229          IF (PROP(1,6).GT.0.11.OR.PROP(1,6).LT.-0.11)GO TO 570
230      C      IF (PROP(1,2).GT.0.001.AND.PROP(1,3).LT.0.020)GO TO 570
231      C      IF (PROP(1,6).LT.-0.000)GO TO 570
232      C      IF (PROP(1,6).GT.-0.040)GO TO 570

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233 C      IF(ABS(PROP(1,6)+1.000).GT.0.0001)GO TO 570
234 C      IF(PROP(1,6).NE.0.5)GO TO 570
235 C      IF(PROP(1,3).EQ.0.0)GO TO 570
236 C      IF(ABS(PROP(1,6)).GT.0.155)GO TO 570
237      DO 540 NF=1,NFT
238      DO 530 NC=1,2
239 C
240 C      ONE MAGNITUDE OR PHASE DRIFT IS SET ON AT A TIME.
241 C
242      IF(NC.EQ.1)TMDFT(NF)=.0001*TMAG1(1,NF)
243      IF(NC.EQ.2)PHDFT(NF)=.001
244      CALL RDGEXP(RDG1, TMAG1, PHASE1, NPOL, IOFSET, TMDFT, PHDFT,
245      *1, IRDPR1, 1, NFT, 1, 1, 1, 1)
246 C
247 C      THE POLYNOMIAL IS CALCULATED
248 C
249      SUM=0.
250      DO 520 IR=1, IRDPR
251      SUM=SUM+COE(IR)*RDG1(1, IR)
252 520 CONTINUE
253      DRIFT=DRIFT+ABS(READNG(NR, IRDPR1)-SUM)
254      TMDFT(NF)=0.
255      PHDFT(NF)=0.
256 530 CONTINUE
257 540 CONTINUE
258      DIFF=PRO(NR)-READNG(NR, IRDPR1)
259      SSDIFF=SSDIFF+DIFF*DIFF
260      SSDRIF=SSDRIF+DRIFT*DRIFT
261      IF(NPRINT.NE.2)GO TO 565
262 C
263 C      THE ENTIRE FIT IS PRINTED OUT
264 C
265      WRITE(LOU, 560)NR, PRO(NR), READNG(NR, IRDPR1), DIFF, DRIFT
266      WRITE(LOTEK, 560)NR, PRO(NR), READNG(NR, IRDPR1), DIFF, DRIFT
267 560 FORMAT(1X, I3, 4F12.5)
268      NR=NR+1
269 570 CONTINUE
270      SDRIF=SQRT(SSDRIF/FLOAT(MSET))
271      SDIFF=SQRT(SSDIFF/FLOAT(MSET))
272      WRITE(LOU, 580)PRONAM(NPROP), SDIFF, SDRIF
273      WRITE(LOTEK, 580)PRONAM(NPROP), SDIFF, SDRIF
274 580 FORMAT(' RMS DIFF IN ', A4, ' = ', F10.5, 'X', ' DRIFT = ', F10.5)
275 590 IF (NPRINT.NE.3)GO TO 630
276      IF(NPROPT.NE.1)GO TO 597
277      DO 595 NC=1,NCAL
278      WRITE(21' ICDEF) (RDG0(JJ,NC), JJ=1, LNF)
279      DO 595 NF=1, LNF
280      CALL CONVR9(RDG0(NF,NC), 1, NCONV)
281      DO 595 II=1,4
282      WRITE(31' NCOED)NCONV(II)
283 595 CONTINUE
284      WRITE(21' ICDEF) (VOLSTD(NF), NF=1, LNF)
285      DO 596 NF=1, LNF
286      CALL CONVR9(VOLSTD(NF), 1, NCONV)
287      DO 596 II=1,4
288      WRITE(31' NCOED)NCONV(II)
289 596 CONTINUE
290 597 WRITE(LOU, 160)

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291      WRITE(LOTEK,100)
292      NCOED1=NCOED+4*IRDPRI+1
293      WRITE(31*NCOED) IRDPRI
294      DO 610 I=1,IRDPRI
295      CALL CONVRT(COE(I),1,ICCONV)
296      C      WRITE(LOU,088) I,COE(I),(ICCONV(I),I=1,4),(POLARY(I,J),J=1,5)
297      WRITE(LOTEK,088) I,COE(I),(ICCONV(I),I=1,4),(POLARY(I,J),J=1,5)
298      600  FORMAT(' COEF(',I2,')=(',1PE10.7,4X,4D2,1X),1X,5A4)
299      COEF(I,NPROPT)=COE(I)
300      DO 610 NCO=1,4
301      WRITE(31*NCOED)NCONV(NCO)
302      610  CONTINUE
303      NCOED=NCOED1
304      C
305      C      THE COEFFICIENT,OFFSET,NPOL AND IRDPRI ARE WRITTEN ON THE RAD DISC
306      C      FILE #21.
307      C
308      WRITE(21*ICDEF)PRONAM(NPROPT),IRDPRI,JOFFSET(NPROPT)
309      WRITE(21*ICDEF)(COEF(IR,NPROPT),IR=1,IRDPRI)
310      DO 620 NF=1,NFT
311      WRITE(21*ICDEF)(NPOL(I,NF),I=1,6)
312      620  CONTINUE
313      WRITE(21*ICDEF)STOP,NFT,NFT
314      PROPT(NPROPT)=PRONAM(NPROPT)
315      ICDEF=ICDEF-1
316      NPROPT=NPROPT+1
317      C
318      630  WRITE(LOTEK,640)
319      640  FORMAT(' 1 FIT PROP 2 PRT ENTIRE FIT 3 PRT/SV COEF 4 CHG FCTH/POL'
320      *, ' TYP 5 RUN TEST',/ )
321      READ(LOTEK,#)NPRINT
322      GO TO(300,500,090,350,650),NPRINT
323      650  NPROPT=NPROPT-1
324      WRITE(LOU,100)
325      GO TO 080
326      C      CALCULATES PROPERTIES FROM MAGNITUDES AND PHASES AND CONTINUOUSLY
327      C      DISPLAYS THE VALUES ON THE LSI TERMINAL.
328      C
329      700  CONTINUE
330      IF(NPRINT.EQ.2)WRITE(LOTEK,710)(PROPT(NPRO),NPRO=1,NPROPT)
331      710  FORMAT(1X,5(0X,A4,1X))
332      IF(NPRINT.EQ.3)WRITE(LOTEK,715)(I,I,I=1,NFT)
333      715  FORMAT(1X,3('  MAG',I1,')    PHA('',I1,')')
334      WRITE(LOTEK,100)
335      C
336      C      EXPANSION OF TMAG1(I,NF) AND PHAS1(I,NF) INTO READING(I,IRDPRI)
337      C
338      720  DO 800 NPRO=1,NPROPT
339      DO 700 NF=1,NFT
340      DO 700 I=1,6
341      NPOL(I,NF)=JPOL(I,NF,NPRO)
342      700  CONTINUE
343      TNDFT(NF)=0.
344      PHDFT(NF)=0.
345      790  CONTINUE
346      JOFFSET=JOFFSET(NPRO)
347      IRDPRI=IRDPRI(NPRO)
348      IRDPRI=IRDPRI+1

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349      CALL RDGEXP(RDG1, TMAG1, PHASE1, NPOL, IOFSET, TNDFT, PHDFT,
350      *1, IRDPRI, 1, NFT, 1, 1, 1, 1)
351      PRO(NPRO)=0.
352      DO 000 IR=1, IRDPR
353      PRO(NPRO)=PRO(NPRO)+COEF(IR, NPRO)*RDG1(1, IR)
354  000 CONTINUE
355      NSTART=1
356      IF(NPRINT.EQ.2)WRITE(LOTEK, 005) (PRO(NPRO), NPRO=1, NPROPT)
357  005 FORMAT(1H+, 6(F13.5))
358  C
359  C      NEW READINGS ARE MADE FROM THE EDDY CURRENT INSTRUMENT.
360  C
361  025 IF(MAG.EQ.1) CALL RDGMIC(VOLTS, NCHS, 12, 1, NSTOP, MAG, 0)
362      CALL RDGMIC(VOLTS, NCHS, ITMS, NRET, NSTOP, MAG, 0)
363      IF(MAG.EQ.1) CALL SATMAG(0)
364  C      VOLTS(0)=25.*VOLTS(7)/VOLTS(0)
365  C      DO 030 NC=1, NCHS
366  C      VOLTS(NC)=VOLTS(NC)+TOPSET(NC)+TSLOPE(NC)*VOLTS(0)
367  030 CONTINUE
368      IF(NPRINT.EQ.3)WRITE(LOTEK, 020) ((VOLTS(2*NK-1), VOLTS(2*NK))
369      *, NK=1, NFT)
370      CALL CORRDC(VOLTS, OFSET, CGAIN, NCHS)
371  040 DO 045 NK=1, NFT
372      TMAG1(1, NK)=VOLTS(2*NK-1)
373      PHASE1(1, NK)=VOLTS(2*NK)
374  045 CONTINUE
375  020 FORMAT(1H+, 6(F12.4))
376      IF(NSTOP.GT.0)GO TO 720
377  C
378  C      PROGRAM WILL STAY IN THIS LOOP UNTIL THE FOOT PEDAL IS PRESSED.
379  C
380      IF(NLADL+NPRINT.EQ.3)WRITE(LOU, 710) (NPRO, NPRO=1, NPROPT)
381      NLADL=NPRINT
382      IF(NPRINT.EQ.2)WRITE(LOU, 050) (PRO(NPRO), NPRO=1, NPROPT)
383  050 FORMAT(1H , 6(F12.5))
384      IF(NPRINT.EQ.3)WRITE(LOU, 050) ((VOLTS(2*NK-1), VOLTS(2*NK))
385      *, NK=1, NFT)
386      GO TO 000
387  055 WRITE(LOTEK, 057)
388  057 FORMAT(' LIMIT OF FILE 37 IS EXCEEDED. ')
389      GO TO 000
390  060 WRITE(LOTEK, 070)
391  070 FORMAT(' PROP ARRAY IS FILLED. ')
392      000 WRITE(LOTEK, 090)
393  090 FORMAT(' PRINT : 1.NEAS VOLT & PROPERTIES 2.CAL&DISPLAY PROPE'
394      *, '3.RAW RDGS.4.RE-CALIB 5.STOP', /)
395      INLINE
396      LDI, 3          *0067          INTERRUPT, S1 LO, RESET, S2 HI, 0110/0111
397      ODD, 3, 6          OUTPUT TO PORT36, INTERRUPT INITIATED)
398      FINI
399      READ(LITEK, *)NPRINT
400      INLINE
401      LDI, 3          *0077          S1 LO, RESET, INTERRUPT, S2 HI, 0111/0111
402      ODD, 3, 6          OUTPUT TO PORT36
403      FINI
404      GO TO (1300, 700, 700, 095, 900), NPRINT
405  095 CALL CALMIC(RDGC, NCHS, NSTOP)
406      CALL RESET(RDGC, RDGO, OFSET, CGAIN, STDV, NCHS)

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407      GO TO 880
408 C
409 C      PRINT SUMMARY OF DATA ON FILE 37
410 C
411 1300 WRITE(LOU,1350) NPROBE,USER
412 1350 FORMAT(' PROBE NO.:',A6,5X,' SERIAL NO.:',I5)
413      WRITE(LOU,1360) RD,CAPDR
414 1360 FORMAT(' DRIVER SERIES RESISTANCE:',F10.1,5X,' DRIVER SHUNT CAP.:',
415 *          E12.4)
416      WRITE(LOU,1370) RD,CAPPU
417 1370 FORMAT(' PICK-UP SHUNT RESISTANCE:',F10.1,5X,' PICK-UP SHUNT CAP.:',
418 *          ,E12.4)
419      WRITE(LOU,1380) NCABLE,CABLEL,OCABLE
420 1380 FORMAT(' CABLE I.D. NO.:',A6,5X,' LENGTH:',F10.1,5X,' CAP.:',
421 *          E12.4)
422      WRITE(LOU,1390) INSTNO
423 1390 FORMAT(' EDDY CURRENT INSTRUMENT NO.:',A6)
424      WRITE(LOU,1400) POWDSC
425 1400 FORMAT(' POWER OSC I.D.',A6)
426      WRITE(LOU,1410) (FREQ CNF),NF=1,NFTD
427 1410 FORMAT('10X,' FREQUENCY:',I10(1E12.4,5X))
428      WRITE(LOU,1420) (PICKUP NF),NF=1,NFTD
429 1420 FORMAT(' PICK-UP RNF I.D.:',I7,10(10,5X))
430      WRITE(LOU,1430) (PHASE NF),NF=1,NFTD
431 1430 FORMAT(' PHASE DETECTOR I.D.:',I4,10(10,5X))
432      WRITE(LOU,1440) (PHASW NF),NF=1,NFTD
433 1440 FORMAT(' 180 PHASE SWITCH:',B1,10(10,12))
434 C
435 C      PRINT CALIBRATION READINGS
436 C
437 1600 CONTINUE
438      WRITE(LOU,1650) NPHCAL,NPCAL
439 1650 FORMAT('10,' AVERAGES & STANDARD DEVIATIONS OF CALIBRATION
440 *          ' READINGS:',I5,' HAS',I5,' PHA')
441      WRITE(LOU,1660) (FREQ CNF),NF=1,NFTD
442 1660 FORMAT('3(10X,1E12.4)')
443      WRITE(LOU,1670) CNF,1E1,NF=1,NFTD
444 1670 FORMAT('5X,3(5X,' FREQ',I1,5X,' PHA',I3,10)')
445      DO 1700 NC=1,NCAL
446          WRITE(LOU,1680)
447          WRITE(LOU,1690) (CRDR CNF,NC),NF=1,LHF
448 1680 FORMAT('5X,6(F10.4)')
449 1700 CONTINUE
450 C
451 C      PRINT OUT READINGS AND PROPERTIES
452 C
453      WRITE(LOU,1750)
454      WRITE(LOU,1750) CNF,NF,NF=1,NFTD, (PRODR(CNPR),NPR=1,NPROPD)
455      IREC=7+4*NF
456 1750 FORMAT('1X,' POSIT',3(' HAS',I1,' PHA',I1),6(4X,14,1X))
457      DO 1800 NP=1,NPTT
458          READ(37,IREC) ((THG1(1,NF),PHASE1(1,NF),NF=1,NFTD), (PROP(1,
459 *NPR),NPR=1,NPROPD))
460          WRITE(LOU,1760) NP, ((THG1(1,NF),PHASE1(1,NF),NF=1,NFTD), (PROP(1,
461 *NPR),NPR=1,NPROPD))
462 1760 FORMAT('3X,1-,12(10.4)')
463 1800 CONTINUE
464      GO TO 880

```

465 900 STOP JOB
466 END
TOTAL RECORDS WRITTEN = 467/ 75
EXIT
\$AVR CI 4
\$END LIST

Appendix D

PROGRAM PLTRDG

The program PLTRDG is used to plot eddy-current data on a Versatec printer-plotter. Plots are made as the test sample is scanned and as data are recorded. Using prompts, the operator may select either the raw data or a calculated property to be plotted. The raw data consist of a magnitude and a phase value for each data point recorded at each frequency. For example, a raw data plot for a three-frequency test will consist of six curves. The calculated property scan uses the coefficients provided by the program BIGFIT to perform a mathematical fit to the raw data to determine the desired property. A calculated property scan usually consists of one curve for each property, but in special cases more than one property can be represented by a single curve; for example, sample thickness and defects. Calculated properties are usually examined one at a time, but, with a slight program modification, more than one property (or curve) can be displayed simultaneously. The prompts provided make running the program almost self-explanatory. It is necessary to execute options 1, 2, and 3 (raw readings, calculate properties, and recalibrate) in numerical order before making a plot.

The program provides the ability to control the scanning devices associated with the test. The operator can specify the start position and scan increment for each scanner used.

A section of the program provides a curve-smoothing capability by averaging successive calculated values. The operator may specify the number of successive data points to average. The number of points averaged should be as small as possible to minimize computer operating time.

The operator can specify the gain and offset value for each curve. The indication size and curve position (on the chart) can be controlled with these two parameters.

```

1      PROGRAM PLTRDG
2      C      21 JANURARY 1981
3      C
4      C      PROGRAM WILL PLOT RAW READINGS OR CALCULATED PROPERTIES
5      C      FROM READINGS MADE BY THE EDDY CURRENT INSTRUMENT ON THE
6      C      VERSATEC.THE CALCULATE PROPERTIES SECTION MUST BE SELECTED
7      C      BEFORE THE RECALIBRATE SECTION.
8      C
9      DIMENSION JPOL(6,3,6),IRDPR(6),JOFSET(6)
10     DIMENSION READING(16),NPOL(6,3),THACM(3),PHASE(3)
11     DIMENSION COEF(16,6),PROP(6),PRONAM(6)
12     DIMENSION XLIM(2),YRLIM(2),YPLIM(2),XARG(2)
13     DIMENSION VOLSTD(6),VOLTS(12),Y1(2),Y2(2),YVAL(2,12)
14     DIMENSION OFSET(6),GAIN(6),STDV(6)
15     DIMENSION RDGC(6,4),RDBB(6,4)
16     DIMENSION DELTA(3),XNEW(3)
17     DIMENSION NDACH(6),ROFSET(6),RGAIN(6),POFSET(6),PGAIN(6)
18     DIMENSION NPR(10)
19     DEFINE FILE 21(30,100,U,ICDEF)
20     DATA NTT/5/,NTT1/4/,NPR/10:*700/
21     DATA INTER/10/,ICDEF/1/,NPROPH/1/
22     DATA NCHS/6/,IFINS/1/,HRET/1/,NFT/3/
23     DATA LVP/17/,NAG/0/,LOU/6/,LITEK/1/,LOTEK/5/
24     C      VALUES OF OFFSET AND GAIN FOR READINGS
25     DATA ROFSET/-4.15,-1.60,-3.90,-0.00,-3.60,-0.55/,RGAIN/6*1000./
26     C      VALUES OF GAIN AND OFFSET FOR PROPERTIES
27     DATA POFSET/3*0.,2.0,2*0./,PGAIN/1.0E4,1.0E4,0.5E4,1.0E2,2*1./
28     C      VALUES OF GAIN AND OFFSET FOR CALIBRATIONS ARE SET
29     DATA DELTA/3*0.0/,XNEW/3*0.0/,OFSET/6*0.0/,GAIN/6*1.0/
30     DATA NCOUNT/5/
31     C      READINGS FROM A STANDARD TUBE ARE SET
32     C
33     C      SET ADDRESSES SO THAT INSTRUMENT IS READ
34     C
35     INLINE
36     LDI,3          @0057          RESET,S1 LO,INTERUPT,S2 HI,0101/0111
37     ODD,3,6       OUTPUT TO PORT36
38     FINI
39     5 WRITE(LOTEK,15)
40     WRITE(17,10)
41     10 FORMAT('1  ')
42     JSET=0
43     LCOUNT=0
44     15 FORMAT(' WHAT NEXT 1.RAW RDC 2.CAL PROPS 3.RECAL '
45     *, ' 4.SCAN/RAW 5.SCAN/CAL 6.RST 7.STOP? ')
46     INLINE
47     LDI,3          @0067          INTERUPT,S1 LO,RESET,S2 HI,0110/0111
48     ODD,3,6       OUTPUT TO PORT36
49     FINI
50     READ(1,*)NPRINT
51     INLINE
52     LDI,3          @0077          S1 LO,RESET,INTERUPT,S2 HI,0111/0111
53     ODD,3,6       OUTPUT TO PORT36
54     FINI
55     IF(NPRINT.EQ.4)WRITE(LOTEK,17)
56     IF(NPRINT.EQ.5)WRITE(LOTEK,17)
57     17 FORMAT(' TYPE XNEW(1),XNEW(2),DELTA(1),DELTA(2) FOR POSITIONER ')
58     IF(NPRINT.EQ.4)READ(1,*)XNEW(1),XNEW(2),DELTA(1),DELTA(2)

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59     IF (NPRINT.EQ.5) READ(1,*) XNEW(1), XNEW(2), DELTA(1), DELTA(2)
60     GO TO (20, 200, 300, 20, 200, 400, 500), NPRINT
61     20 CONTINUE
62     30 IF (MAG.EQ.1) CALL RDGMIC(VOLTS, NCHS, 12, NRET, NSTOP, 1, 0)
63     LNF=NFT*2
64     WRITE(LOTEK, 110) (NF, NF, NF=1, NFT)
65     WRITE(LOTEK, 120)
66     110 FORMAT('      ', 3('MAG(', 11, ')      PHA(', 11, ')      ')
67     120 FORMAT(1X)
68     130 IF (NPRINT.EQ.1) GO TO 140
69     XNEW(1)=XNEW(1)+DELTA(1)
70     IF (XNEW(1).LT.0.0) XNEW(1)=0.0
71     XNEW(2)=XNEW(2)+DELTA(2)
72     IF (XNEW(2).LT.0.0) XNEW(2)=0.0
73     CALL POSITION(XNEW, 2)
74     140 CALL RDGMIC(VOLTS, NCHS, ITIMS, NRET, NSTOP, MAG, 0)
75     CALL CORRDRG(VOLTS, OFFSET, GAIN, NCHS)
76     K=MOD(NCOUNT, INTER)
77     NCOUNT=NCOUNT+1
78     IF (K.EQ.0) WRITE(LOTEK, 150) (VOLTS(NF), NF=1, LNF)
79     150 FORMAT(1H+, 6(F11.5))
80     DO 60 NF=1, LNF
81     NDACH(NF)=RGAIN(NF)*(ROFSET(NF)+VOLTS(NF))
82     60 CONTINUE
83     CALL PLOTDA(NDACH, LNF, 0, LCOUNT)
84     IF (NSTOP.EQ.1) GO TO 130
85     CALL SATMAG(0)
86     CALL PLOTDA(NDACH, LNF, 1, LCOUNT)
87     IF (NPRINT.EQ.4) CALL TIMECK(17, '1750-1')
88     IF (NPRINT.EQ.4) WRITE(17, 150) (VOLTS(NF), NF=1, LNF)
89     DO 65 NF=1, LNF
90     VOLTS(NF)=VOLTS(NF)+ROFSET(NF)
91     65 CONTINUE
92     IF (NPRINT.EQ.4) WRITE(17, 150) (VOLTS(NF), NF=1, LNF)
93     IF (NPRINT.EQ.4) WRITE(17, 150) (ROFSET(NF), NF=1, LNF)
94     GO TO 5
95     C
96     C     PROPERTY CALCULATION AND DISPLAY SECTION
97     C
98     200 IF (ICOEFF.NE.1) GO TO 215
99     C
100    C     FILE 21 CONTAINS DATA FROM TUBFIT OR RFLFIT
101    C     LINE 1-4 CONTAINS THE INITIAL CALIBRATION DATA FROM TUBFIT
102    C     LINE 5 HAS THE PROPERTY NAME, PRONAM, THE * TERMS, IRDPR, ADD OFFSET
103    C     LINE 6 HAS IRDPR COEFFICIENTS
104    C     LINE 7 THROUGH 6 + NFT HAS JPOL(6, NFT, NPROM)
105    C     THE LAST LINE HAS 'STOP' 0,0
106    C
107    DO 205 NC=1, 4
108    READ(21*ICOEFF) (RDGO(NF, NC), NF=1, LNF)
109    205 CONTINUE
110    READ(21*ICOEFF) (VOLSTD(NF), NF=1, LNF)
111    210 READ(21*ICOEFF) PRONAM(NPROP), IRDPR(NPROP), JOFSET(NPROP)
112    IF (PRONAM(NPROP).EQ.'STOP') GO TO 214
113    IRDP=IRDPR(NPROP)
114    READ(21*ICOEFF) (COEF(IR, NPROP), IR=1, IRDP)
115    DO 213 NF=1, NFT
116    READ(21*ICOEFF) (JPOL(I, NF, NPROP), I=1, 6)

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117 213 CONTINUE
118     NPROPM=NPROPM+1
119     GO TO 210
120 214 CONTINUE
121     NPROPM=NPROPM-1
122 215 CONTINUE
123     WRITE (LOTEK, 217) (PRONAM(NPRO), I, FRO=1, NPROPM)
124 217 FORMAT(1X, ' TUB LOC ', 6(6X, A4, 1X))
125     WRITE (LOTEK, 120)
126 220 IF (NPRINT.EQ.2) GO TO 221
127     XNEW(1)=XNEW(1)+DELTA(1)
128     IF (XNEW(1).LT.0.0) XNEW(1)=0.0
129     XNEW(2)=XNEW(2)+DELTA(2)
130     IF (XNEW(2).LT.0.0) XNEW(2)=0.0
131     CALL POSITION(XNEW, 2)
132 221 CALL RDGMIC(VOLTS, NCHS, ITIMS, NRET, NSTOP, MAG, 8)
133     CALL CORRDC(VOLTS, OFFSET, GAIN, NCHS)
134     DO 260 NPRO=1, NPROPM
135         IRDPR1=IRDPR(NPRO)+1
136         IOFSET=IOFSET(NPRO)
137         DO 230 NF=1, NFT
138             PHASE(NF)=VOLTS(2*NFF)
139             TMAGM(NF)=VOLTS(2*NFF-1)
140             DO 225 I=1, 6
141                 NPOL(I, NF)=JPOL(I, NF, NPRO)
142 225 CONTINUE
143 230 CONTINUE
144     CALL RDEXP(READING, TMAGM, PHASE, NPOL, IOFSET, IRDPR1, NFT)
145     PROP(NPRO)=0.
146     IRDP=IRDPR(NPRO)
147     DO 240 IR=1, IRDP
148         PROP(NPRO)=PROP(NPRO)+READING(IR)*COEF(IR, FRO)
149 240 CONTINUE
150     NDACH(NPRO)=PGAIN(NPRO)*(POFSET(NPRO)+PROP(NPRO))
151 260 CONTINUE
152     IF (JSET.EQ.0) POFSET(3)=0.140-PROP(3)
153     JSET=1
154 C
155 C     SECTION TO SMOOTH THE DEFECT INDICATION BY AVERAGING SUCCESSIVE
156 C     DEFECT CALCULATIONS
157 C
158     DO 265 NT=1, NTT1
159         NPR(NT)=NPR(NT+1)
160 265 CONTINUE
161     NPR(NTT)=NDACH(3)
162     NDACH(3)=0
163     DO 167 NT=1, NTT
164         NDACH(3)=NDACH(3)+NPR(NT)
165 167 CONTINUE
166     NDACH(3)=NDACH(3)/NTT
167 C
168 C     END OF SECTION
169 C
170     K=MOD(NCOUNT, INTER)
171     NCOUNT=NCOUNT+1
172     IF (K.EQ.0) WRITE (LOTEK, 270) XNEW(1), (PROP(NPRO), NPRO=1, NPROPM)
173 270 FORMAT(1H+, F0.3, 6(F11.4))
174     CALL PLOTDR(NDACH, NPROPM, 0, LDCOUNT)

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175     IF(NSTOP.EQ.1)GO TO 220
176     CALL PLOTDA(NDACH,LMF,1,LCOUNT)
177     CALL TIMECK(17,'1758-1')
178     GO TO 5
179 300 CONTINUE
180     CALL CALMIC(RDGC,NCHS,NSTOP)
181     CALL RESET(RDGC,RDGO,OFFSET,GAIN,STDY,NCHS)
182     GO TO 5
183 400 CALL RDGMIC(VOLTS,NCHS,40,NRET,NSTOP,MAG,8)
184     DO 450 NOF=1,NCHS
185     OFFSET(NOF)=VOLSTD(NOF)-GAIN(NOF)*VOLTS(NOF)
186 450 CONTINUE
187     GO TO 5
188 500 CONTINUE
189     STOP JOB
190     END
191     SUBROUTINE PLOTDA(NDACH,NPLO,NRET,LCOUNT)
192 C
193 C     VERSION 2 0 79
194 C
195     INTEGER*2 ITEST,ILATT(64)
196     INTEGER*2 I(6),IAR(64,6)
197     DIMENSION NDACH(6)
198     DATA INTER/100/
199     DATA IAR/384**6/
200 C
201     DATA ILATT/28000,5*0,2800,5*0,280,5*0,28,5*0,28000,5*0,2800,5*0,
202 *280,5*0,28,5*0,28000,5*0,2800,5*0,280,0/
203     DO 50 NPL=1,NPLO
204     I(NPL)=1+NDACH(NPL)/16
205     IF(I(NPL).GT.64)I(NPL)=64
206     IF(I(NPL).LT.0)I(NPL)=0
207     IAR(I(NPL),NPL)=7*2**(15-MOD(NDACH(NPL),16))/2
208 50 CONTINUE
209     ITEST=MOD(LCOUNT,INTER)
210     INLINE
211     LDI,15     *8400     LOAD COMMAND WORD INTO REG 1
212     OCA,15,8     OUTPUT COMMAND WORD TO VERSATEC
213     LDI,1     0     SET COUNTER IN REG 1 TO 0
214     LDM,14     ITEST     LOAD VERTICAL LINE TEST IN REG 14
215 LOOP     ISA,3,0     INPUT STATUS INTO REG 3
216     TBRB,3,0     LOOP     TEST BIT 0 AND LOOP BACK IF HI
217     TRR,2,1     COPY OFFSET FROM REG1 TO REG2.
218     LDM,3,1     ILATT     LOAD LATTICE INTO REG3
219     XDM,3,2     IAR     EXCLUSIVE OR IAR(REG1,NPL)WITH REG3
220     ABR,2,9     ADD 64 TO REG2
221     XDM,3,2     IAR     EXCLUSIVE OR IAR(REG1,NPL)WITH REG3
222     ABR,2,9     ADD 64 TO REG2
223     XDM,3,2     IAR     EXCLUSIVE OR IAR(REG1,NPL)WITH REG3
224     ABR,2,9     ADD 64 TO REG2
225     XDM,3,2     IAR     EXCLUSIVE OR IAR(REG1,NPL)WITH REG3
226     ABR,2,9     ADD 64 TO REG2
227     XDM,3,2     IAR     EXCLUSIVE OR IAR(REG1,NPL)WITH REG3
228     ABR,2,9     ADD 64 TO REG2
229     XDM,3,2     IAR     EXCLUSIVE OR IAR(REG1,NPL)WITH REG3
230     ZBRB,14,0     SKIP     SKIP AROUND IF REG 14 NOT ZERO
231     TOR,3,3     TAKE ONE'S COMPLEMENT OF REG 3
232 SKIP     ODA,3,8     SEND DATA OUT TO THE VERSATEC

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233      ABR,1,15      INCREMENT COUNTER IN REG 1
234      ZBRB,1,9      LOOP      STAY IN LOOP UNTIL FINISHED
235      LDI,15      *4900      LOAD END OF BLOCK COMMAND
236      OCA,15,8      SEND TO VERSATEC
237      FINI
238      DO 60 NPL=1,NPLD
239      IAR(I(NPL),NPL)=0
240      60 CONTINUE
241      LCCOUNT=LCCOUNT+1
242      IF(NRET.EQ.0)GO TO 900
243      C
244      C      SECTION TO ADVANCE VERSATEC
245      C
246      INLINE
247      LOP1 ISA,2,0      INPUT STATUS INTO REG 2
248      TBRB,2,0      LOP1      TEST BIT 0 AND LOOP BACK IF HI
249      LDI,2      *8000      LOAD COMMAND WORD INTO REG 1
250      OCA,2,0      OUTPUT COMMAND WORD TO VERSATEC
251      LOP2 ISA,2,0      INPUT STATUS INTO REG 2
252      TBRB,2,0      LOP2      TEST BIT 0 AND LOOP BACK IF HI
253      LDI,2      *1810      LOAD LINE FEED INTO REG 1
254      ODA,2,8      OUTPUT WORD TO VERSATEC
255      LOP3 ISA,2,0      INPUT STATUS INTO REG 2
256      TBRB,2,0      LOP3      TEST BIT 0 AND LOOP BACK IF HI
257      LDI,2      *4400      LOAD TERMINATE COMMAND
258      OCA,2,0      SEND TO VERSATEC
259      FINI
260      900 RETURN
261      END
262      SUBROUTINE RDEXP(READNG, TMAG, PHASE, NPOL, IOPSET, IRDPR1, NFT)
263      DIMENSION READNG(IRDPR1),NPOL(6,NFT)
264      DIMENSION TMAG(NFT),PHASE(NFT)
265      C
266      C      NPOL CONTAINS A NUMBER FOR THE FUNCTION TYPE, THE POLYNOMIAL
267      C      DEGREE, AND THE NUMBER OF CROSS TERMS
268      C      FOR THE MAGNITUDE AND PHASE AT EACH FREQUENCY, STORED AS NPOL
269      C      (NF: 1-MAG FUN, 2-MAG POL, 3-MAG *CROSS TERMS, 4-PH FUN, 5-PH POL,
270      C      6-PH *CROSS TERMS). IF IOPSET=0, NO OFF-SET
271      C      WILL BE INCLUDED, =1 OFF-SET IS INCLUDED, IF
272      C      NPOL(NCP,NF) =0, THAT PARTICULAR MAGNITUDE AND PHASE FOR THAT
273      C      FREQUENCY WILL BE SKIPPED.
274      C
275      READNG(1)=1.
276      N=1
277      IF(IOPSET.EQ.1)N=2
278      DO 210 NF=1,NFT
279      DO 200 NC=1,2
280      NCC=NC*3
281      NCP=NCC-1
282      NCF=NCP-1
283      ROLD=RDG
284      IF(NPOL(NCP,NF).EQ.0) GO TO 200
285      IF(NC.EQ.1) RDG=TMAG(NF)
286      IF(NC.EQ.2) RDG=PHASE(NF)
287      C
288      C      THE TYPE OF FUNCTION IS SELECTED
289      C
290      IF(NPOL(NCF,NF).EQ.1)RDG=RDG

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291      IF(NPOL(NCF,NF).EQ.2)RDG=ALOG(RDG)
292      IF(NPOL(NCF,NF).EQ.3)RDG=EXP(RDG)
293      IF(NPOL(NCF,NF).EQ.4)RDG=1./RDG
294  C
295  C      THE TYPE OF POLYNOMIAL IS SELECTED
296  C      AND THE POLYNOMIAL VALUES ARE CONSTRUCTED.
297  C
298      READNG(N)=RDG
299      N=N+1
300      NDEG=NPOL(NCF,NF)-1
301      IF(NDEG.LT.1) GO TO 15
302      DO 10 I=1,NDEG
303      READNG(N)=RDG*READNG(N-1)
304      N=N+1
305  10 CONTINUE
306  C
307  C      CROSS TERMS ARE CONSTRUCTED
308  C
309  15  IF(NPOL(NCC,NF).EQ.0) GO TO 200
310      RDY=ROLD
311      NCTERM=NPOL(NCC,NF)
312      DO 20 I=1,NCTERM
313      RDY=ROLD*RDY
314  20 CONTINUE
315      IF(RDY.NE.0) RINV=RDG/ROLD
316      IF(RDY.EQ.0) RINV=0.
317      DO 30 I=1,NCTERM
318      RDY=RDY*RINV
319      READNG(N)=RDY
320      N=N+1
321  30 CONTINUE
322  C
323  200 CONTINUE
324  210 CONTINUE
325      RETURN
326      END
327      SUBROUTINE POSITION(XNEW,NAXIS)
328  C
329  C      DETERMINES THE NEW LOCATION FOR 4 DIFFERENT POSITIONERS AND FROM
330  C      THE OLD LOCATION,THE NUMBER OF STEPS NEEDED TO REACH THE NEW
331  C      LOCATION.THEN CALLS STEPER TO MOVE THE MOTORS TO THE NEW LOCATION
332  C
333      DIMENSION XOLD(3),XNEW(3),NSTEPS(3)
334      DATA XOLD/3*0.0/,STEPSZ/0.00025/
335      DO 20 IAXIS=1,NAXIS
336      NSTEPS(IAxis)=(0.5*STEPSZ*(XNEW(IAxis)-XOLD(IAxis)))/STEPSZ
337      XOLD(IAxis)=XOLD(IAxis)+FLOAT(NSTEPS(IAxis))*STEPSZ
338  20 CONTINUE
339      CALL STEPER(NSTEPS,XOLD,STEPSZ,NAXIS)
340      RETURN
341      END
342      SUBROUTINE STEPER(NSTEPS,XOLD,STEPSZ,NAXIS)
343  C
344  C      SEND PROPER NUMBER OF STEPS TO PROPER AXIS CONTROLLER
345  C
346      INTEGER*2 REG(8),NCOUNT
347      DIMENSION XOLD(3),NSTEPS(3)
348  1 DO 200 NAX=1,NAXIS

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349     IF (NSTEPS(MAX).EQ.0)GO TO 200
350     REG(1)=0
351     IF (NSTEPS(MAX).GE.0)GO TO 10
352     REG(1)=0
353     NSTEPS(MAX)=-NSTEPS(MAX)
354 10  CONTINUE
355     IF (NSTEPS(MAX).GE.65535)NSTEPS(MAX)=65535
356  C
357  C     SIGN SET IN REG(1);CONVERT NSTEP TO DCB IN REG(2)-REG(5)
358  C
359     DO 30 NRG=2,5
360     REG(NRG)=NSTEPS(MAX)/10000
361     NSTEPS(MAX)=(NSTEPS(MAX)-10000*REG(NRG))*10
362 30  CONTINUE
363  C     WRITE(5,40) (REG(I), I=1,5)
364 40  FORMAT(1X,5I2)
365  C
366  C     DATA FOR OUTPUT IN REG(NRG);OUTPUT TO APPROPRIATE CONTROLLER
367  C
368     NCOUNT=MAX-1
369     INLINE
370     LDI,1      0          ZERO REGISTER 1,USE AS INDEX,COUNTER
371     LDH,2      NCOUNT  LOAD THE CONTROLLER SELECT CHANL
372     LLS,2,4    LOGICAL LEFT SHIFT REG2,4 PLACES
373     ADH,2,1    REG       ADD SIGN TO REGISTER 2
374     NBL,2,2    SHIFT BYTE LEFT
375     ADI,2      @00FF    LEAVE CALIBRATE BITS ,COUNTER HI
376     ODD,2,3    OUTPUT REG 2 TO HD0AC PORT 33
377  LOP5  IDD,3,1    INPUT PORTS1 INTO REG5
378     TDRD,3,15  LOP5     STAY IN LOOP UNTIL BUSY GUES HI
379     LBRD,4,14  LOP5     BIT14 IN REG 4 HI,SPER TO LOP5
380  LOP1  IDD,4,1    INPUT PORT 31 TO REG 4
381  LOP6  ADR,1,15  INCREMENT REGISTER 1
382     LDH,2,1    REG       LOAD DCB VALUE INTO REG 2
383     NBL,2,2    SHIFT BYTE IN REG 2 TO LEFT
384     ADI,2      @00FF    TAKE INDEX BIT HI,LEAVE CALIBRATE HI
385  LOP2  IDD,3,1    INPUT PORT 31 INTO REG 3
386     TBRD,3,15  LOP4     JUMP TO ERROR LOOP IF NOT BUSY
387     XOR,3,4    ENCLUSIVE OR REG 3&4,RESULT IN 3
388     TOR,3,3    TAKE ONE'S COMPLEMENT OF REG 3
389     TDRD,3,14  LOP2     BIT 14=0 WHEN DATA STROBE SWITCHES
390     ODD,2,3    OUTPUT REG 2 TO HD0AC PORT 33
391     CRI,1      6        COMPARE REG 1 TO 6
392     BLNS,0     LOP1     BRANCH BACK IF REG 1.LT.6
393  LOP4  LDI,2      @00FF  LOAD ALL HI INTO 2
394     ODD,2,3    SEND ALL OUTPUTS HI
395  LOP3  IDD,3,1    INPUT PORT 31 TO REG 3
396     TOR,3,3    TAKE ONE'S COMPLEMENT OF REG 3
397     TBRD,3,15  LOP3     BRANCH BACK IF BUSY
398     FINI
399 200  CONTINUE
400  C
401  C     CHECK FOR POSITION FINISHED
402  C     HANG HERE UNTIL ALL POSITIONS ARE REACHED
403  C
404 300  CONTINUE
405     JSTEP=0
406     DO 400 NAX=1,NAXIS

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407      NCOUNT=MAX-1
408      INLINE
409      LDM,2      NCOUNT      LOAD THE COUNTER SELECT CHANL
410      LLS,2,6    LOGICAL LEFT SHIFT REG2,6 PLACES
411      ADI,2      #000F      LEAVE CALIBRATE BITS HI
412      ODD,2,3    OUTPUT REG 2 TO MODAC PORT 33
413      XOR,2,2    ZERO REG 2, IT WILL BE HI ORDER OF WRD
414      IDD,3,1    INPUT COUNT NO INTO REG 2,3
415      STMD,2     KSTEPS      STORE COUNT POSITION IN MEMORY
416      LDI,2      #00FF      SEND PROPER OUTPUTS HI
417      ODD,2,3    RESET PORT 33
418      FINI
419      JSTEPS=(XOLD(MAX)+.5*STEPSZ)/STEPSZ
420      350 NSTEPS(MAX)=JSTEPS -KSTEPS
421      IF(NSTEPS(MAX).LT.65535)GO TO 360
422      KSTEPS=KSTEPS+65536
423      GO TO 350
424      C      COUNTER ONLY GOES TO 65535, THEN STARTS BACK OVER AT 0
425      C      WRITE(5,390)MAX,JSTEPS,KSTEPS
426      360 JSTEP=JSTEP+NSTEPS(MAX)*NSTEPS(MAX)
427      390 FORMAT(1X,3I6)
428      400 CONTINUE
429      C      IF(JSTEP.NE.0)WRITE(5,410)
430      410 FORMAT(' TRANSLATOR ERROR ')
431      IF(JSTEP.GT.2)GO TO 1
432      420 CONTINUE
433      RETURN
434      END
TOTAL RECORDS WRITTEN = 435/ 66
EXIT
$AVR CI 4
$END LIST

```


Appendix E
PROGRAM SQRWLD

The program SQRWLD (written in assembly language) controls the entire inspection process of the seam weld in the steel sheath for the superconducting cable. The program controls the calibration of all instrumentation (including the magnetic tape recorder), and the recording of the calibration data. It provides prompts to the operator to remind him to perform the necessary steps in the correct order to perform the examination. The program controls the recording of raw data on magnetic tape and controls the calculated properties that are displayed on the strip-chart recorder as the test is conducted. It also allows the playback of the magnetic tape through the microcomputer in the transceiver unit to determine additional properties not determined during the on-line examination. The program provides operator prompts to control the calibration and operational procedure required to perform the manual inspection for weld repair.

The program performs the following functions, depending on the position of the switch on the computer module or the remote control box. A remote control box was used to select the test functions for this particular examination. The switches on the computer module in the multiple-frequency eddy-current instrument were used to select the correct PROM for the particular eddy-current probe being used.

<u>Switch position</u>	<u>Function</u>
0	Main running loop
1	Read tape
2	Read standard tube
3	Display raw readings
4	Display calculated readings
5	Perform and display calibrations
6	Inspect square conductors
7	Calibrate the digital-to-analog converters and recorder

Position 0 is used for the automated on-line examination of the superconductor cable (see Appendix F). In position 0, the microcomputer controls the fixed locations across the scan path where eddy-current readings are taken. (The readings are synchronized with the mechanical scanning system by a pulse generated from the crankshaft drive mechanism.) The program also maintains the various readings in separate data arrays. This allows the output data to be represented in the form of continuous scans at fixed axes on the weld and heat-affected zones.

Position 1 provides a means to read the magnetic tape back through the microcomputer in the transceiver unit. The operator can designate other parameters to be calculated from the raw data and displayed on the analog recorder (Appendix F).

Position 2 is used for calibration and calibration corrections (see Appendix F).

Position 3 provides a means to observe the raw phase and magnitude data on the video terminal during the initial setup. This position is used to check the phase detectors and the bandpass amplifiers in the multifrequency eddy-current instrument (see Appendix F).

Position 4 provides a means to observe calculated data on the video terminal. This function was not used for this examination.

In position 5, the video terminal displays signals that are generated by the calibrator module and fed through the bandpass amplifiers and phase detectors. This allows the operator a means to check the calibration of the multifrequency eddy-current instrument (see Appendix F).

Position 6 is used for the manual inspection of the superconductor cable (see Appendix G).

Position 7 is used to check the operation of the digital-to-analog converters and to check the calibration of the analog recorder (see Appendix F).

```

1          TITLE 'SORULD PROGRAM VERSION 10.26 APRIL 83'
2          NAME   SORULD
3          LIST   B,G,O,T
4          ;      MLIST   I,N,S,T
5          ORG 0000H          START PROGRAM IN SECOND PROM.
6          ; SYMBOL DEFINITIONS
7          ;
8          ; DEFINE PORT ADDRESSES
9          ;
10         PORT1      EQU 0F7H          PORT 1 CONTROL WORD ADDRESS
11         PORT1A     EQU 0F4H          PORT1A ADDRESS
12         PORT1B     EQU 0F5H          PORT1B ADDRESS
13         PORT1C     EQU 0F6H          PORT1C ADDRESS
14         PORT2      EQU 0E0H          PORT 2 CONTROL WORD ADDRESS
15         PORT2A     EQU 0E3H          PORT2A ADDRESS
16         PORT2B     EQU 0E4H          PORT2B ADDRESS
17         PORT2C     EQU 0E5H          PORT2C ADDRESS
18         PORT3      EQU 0D0H          PORT3 CONTROL WORD ADDRESS
19         PORT3A     EQU 0D3H          PORT3A ADDRESS
20         PORT3B     EQU 0D4H          PORT3B ADDRESS
21         PORT3C     EQU 0D5H          PORT3C ADDRESS
22         APDATA     EQU 07EH          ARITHMETIC PROCESSOR DATA PORT
23         APSTS      EQU 07FH          ARITHMETIC PROCESSOR CONTROL/STATUS ADDR
24         USCTS      EQU 0F8H          USART CONTROL/STATUS ADDRESS
25         ;
26         ; MATH SUBROUTINES FOR THE COMP 9 ARE STORED AS PUBLIC,ANY ROUTINE
27         ; CAN BE CALLED USING AN 'EXTRN' STATEMENT.
28         ;
29         ;EXTRN      ACOS,ASIN,ATAN,ATANH,BIDEC,BIDECF
30         ;EXTRN      CHSD,CHSDA,CHSF,CHSFA,CHSS,CHSSA,COS,COSA
31         ;EXTRN      DADD,DADDA,DADD,DDIV,DDIVA,DDIVB,DECHO
32         ;EXTRN      DMUL,DMULA,DMULB,DMUB,DMUA,DMUB,USUB,DSUBA,DSUBB
33         ;EXTRN      EXP,EXPA,EXP10,FADD,FADDA,FADD,FDIV,FDIVA,FDIVB
34         ;EXTRN      FIND,FINDA,FIND,FINDA,FLTD,FLTDA,FLTS,FLTSA
35         ;EXTRN      FMUL,FMULA,FMULB,FMUB,FSUBA,FOUBB,LN,LNA,LOG,LOGA
36         ;EXTRN      NADD,POPD,POPS,PTDD,PTDS,PUPI,PER,PURA,PURB
37         ;EXTRN      SADD,SADDA,SADD,SDIV,SDIVA,SDIVB,SH,SHA
38         ;EXTRN      SMUL,SMULA,SMULB,SMUB,SMUA,SMUB,SGRT,SGRTA
39         ;EXTRN      SSUB,SSUBA,SSUBB,TAN,TANA,TOS2,TOS4
40         ;EXTRN      WRT2,WRT4,XCHD,XCHS
41         ;EXTRN      CROUT,COPDT,GETCH,PRINT,PRINTF,EPNRT,FPNRT,ZERU
42         ;EXTRN
43         ;
44         ; PROM DATA ASSIGNMENTS
45         ; INITIAL CORRECTION FACTOR ASSIGNMENTS,4 BYTES EACH STARTING AT C9F0
46         ; AS OFFSET1,SLOP1,OPST2,SLOP2...STORED AS FLOATING BINARY;EX HI NO LD.
47         ; COEFFICIENT DATA,4 BYTES EACH STORED IN FLOATING BINARY AS EX,HI-LO.
48         ; STARTING AS C10,C11,C12...C1N;C20,C21,C22...C2N.THERE ARE UP TO 16
49         ; PER PROPERTY,SIX PROPERTIES,STARTING ADDRESS IS COEVT,THE NUMBER OF
50         ; COEFFICIENTS USED FOR EACH PROPERTY IS STORED BEFORE EACH SET.
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999        ;
1000       ;

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55 003D COE0F EQU 03DH COEFFICIENT OFFSET(15 COEF EA #4 BY +1)
56 0001 NRDC EQU 00H NRDC=2*#H=NUMBER OF RDGS PER CHANNEL=1
57 0066 NCHN EQU 06H NCHN=NUMBER OF CHANNELS TO BE READ
58 0004 NCHLC EQU 04H NCHLC=NUMBER OF CALIBRATION RDGS/CHANNEL
59 0002 PROP# EQU 02H PROP#-NUMBER OF PROPS TO BE CALCULATED
60 0000 PRT10 EQU 00H PRT10=CONTROL WORD FOR PORT1 OUTPUT MODE
61 0099 PRT11 EQU 09H PRT11=CONTROL WORD FOR PORT1 INPUT MODE
62 0093 PRT3 EQU 093H CONTROL WORD FOR A INPUT,
63 ; B INPUT (C C1-3 INPUT,C4-7 OUT)
64 000D CR EQU 0DH DEFINE CARRIAGE RETURN <CR>
65 000A LF EQU 0AH DEFINE LINE FEED <LF>
66 0009 POSCH# EQU 09H NUMBER OF POSITION CHANNELS+1
67 ;
68 ; RAM ADDRESS DEFINITIONS
69 ;
70 3C10 TRMCT EQU 03C10H SINGLE BYTE COUNT OF NUMBER OF TERMS
71 3C11 CHNO EQU 03C11H CALIBRATION CHANNEL NUMBER
72 3C12 DSPAD EQU 03C12H ADDRESS FOR THE FRONT PANEL DISPLAY,2 BYTES
73 3C14 FCAL# EQU 03C14H COUNTER FOR THE NUMBER OF PROPERTY CALCS.
74 3C15 FCAL1 EQU 03C15H NUMBER OF FIRST PROPERTY TO BE CALCULATED.
75 3C16 FCAL2 EQU 03C16H NUMBER OF 2ND PROPERTY TO BE CALCULATED.
76 3C17 FCAL3 EQU 03C17H NUMBER OF THIRD PROPERTY TO BE CALCULATED.
77 3C18 FCAL4 EQU 03C18H NUMBER OF FOURTH PROPERTY TO BE CALCULATED.
78 3C19 COUN# EQU 03C19H 3 BYTES,COUNT NUMBER FOR MEASUREMENTS
79 3C1B NRDG# EQU 03C1BH 1RDG RDGS,4 BYTES/CHNL,N#1,N#1,N#2,.. HI-LO
80 ; COUN#(LO) CORRECTED RDGS,4 BYTES EN;NRG1,PH1,NRG2;EX,HI-LO
81 3C35 CORFA EQU 03C35H CORR FACTOR,4BYTES EN,UP#1,SLOP1,UP#2,..
82 3C63 DRDGS EQU 03C63H PROP# WORDS 20Y EACH(LO)16 BIT FIXED DEC 0
83 3C79 RDGDA EQU 03C79H DRDGS*2+POSCH#2 4 BY DA(EX HI-LO),RDG11 RDG21..RDGC
84 ;,RDGDA=209 BYTES TOTAL (0120H).
85 3D99 CALRD EQU 03D99H CALIBRATION READINGS,960H,960 BYTES
86 3DF9 SURCX EQU 03DF9H 4 BYTES,SUM OF CALC(NCALC)*#2
87 3DFD SURC EQU 03DFDH 4 BYTES,SUM OF CALC(NCALC)
88 3E01 SURY EQU 03E01H 4 BYTES,SUM OF CALC(NCALC)*#2
89 3E05 SURY EQU 03E05H 4 BYTES,SUM OF CALC(NCALC)
90 3E09 SURZY EQU 03E09H 4 BYTES,SUM OF CALC(NCALC)*NCHLC(NCALC)
91 3E0D SURZ EQU 03E0DH 4 BYTES,SUM OF CALC(NCALC)*NCHLC
92 3E11 YORR EQU 03E11H 4 BYTES,SUM OF CALC(NCALC)/NCHLC
93 3E15 PROP# EQU 03E15H 16H BYTES,CALCULATED PROPERTIES
94 3E20 CLORDR EQU 03E20H 1 BYTE, BASE ADDR OF INITIAL CHL RDGS
95 3E2C VOLNEW EQU 03E2CH NEU STANDARD RDGS,24 BYTES
96 3E44 VSTDYF EQU 03E44H BYTE TO SHOW THAT TUBE STANDARD HAS BEEN R
97 3E45 POSCH EQU 03E45H POSITION CHANNEL,2 BYTES
98 3E47 OLD EQU 03E47H OLD ADC VALUES,2*(POSCH#1) BYTES
99 3E5B POSCH# EQU 03E5BH NEU POSITION; CHL RDG ADDR
100 3E5D POSCH# EQU 03E5DH OLD POSITION CHANNEL RDC ADDR
101 3E5F RDC# EQU 03E5FH RDC CHANNEL NUMBER BYTE
102 3E60 ALK# EQU 03E60H ALK#1 BYTE
103 3E61 THICK EQU 03E61H THIN THICKNESS VALUE,2 BYTES
104 3E63 SYCNT EQU 03E63H 2 BYTES,CYCLE COUNT FOR IND TYPE
105 3E65 FILECT EQU 03E65H 1 BYTE,FILE COUNTER
106 3E66 COL# EQU 03E66H 2 BYTES,COL NUMBER FROM TAPE
107 3E69 RDC# EQU 03E69H RDC#10 FROM TERMINAL
108 3E6A PROP# EQU 03E6AH 2 BYTES,NO OF PROP TO BE CALCULATED

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109 3E6C          RCNT      EQU NPROP+2      ONE BYTE,NO. OF TAPE READINGS TO BE MADE
110              ;          RAM ADDRESS FOR TAPE READBACK WITH LOST DATA MUST HAVE
111              ;          A 2K RAM
112 3000          TAPDAT    EQU 3000H          TAPE READBACK DATA 400 BYTES
113              ;THREE FREQ PORTSET-UP
114 0000 3E 99          PRTSU    MVI A,PR11          LOAD PROGRAM WORD FOR A&C INPUT,B OUTPUT
115 0002 D3 F7          OUT PORT1          SEND TO PORT 1
116 0004 3E 90          MVI A,000H          LOAD PROGRAM WORD,A=INPUT,B&C=OUTPUT
117 0006 D3 EF          OUT PORT2          SEND TO PORT2.
118 0008 3E 07          MVI A,007H          LOAD 0000/0111 INTO A,CHART OFF,
119 000A D3 ED          OUT PORT2B          TURN CALIBRATOR RELAYS OFF
120 000C 3E 70          MVI A,070H          SET MAG TAPE READ,WRITE,DAC LATCH HI
121 000E D3 EE          OUT PORT2C          LEAVE STROBE LINES HI
122 0010 3E 93          MVI A,PR13          LOAD WORD FOR A OUT, B INPUT,C I/O
123 0012 D3 DF          OUT PORT3
124              ;          COPY INITIAL CORRECTION FACTORS INTO RAM
125 0014 21 52 12        LXI H,CRR0          ADDR OF CORR FAC IN ROM IN HL
126 0017 01 95 12        LXI D,DRFAC-1      ADDR OF LAST BYTE TO BE COPIED
127 001A 11 35 3C        LXI D,CRR4          ADDR WHERE CORR FAC IS COPIED TO IN RAM
128 001D CD 00 00        CALL COPDT          COPY DATA SUB CALL,START IN HL.
129 0020 3E 00          MVI A,0            LOAD 0 INTO A
130 0022 32 15 3C        STA PCAL1          SET 1ST PROP TO BE CALCULATED
131 0025 3E 01          MVI A,1            LOAD 1 INTO A
132 0027 32 16 3C        STA PCAL2          SET 2ND PROP TO BE CALCULATED
133 002A 3E 02          MVI A,2            LOAD 2 INTO A
134 002C 32 17 3C        STA PCAL3          SET 3RD PROP TO BE CALCULATED
135 002F 3E 03          MVI A,3            LOAD 3 INTO A
136 0031 32 18 3C        STA PCAL4          SET 4TH PROP TO BE CALCULATED
137              ;
138              ; READ THE TEN'S BCD SWITCH TO SEE WHICH SET OF INITIAL
139              ; CALIBRATION READINGS TO USE IN THIRD PROM.
140              ;
141 0034 DB DE          IN PORT3C          READ BCD SWITCHES IN REMOTE 3 FREQ INST
142 0036 E6 0F          ANI 0FH           ONLY LOOK AT FIRST 4 BITS
143 0038 07           RLC             MULTIPLY BY 2, GET OFFSET FROM ORG
144 0039 D6 10          ADI 10H           ADD ORG, WE HAVE HI BYTE OF CALO ADDR
145 003B 32 2B 3E          STA CLADR          STORE THIS HI BYTE
146              ;
147              ; BE SURE ALL TAPE CONTROL LINES ON CONN C0 ARE FALSE
148              ;
149 003E 3E 20          MVI A,020H          HOLD CNF(PORT3CS),0010/0000,HI
150 0040 D3 DE          OUT PORT2C
151              ;          DECISION BRANCH POINT FOR 3 FREQUENCY INSTRUMENT
152              ;          FRONT PANEL SWITCHES ALLOWS CONTROL OF ACTION
153              ;          TO BE TAKEN.ACTION SUMMARY IS:
154              ;          0.MAIN RUNNING LOOP-RECALIBRATE,RECORD
155              ;          RUN/RAM,RECORD,CALC UNTIL .NE.0
156              ;          RECALIBRATE,RECORD,STOP
157              ;
158              ;          1.READ TAPE
159              ;          2.READ STANDARD TUBE
160              ;          3.DISPLAY RAW READINGS
161              ;          4.DISPLAY CALCULATED READINGS
162              ;          5.PERFORM AND DISPLAY CALIBRATIONS
163              ;          6.INSPECT SQUARE CONDUCTORS

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163 ; 7.CALIBRATE THE DIG TO ANALOG CONVERTERS & RECORDER
164 ;
165 0042 DB EC MAIND IN PORT2A INPUT PORT2A,LOOK AT FRONT PANEL SWITCHES
166 0044 E6 07 ANI 07H SET STATUS BITS
167 0046 32 12 5C STA DSPAD STORE IN RAM
168 004D CA CB 00 JZ R00H IF SWITCHES EQ 0,JUMP TO MAIN RUN LOOP
169 004C FE 01 CPI 001H TEST FOR READ TAPE
170 004E CA C9 0F JZ RUC1P JUMP TO READ TAPE ROUTINE IF 2A.EQ.1
171 0051 FE 02 CPI 002H TEST FOR READ STANDARD
172 0053 CA DA 0E JZ R0ST0 CALL READ STANDARD ROUTINE
173 0056 FE 03 CPI 003H TEST FOR RAW RDGS LOOP
174 0058 CC 72 00 C2 RADWD CALL RAW READINGS ROUTINE
175 005B FE 04 CPI 004H TEST FOR CAL PROPS LOOP
176 005D CC 98 00 C2 CALPR0 CALL CALCULATED PROPERTIES ROUTINE
177 0060 FE 05 CPI 005H TEST FOR CALIBRATIN LOOP
178 0062 CC 0A 0D C2 CALIB CALL CALIBRATION LOOP
179 0065 FE 06 CPI 006H TEST FOR WELD REPAIR LOOP
180 0067 CA 9E 0D JZ R00H0 JUMP TO RUN LOOP FOR WELD REPAIR
181 006A FE 07 CPI 007H CALIBRATION PROGRAM FOR DIGITAL
182 006C CC E4 0D C2 DACNLE TO ANALOG CONVERTERS.
183 006F C3 42 00 JRP MAIND LOOP BACK TO READ FRONT PANEL AGAIN
184 ;
185 ;RAW READINGS ROUTINE
186 ;
187 0072 06 01 RADWD IVI B,RADWD NUMBER OF READINGS/CHANNEL IN B
188 0074 0E 06 IVI C,CH0H NUMBER OF CHANNELS IN C
189 0076 CD AE 0A CALL SMDAT AD CONVERTOR READ,BATH SUMMED
190 0079 3A 12 3C LDA DSPAD SEE WHERE WE WERE CALLED FROM
191 007C E6 01 ANI 01 CONTINUE NORMALLY FOR ODD FUNCTIONS
192 007E C8 RZ IF IT IS 0 OR 4, WAIT UNTIL RDGS ARE WRITT
193 ; ON MAG TAPE BEFORE FLOATING & CORRECTING
194 007F 06 00 FLT00R IVI B,CH0H NUMBER OF CHANNELS LOADED IN D
195 0081 CD 0F 0A CALL CRP0 READINGS ARE CORRECTED
196 0084 21 16 3C LXA B,CH0H LOAD ADDRESS OF RAW DATA IN HL
197 0087 16 06 IVI D,CH0H LOAD NO OF CHANNELS INTO D
198 0089 1E 01 IVI E,01H ONE LINE TO BE PRINTED LOADED INTO E
199 008B 01 04 0D LXI D,0004H LOAD FIXED FORMAT,9 DIGS,4 AFTER DEC
200 008E 3A 12 3C LDA DSPAD LOAD DISPLAY NO FROM RAM
201 0091 FE 03 CPI 003H SEE IF WE ARE IN RAW RDG LOOP
202 0093 CC 00 00 E C2 FRPRT PRINT RAW READINGS IF SO
203 0096 AF XRA A ZERO ACCUMULATOR
204 0097 C9 RET RETURN TO CALLING ROUTINE
205 ;
206 ; CALCULATE PROPERTIES ROUTINE
207 ;
208 0090 CD 72 00 CALPR0 CALL RADWD ENTRY POINT FOR FCN 4
209 009B CD 7F 00 CALPR CALL FLT00R FLOAT AND CORRECT RAW RDGS
210 009E 3E 02 IVI B,PROP0 NUMBER OF PROPERTIES IN A
211 00A0 32 14 3C STA PONLE STORED IN RAM
212 00A3 21 15 3E LXI B,PROP0 PROPERTY ADDRESS IN HL
213 00A6 E5 ONLPR0 RSH B HL STORED ON STACK
214 00A7 21 14 3C LXI B,POLENH ADDRESS OF PROP NO CAL IN HL
215 00AA 4E MOV C,H NUMBER OF PROPS LEFT TO BE CAL IN C
216 00AB 06 00 IVI B,0 EQ-NO OF PROPS LEFT TO BE CAL

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217	08AD	09		DAD B	HL = PCAL(N)=PROP NO TO BE CAL
218	08AE	7E		MOV A,M	LOADED INTO A
219	08AF	CD 38 0A		CALL POLSN	CALCULATE POLYNOMIAL FOR PROP1
220	0892	E1		POP H	ADDR TO STORE PROPS RESTORED TO HL
221	0893	CD 00 00	E	CALL TOS4	TOP OF ASTACK STORED IN RAM
222	0896	23		INX H	HL INCREMENTED FOR NEXT CAL PROP
223	0897	3A 14 3C		LDA PCALN	LOAD PROP CAL NO INTO A
224	089A	3D		DCR A	DECREMENT PROP CAL COUNTER
225	089B	32 14 3C		STA PCALN	
226	089E	C2 A6 00		JNZ CALPRL	LOOP BACK IF NOT DONE
227	08C1	3A 12 3C		LDA DSPAD	LOAD THE FRONT PANEL CONTROL DATA
228	08C4	FE 04		CPI 004H	SEE IF WE ARE IN CAL PROP LOOP
229	08C6	CC 2F 0F		C2 PCALP	PRINT CALCULATED PROPERTIES ON TERMINAL
230	08C9	AF		XRA A	ZERO ACCUMULATOR
231	08CA	C9		RET	RETURN TO CALLING ROUTINE
232			:		
233			:		
234			:	RUNM	MAIN RUNNING LOOP
235			:		RECALIBRATE, RUN UNTIL FRONT PANEL SWITCH IS MOVED
236			:		FROM 0, THEN MAKE A SET OF CALIBRATION READINGS. ALL
237			:		DATA IS RECORDED ON MAGNETIC TAPE.
238	08CB	21 00 00	RUNM	LXI H,0000H	ZERO BYTE COUNT FOR MAG TAPE WRITES
239	08CE	22 63 3E		SHLD BOUNT	STORE BYTE COUNT IN RAM
240	08D1	22 19 3C		SHLD CONTN	STORE READING COUNT NO IN RAM
241	08D4	3E 80		MVI A,PRTI0	SET PORT1 FOR OUTPUT TO TAPE
242	08D6	D3 F7		OUT PORT1	SEND CONTROL WORD
243	08D8	CD 6C 11		CALL WRITD	WRITE IDENTIFICATION ON TAPE
244	08DB	CD 00 00	E	CALL CROUT	CARRIAGE RETURN ,LINE FEED
245	08DE	3E 99		MVI A,PRTI1	SETUP FOR RECAL LOOP
246	08E0	D3 F7		OUT PORT1	
247	08E2	CD 99 00		CALL RECAL	CALL RECALIBRATION PROGRAM
248	08E5	01 99 3D		LXI B,CALRD	ADDRESS OF CALIBRATION RDDS IN BC
249	08E8	11 F8 3D		LXI D,CALRD+05FH	50H BYTES OF CALD RDDS TO BE STORED
250	08EB	3E 80		MVI A,PRTI0	SET PORT1 FOR OUTPUT TO TAPE
251	08ED	D3 F7		OUT PORT1	SEND CONTROL WORD
252	08EF	CD 57 0F		CALL WRTP	DATA FROM BC THRU DE STORED
253	08F2	01 35 3C		LXI B,CRFRA	ADDR OF CORRECTION FACTOR IN BC
254	08F5	11 64 3C		LXI D,CRFRA+02FH	LAST CORR FACT ADDR IN DE
255	08F8	CD 57 0F		CALL WRTP	WRITE ON TAPE
256	08FB	3E 99		MVI A,PRTI1	SETUP FOR RECAL LOOP
257	08FD	D3 F7		OUT PORT1	
258	08FF	21 45 3E		LXI H,POSCH	LOAD HL WITH CHANNEL POSITION ADDR
259	0902	CD 57 0F		CALL RESET	RESET ALL CHANNELS, START RDDS AFTER STROBE
260	0905	CD 72 00	RUNM	CALL RADWD	MAKE RAW RDDS, NO CORR YET
261	0908	01 1D 3C		LXI B,RAWDA+2	ADDR OF NON ZERO PART OF 1ST RAW DAT.
262	090B	11 32 3C		LXI D,RAWDA+17H	WRITE FROM COUNT NO THRU RAW DAT
263	090E	3E 80		MVI A,PRTI0	SET PORT1 FOR OUTPUT TO DAC
264	0910	D3 F7		OUT PORT1	CONTROL WORD SENT
265	0912	CD 78 0F		CALL WRTPF	STORE RAW RDDS ON TAPE
266	0915	CD 90 00		CALL CALP	CALC PROPS FROM RDDS ALREADY TAKEN
267	0918	CD FF 0C		CALL DACON1	DEFECT CALCULATIONS AVERAGED & SENT TO DAC
268	091B	CD 40 0E		CALL DACON2	SELECT MIN TH, SEND TO DAC IF POSCH=0
269				CALL OUTLIF	SEND MINIMUM LIFTOFF TO TERM EVERY F TIMES
270	091E	21 45 3E		LXI H,POSCH	LOAD HL WITH CHANNEL POSITION ADDR

271	0921	35		DCR H	DECREMENT CHANNEL POSITION INDEX IN MEM
272	0922	FC 57 09		CH RESET	RESET POS CH, INK COUNT NO, WAIT FOR NEXT ST
273	0925	3E 99		MVI A, PRT11	SET PORT1 BACK FOR INPUT
274	0927	D3 F7		OUT PORT1	CONTROL WORD SENT
275	0929	C3 05 09		JMP RUMH1	LOOP BACK FOR ANOTHER RUN
276	092C	C1	STOFR	POP B	POP STACK TO GET BACK CORRECT
277	092D	01 19 3C		LXI D, CONTH	ADDR OF COUNT NO
278	0930	11 1A 3C		LXI D, CONTH+1	LAST BYTE OF COUNT NO.
279	0933	CD 57 0F		CALL WRTAP	STORE ON TAPE, NO INCREMENT
280	0936	3E 99		MVI A, PRT11	SETUP FOR CALIBRATION LOOP
281	0938	D3 F7		OUT PORT1	
282	093A	CD 0A 0D		CALL CALIB	MAKE ANOTHER CALIBRATION
283	093D	3E 09		MVI A, PRT10	SET PORT1 FOR OUTPUT TO TAPE
284	093F	D3 F7		OUT PORT1	SEND CONTROL WORD
285	0941	01 29 3D		LXI D, CALRD	ADDRESS OF CALIBRATION EDGE IN BC
286	0944	11 F0 3D		LXI D, CALRD+05FH	END BYTES OF CALD RDS TO BE STORED
287	0947	CD 57 0F		CALL WRTAP	DATA FROM BC THRU DE STORED
288	094A	CD 36 11		CALL DUMPDF	DUMP THE REST OF THE BUFFER ON TAPE
289	094D	CD 4E 11		CALL WFOF	WRITE END OF FILE ON TAPE
290	0950	3E 99		MVI A, PRT11	SET PORT 1 FOR INPUT
291	0952	D3 F7		OUT PORT1	SEND CONTROL WORD
292	0954	C3 09 0D	E	JMP GETCH	RETURN TO MONITOR
293					
294	0957	36 09	RESET	MVI H, POSCHH	RESET POSITION CHANNEL NUMBER
295	0959	DB EC		IN PORTCH	LOOK AT FRONT PANEL CONTROL SWITCHES
296	095B	E6 07		ANI 07H	DUMP SPEED, DIR SELECTION BITS
297	095D	C2 2C 09		JNE STOFR	STOP RUN IF NOT ZERO
298	095D	DB EC		IN PORT2A	INPUT CHANNEL SWIC BIT
299	095E	E6 03		ANI 03H	AND WITH C00C/C005, SWIC BIT
300	0954	C2 57 09		JNE RESET	HANG IN LOOP UNTIL PROBE STARTS ACROSS
301	0957	DB EC		IN PORTCH	LOOK AT CH-CHECK FOR REZERO
302	0959	E6 4D		ANI 040H	SEE IF C100/C000 IS HI
303	095B	C4 00 0D		CHG REZER0	RESET DAC OFFSETS IF HI
304	095E	2A 19 3C		LHLD CONTH	LOAD COUNT NUMBER FROM RAM
305	0971	23		INX H	INCREMENT COUNT NUMBER
306	0972	22 19 3C		CHLD CONTH	STORE BACK IN RAM
307	0975	01 19 3C		LXI D, CONTH	LOAD COUNT TO ADDR INTO BC
308	0978	11 1A 3C		LXI D, CONTH+1	END OF COUNT NO IN DE
309	097B	CD 57 0F		CALL WRTAP	WRITE ON P50 TAPE
310	097E	21 00 3E		LXI H, CALRD	LOAD ADDRESS OF ALARM BYTE INTO HL
311	0981	7E		MOV B, H	LOAD ALARM BIT(C000-B100) FROM RAM
312	0982	F6 37		ANI 001H	OR WITH 0011 0111 BITS FOR CALIBRATOR
313	0984	D3 ED		OUT PORT2D	SET ALARM ACCORDING TO D6
314	0986	AF		XRA A	ZERO ACC
315	0987	77		MOV A, A	RESET ALARM BIT
316	0988	21 59 3E		LXI H, DADLD+2*POSCHH	
317	098B	22 5B 3E		CHLD POSCHD	STORED FOR NEW ADDR ADDR
318	098E	21 40 3E		LXI H, DADLD+1	LD ORDER BYTE OF 1ST RDS
319	0991	22 5D 3E		CHLD POSCHD	STORED FOR OLD ADDR ADDR
320	0994	AF		XRA B	ZERO ACCUMULATOR
321	0995	32 0F 3E		STB DADCH	ZERO DAC CHANNEL NUMBER
322	0998	3E 0F		MVI B, CHN	LOAD HEAR TEST VALUE INTO B
323	099A	32 61 3E		STB DADCH	STORE AC IN ORDER TEST TEST VALUE
324	099D	C9		RET	

325			2		
326			3		
327			4		
328			5		
329			6		
330			7		
331	099E	21 00 00	RUNNS	LXI H,0000H	ZERO BYTE COUNT FOR MAG TAPE WRITES
332	09A1	22 63 3E		SHLD BYCNT	STORE IN RAM
333	09A4	3E 80		MVI A,PORT10	SET PORT1 FOR OUTPUT TO TAPE
334	09A6	D3 F7		OUT PORT1	SEND CONTROL WORD
335	09A8	CD 6C 11		CALL WRTID	WRITE IDENTIFICATION ON TAPE
336	09AB	CD 00 00	E	CALL CROUT	CARRIAGE RETURN ,LINE FEED
337	09AE	3E 99		MVI A,PORT11	SETUP FOR RECAL LOOP
338	09B0	D3 F7		OUT PORT1	
339	09B2	CD 99 80		CALL RECAL	CALL RECALIBRATION PROGRAM
340	09B5	01 93 3D		LXI B,CALRD	ADDRESS OF CALIBRATION RDGS IN BC
341	09B8	11 F0 3D		LXI D,CALRD+05FH	60H BYTES OF CALD RDGS TO BE STORED
342	09BB	3E 80		MVI A,PORT10	SET PORT1 FOR OUTPUT TO TAPE
343	09BD	D3 F7		OUT PORT1	SEND CONTROL WORD
344	09BF	CD 57 0F		CALL WRTAP	DATA FROM BC THRU DE STORED
345	09C2	01 35 3C		LXI D,CRRFA	ADDR OF CORRECTION FACTOR IN BC
346	09C5	11 64 3C		LXI D,CRRFA+02FH	LAST CORR FACT ADDR IN DE
347	09C8	CD 57 0F		CALL WRTAP	WRITE ON TAPE
348	09CB	3E 99		MVI A,PORT11	SETUP FOR RECAL LOOP
349	09CD	D3 F7		OUT PORT1	
350	09CF	21 00 00		LXI H,0000	ZERO HL FOR COUNT NUMBER
351	09D2	22 19 3C		SHLD CONTN	STORE IN RAM
352	09D5	CD 72 00	RUNNS1	CALL RADWD	MAKE RAW RDGS. NO CORR YET
353	09D8	2A 19 3C		LHLD CONTN	LOAD COUNT NUMBER FROM RAM
354	09DB	23		INX H	INCREMENT COUNT NUMBER
355	09DC	22 19 3C		SHLD CONTN	STORE BACK IN RAM
356	09DF	01 1D 3C		LXI B,RAWDA+2	ADDR OF NON ZERO PART OF 1ST RAW DATA
357	09E2	11 32 3C		LXI D,RAWDA+17H	WRITE FROM COUNT NO THRU RAW DAT
358	09E5	3E 80		MVI A,PORT10	SET PORT1 FOR OUTPUT TO DAC
359	09E7	D3 F7		OUT PORT1	CONTROL WORD SENT
360	09E9	CD 7B 0F		CALL WRTAPF	STORE RAW RDGS ON TAPE
361	09EC	CD 7F 00		CALL FLTCLR	FLOAT AND CORRECT RAW RDGS
362	09EF	3E 04		MVI A,PROPN+2	NUMBER OF PROPS. FOR SQWLD IN A
363	09F1	32 14 3C		STA PCALM	STORED IN RAM
364	09F4	21 15 3E		LXI H,PROPA	PROPERTY ADDRESS IN HL
365	09F7	CD A6 00		CALL CALPRL	CALCULATE THE PROPERTIES
366	09FA	CD 0A 0E		CALL DACONS	CONVERT TO ANALOG FOR WELD REPAIR
367	09FD	3E 99		MVI A,PORT11	SET PORT1 BACK FOR INPUT
368	09FF	D3 F7		OUT PORT1	CONTROL WORD SENT
369	0A01	DB EC		IN PORT2A	LOOK AT FRONT PANEL CONTROL SWITCHES
370	0A03	E6 07		ANI 07H	DUMP SPEED,DIR SELECTION BITS
371	0A05	FE 06		CPI 000H	SEE IF VAL IS STILL 00H
372	0A07	CA D5 09		JZ RUNNS1	STAY IN LOOP IF IT IS
373	0A0A	3E 80		MVI A,PORT10	SET PORT1 FOR OUTPUT TO TAPE
374	0A0C	D3 F7		OUT PORT1	SEND CONTROL WORD
375	0A0E	01 19 3C		LXI B,CONTN	ADDR OF COUNT NO
376	0A11	11 1A 3C		LXI D,CONTN+1	LAST BYTE OF COUNT NO.
377	0A14	CD 57 0F		CALL WRTAP	STORE ON TAPE
378	0A17	3E 99		MVI A,PORT11	SETUP FOR CALIBRATION LOOP

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379 0A19 D3 F7          OUT PORT1
380 0A1B CD 0A 0B      CALL CALIB           MAKE ANOTHER CALIBRATION
381 0A1E 3E 08          MVI A,PORTIO        SET PORT1 FOR OUTPUT TO TAPE
382 0A20 D3 F7          OUT PORT1           SEND CONTROL WORD
383 0A22 01 09 3D      LXI D,CALIB+00FH    ADDRESS OF CALIBRATION RDCS IN BC
384 0A25 11 F0 3D      LXI D,CALIB+00FH    FOR BYTES OF CALIB RDCS TO BE STORED
385 0A28 CD 57 0F      CALL MXTAP          DATA FROM BC THRU DE STORED
386 0A2B CD 36 11      CALL DUMDF          DUMP THE REST OF THE BUFFER ON TAPE
387 0A2E CD 4E 11      CALL MGEF           WRITE END OF FILE ON TAPE
388 0A31 3E 09          MVI A,PORTII        SET PORT 1 FOR INPUT
389 0A33 D3 F7          OUT PORT1           SEND CONTROL WORD
390 0A35 C3 00 00      JMP GETCH           RETURN TO TIGHTER
391
392
393 ;POLCH - SUBROUTINE CALCULATES PROPK FROM COEFS (CKI) AND RDCS (RIK)
394 ;PROPK = OFFSET + CK1*RIK + CK2*RIK + CK3*RIK ...+CKJ*RIK.
395 ;THE "READINGS" MUST ALREADY BE CALCULATED AND STORED IN RAM, AT ADDRESS
396 ;STARTING AT RDCDA + K*(COEFFICIENT OFFSET(COEF)). THE TERMS ARE
397 ;CALCULATED AND SUMMED FROM THE HIGHEST ORDER TO THE LOWEST ORDER.
398 ;THE PROPERTY NUMBER TO BE CALCULATED MUST BE SET IN A.
398 0A38 D3 7E          POLCH  OUT APDATA    LOAD PROPERTY NO INTO AP STACK
399 0A3A AF             CALL D             ZERO A
400 0A3D D3 7E          OUT APDATA        LOAD END BYTE INTO AP STACK
401 0A3D CD 00 00      CALL PROC          AP STACK CONTAINS 2 COPIES OF PROP NO
402 0A40 3E 00          MVI A,COEF        READING OFFSET LOADED INTO A
403 0A42 D3 7E          OUT APDATA        AND STORED INTO APSTACK
404 0A44 AF             XRA A             A ZEROED
405 0A45 D3 7E          OUT APDATA        SECOND BYTE ON AP STACK
406 0A47 CD 00 00      CALL SHUL          LOW ORDER TWO BYTE PRODUCT CALCULATED
407 0A4A DB 7E          IN APDATA         READ FROM APSTACK
408 0A4C 57             MOV D,A           STORED IN D
409 0A4D D0 7E          IN APDATA         LO ORDER BYTE READ
410 0A4F 5F             MOV E,D           LOADED INTO E
411 0A50 21 10 3C      LXI H,RAUBA       STARTING ADDR OF RDC DATA LOADED INTO HL
412 0A53 19             DAD D             HL HAS START RDC ADD +(RDCOF)*(PRO NO)
413 0A54 ED             XCHG             MOVED TO DE
414 0A55 3E 3D          MVI A,COEF        COEFFICIENT OFFSET MOVED INTO A
415 0A57 D3 7E          OUT APDATA        STORED ON AP STACK
416 0A59 AF             XRA A             A ZEROED
417 0A5A D3 7E          OUT APDATA        AND STORED ON STACK
418 0A5C C9 00 00      CALL SHUL          LOW ORDER (COEF OFFSET)*(CH NO) CALC
419 0A5F DB 7E          IN APDATA         HI BYTE READ IN
420 0A61 67             MOV H,A           AND STORED IN H
421 0A62 DB 7E          IN APDATA         LOW ORDER BYTE READ
422 0A64 6F             MOV L,A           AND STORED IN L,HL=(COEF OFF)*(CH NO)
423 0A65 3A 2B 3E      LDA CLADR          LOAD COEFT STARTING COEFF IN BC
424 0A68 47             MOV D,A           GET HI BYTE INTO D
425 0A69 0E 79          MVI C,COEFT-CALD GET OFFSET FROM CALD TO COEFT
426 0A6B 09             DAD B             AND ADDED TO HL,HL=(COEFT*(CH NO)+COEFT
427 0A6C 7E             MOV A,H           NO OF TERMS IN POLYNOMIAL LOADED IN A
428 0A6D 07             AND A             NO TERMS DODEED
429 0A6E 07             AND A             THEN 4 TERMS(SINCE THERE ARE 4 BYTES EACH)
430 0A6F 4F             MOV C,A           (AND TERMS) IN C
431 0A70 06 00          MVI D,0           D ZEROED,LC CONTAINS (AND TERMS)
432 0A72 0D             DAD L             HL=(COEFT*COEFT*(AND TERMS)

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433 0A73 EB          XCHG          DE=COEET+COEOP*(RDC NO)+4*(NO TERMS)
434 0A74 09          DAD B         HL=RDCDA+RDCOP*(RDC NO)+4*(NO TERMS)
435 0A75 2B          DCX H         READING CALS CONTAINS 1 LESS BYTE THAN COE
436 0A76 1F          RAR          ACCUMULATOR ROTATED RIGHT TWICE
437 0A77 1F          RAR          TO GET COUNT NO, RATHER THAN 4*(COUNT NO)
438 0A78 47          MOV B,A      NO OF TERMS IN POLYNOMIAL COUNT IN B
439 0A79 AF          XRA A        ZERO ACCUMULATOR, WILL BE LOADED IN AP
440 0A7A D3 7E         OUT APDATA   FIRST BYTE SENT OUT
441 0A7C D3 7E         OUT APDATA   2ND AND 3RD BYTES SENT TO AP
442 0A7E D3 7E         OUT APDATA   AP NOW CONTAINS 32 BIT, 4 BYTE
443 0A80 D3 7E         OUT APDATA   FLOATING POINT ZERO
444 0A82 CD 00 00     E  POLLP    CALL FMULD   MULTIPLY READING*COEFFICIENT
445 0A85 CD 00 00     E          CALL FADD   ADD RESULT TO RUNNING SUM ON AP STACK
446 0A88 1B          DCX D        DECREMENT DE, COEFFICIENT ADDR POINTER
447 0A89 2B          DCX H        DECREMENT HL, READING ADDR POINTER
448 0A8A 05          DCR B        DECREMENT B, TERM COUNTER
449 0A8B C2 82 0A     JNZ POLLP   STAY IN LOOP UNTIL ALL TERMS DONE
450 0A8E C9          RET         RETURN WITH ANSWER ON AP STACK WHEN DONE
451                ;CRFAC - PROGRAM APPLIES CORRECTION FACTORS AI + BI*RI = R*I TO
452                ;NO OF READINGS STORED IN REG B. THE PROGRAM STARTS WITH THE
453                ;LAST RAW READING (4 BYTES) MULTIPLIES THE GAIN, ADDS THE
454                ;OFFSET, AND STORES THE RESULT BACK IN PLACE OF THE RAW DATA.
455                ;THE PROGRAM EXITS WHEN THE FIRST CHANNEL HAS BEEN DONE.
456                ;HL, DE, & A REGISTERS ARE OVERWRITTEN.
457 0A8F 21 32 3C     CRFAC       LXI H, RAMDA+17H  HL SET FOR LAST RAW DATA BYTE
458 0A92 11 64 3C     LXI D, CRFRA+2FH DE = ADDR OF LAST BYTE OF CORR FAC
459 0A95 CD 00 00     E  CORLP    CALL FLTDA   FLOAT THE RAW READING
460 0A98 EB          XCHG        XCHANGE HL WITH DE(ADDR OF CORR FACT IN HL)
461 0A99 CD 00 00     E          CALL FMULA   MULTIPLY RAW DATA BY CORR FAC
462 0A9C 2B          DCX H        DECREMENT HL TO OFFSET
463 0A9D CD 00 00     E          CALL FADDA   ADD OFFSET TO READING
464 0AA0 2B          DCX H        SET ADDRESS FOR NEXT CORRECTION FACTOR
465 0AA1 EB          XCHG        STORE BACK IN DE
466 0AA2 CD 00 00     E          CALL TUSA   CORRECTED READING STORED BACK
467 0AA5 2B          DCX H        HL DECREMENTED 4 TIMES, ADDR NEXT RAW DAT
468 0AA6 2B          DCX H
469 0AA7 2B          DCX H
470 0AA8 2B          DCX H
471 0AA9 05          DCR B        DECREMENT THE COUNTER IN B
472 0AAA C2 95 0A     JNZ CORLP   LOOP BACK IF B .NE. 0
473 0AAD C9          RET         RETURN TO CALLING PROG IF DONE
474                ;SDAT - DATA SUMMATION ROUTINE, STARTING WITH CHANNEL 1, READS NO OF
475                ;CHANNELS IN C, WITH NO OF READINGS PER CHANNEL IN B (UP TO
476                ;255). SUM OF THE DATA WILL BE IN RAMDA +4 + (4*CH. NO.)
477                ;RAW DATA IS STORED AS MAG1, PH1, MAG2, PH2, MAG3, PH3; 4 BYTES EACH
478 0AAE 21 1B 3C     SDAT       LXI H, RAMDA   HL LOADED WITH LAST RAW DATA ADDRESS
479 0AB1 C9          PUSH B      COPY OF REGS B,C STORED ON STACK
480 0AB2 79          MOV A,C     NUMBER OF CHANNELS LOADED INTO A
481 0AB3 87          ADD A
482 0AB4 87          ADD A
483 0AB5 4F          MOV C,A    4*NO OF CHANNELS IN REG C
484 0AB6 AF          XRA A      A REGISTER ZEROED
485 0AB7 CD 00 00     E          CALL ZERO   ZERO RAM FROM HL TO HL+0
486 0ABA C1          POP B      NO OF CHANNELS (REG C) * TIMES/CH (B) RES

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487	0A9B	11 04 00		LXI D,0004H	LOAD #4 INTO DE
488	0ABE	21 1E 3C	SHLOP	LXI H,RA0DA+03H	HL LOADED WITH FIRST RAW DATA ADDRESS
489	0AC1	C5		PUSH D	AND COPY STORED ON STACK AGAIN
490	0AC2	CD F4 0A		CALL ABCUS	CHECK FOR BUSY, START NEXT CONVERSION
491	0ACS	3E 06	CHLUP	LVI A,BCNA	TOTAL NUMBER OF CHANNELS IN A
492	0AC7	91		SUB C	NO. = TOTAL NO. - CHA COUNT IN REG C
493	0AC8	CD DC 0A		CALL ABCRG	TAKE AD CON. RDC, ANSWER ON AP TOP OF STACK
494	0ACB	CD 00 00	E	CALL DADA	32 BIT FIXED ADD TO DATA AT HL, HL=HL-3
495	0ACE	CD 00 00	E	CALL TDC	AP TOP OF STACK STORED IN RAM AT HL
496	0AD1	19		ADD D	DE (+4) ADDED TO HL, POINTS TO NEXT ADDR
497	0AD2	0D		DCR C	CHANNEL COUNT DECREMENTED
498	0AD3	C2 C5 0A		JNE CHLUP	JUMP BACK TO CHANNEL LOOP IF NOT FINISHED
499	0AD6	C1		POP B	RESTORE BC FROM STACK
500	0AD7	05		DCR B	DECREMENT THE NUMBER OF RDCS/CHANNEL
501	0ADB	C2 BE 0A		JNZ SHLOP	GO BACK TO THE SUM LOOP IF NOT FINISHED
502	0ADB	C9		RET	
503			;ADRDG		SELECTS THE AD CONVERTOR NUMBER THAT IS IN A, READS THE
504			:		12 BITS FROM THE CONVERTOR, ADDS 20 BENDG AND RETURNS WITH
505			:		A POSITIVE 32 BIT FIXED NUMBER ON THE TOP OF THE RSTACK.
506			:		FOR LATEL ADC-ET12D ANALOG TO DIGITAL CONVERTOR.
507	0ADC	C6 98	BENDG	ADI 000H	CH SEL NO. ADY'S ON 000H, SEL ON ADD
508	0ADE	D3 F5		OUT PORT1D	SET CH. SWITCH TO CH. NO.
509	0AE0	D0 F4		IN PORT1A	LOW ORDER BYTE IS BROUGHT IN AND
510	0AE2	D3 7E		OUT APDATA	STORE ON ARITHMETIC PROCESSOR STACK.
511	0AE4	DB F6		IN PORT1C	HIGH ORDER BYTE IS BROUGHT IN.
512	0AE6	EG 0F		ANI 0FH	4 HIGHEST ORDER BITS ARE DUMPED
513	0AE8	D3 7E		OUT APDATA	STORE ON ARITHMETIC PROCESSOR STACK.
514	0AEA	AF		ORA A	ZERO ACCUMULATOR
515	0AEB	D3 7E		OUT APDATA	STORE ON ARITHMETIC PROCESSOR STACK.
516	0AED	D3 7E		OUT APDATA	STORE ON ARITHMETIC PROCESSOR STACK.
517	0AEF	3E 90		LVI A,000H	LEAVE START LG, DESELECT AD CONVERTORS
518	0AF1	D3 F5		OUT PORT1D	SEND TO PORT1D
519	0AF3	C9		RET	RETURNS WITH POS. ANSWER ON AP STACK.
520			:		
521			:		
522			:	ABUS	HANG HERE UNTIL ALL BUSY LINES OF THE LATEL
523			:		ADC-ET12D ANALOG TO DIGITAL CONVERTORS GOES LOW
524			:		THEN START THE NEXT CONVERSION AND RETURN. THE
525			:		DATA FROM THE LAST CONVERSION CAN BE READ FOR
526			:		THE NEXT 9 NANOSECONDS.
527	0AF4	D0 F6	ABUS	IN PORT1C	CHECK PORT1C, BIT4 FOR BUSY (HI)
528	0AF6	EG 10		ANI 010H	DUMP ALL BITS EXCEPT #4
529	0AF8	C2 F4 0A		JNE ABUS	STAY IN LOOP UNTIL BUSY LINE LOW
530	0AFD	3E 00		LVI A,000H	SEND START BIT HI
531	0AFD	D3 F5		OUT PORT1D	STROBE BIT HI, STARTS CONVERSION
532	0AFF	C9		RET	START BIT WILL GO LG WITH DATA CH READ
533			;DELAY 2 FREQ. - GENERATES A TIME DELAY, DEPENDING ON THE CONSTANT LOADED		
534				INTO DC, * CYCLES = 255*FREQ/DC	
535	0B00	E5	DELAY	PUSH H	SAVE THE CONTENTS OF HL AND
536	0B01	21 00 00		LXI H,00H	ZERO HL
537	0B04	09	LOOPH	ADD D	ADD DC TO THE CONTENTS OF HL
538	0B05	D2 04 0B		JNE LOOPH	STAY IN LOOP UNTIL HL OVERFLOWS.
539	0B00	E1		POP B	RESTORE ORIGINAL VALUES
540	0B09	C9		RET	AND RETURN.

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541
542 ;CALIB CALIBRATION PROGRAM - MAKES 4 SETS OF CALIBRATION READINGS
543 ; FOR EACH OF NCALC CALIBRATION READINGS PER DATA CHANNEL. EACH
544 ; CALIBRATION READING IS MADE 4*15 TIMES, AND THE READINGS ARE
545 ; AVERAGED AND STORED STARTING AT CALRD
546 ;
547 0B0A AF CALIB XRA A ZERO ACCUMULATOR, SO RAM CAN BE ZEROED
548 0B0B 21 99 3D LXI H,CALRD RAM ADDRESS TO BE ZEROED LOADED
549 0B0C 0E 60 MVI C,000H NUMBER OF BYTES TO BE ZEROED IN C
550 0B10 CD 00 00 E CALL ZERO RAM ZEROED FROM CALRD TO CALRD+3FH
551 0B13 3E 04 MVI A,04H INITIAL NO OF CALIBRATIONS SET TO 4
552 0B15 32 10 3C CALLP STA TRMCT NO OF CALIBRATIONS STORED IN TRMCT
553 ; TRMCT IS NUMBER OF TIMES EACH CALIBRATOR VALUE READ
554 0B18 21 9C 3D LXI H,CALRD+03H HL LOADED WITH FIRST ADDRESS
555 0B1B 11 04 00 LXI D,0004H LOAD +4 INTO DE
556 0B1E AF XRA A ZERO A
557 ; NOW LOOP OVER NUMBER OF MAG & PH CALIBRATOR VALUES
558 0B1F 32 11 3C CHALP STA CHANO STORE CHANNEL NUMBER BACK IN CHANO
559 0B22 E6 03 ANI 03H DUMP ALL BUT TWO LOWER BITS
560 ; ADI 0400H TURN ON STRIP CHART REC DURING CALIBRATE
561 0B24 D3 ED OUT PORT2B SET CALIBRATOR ADDRESSES
562 0B26 01 93 00 LXI B,0000 LOAD DELAY FOR BC
563 0B29 CD 00 00 CALL DELAY DELAY FOR 150 MS TO ALLOW RDGS TO SETTLE
564 0B2C CD 00 00 CALL DELAY DELAY FOR 150 MS TO ALLOW RDGS TO SETTLE
565 0B2F 06 10 MVI D,0100H 160 RDGS/CH IN 0.6 CHS IN C
566 0B31 0E 06 MVI C,NCHA NUMBER OF DATA CHANNELS TO BE READ IN C
567 0B33 E5 PUSH H HL STORED ON STACK
568 0B34 3E 00 MVI A,0000H SEND START BIT HIGH
569 0B36 D3 F5 OUT PORT1D STROBE START LINE HI, STARTS CONVERSION
570 ; FOR FIRST READING
571 0B38 3E 90 MVI A,0000H SEND START BIT LOW
572 0B3A D3 F5 OUT PORT1D STROBE START LINE LOW
573 ; LOOP OVER NUMBER OF TIMES MAG & PHASE VALUES READ FOR
574 ; EACH CALIBRATOR SETTING
575 0B3C E1 SMCLP POP H HL ADDRESSES RESTORED
576 0B3D E5 PUSH H HL COPIED ON STACK AGAIN
577 0B3E C5 PUSH B BC COPIED ON STACK AGAIN
578 0B3F CD F4 0A CALL ADDBUS HANG HERE UNTIL ADC'S ARE READY
579 ; LOOP OVER NUMBER OF MAG & PHASE VALUES AT EACH FREQUENCY
580 0B42 3E 06 CHCLP MVI A,NCHA CALIBRATION CHANNEL LOOP, CH NO IN A
581 0B44 91 SUB C NCH = TOTAL NO. - CHA COUNT IN REG C
582 0B45 CD DC 0A CALL ADXRDG MAKE AD CON RDG, ANSWER ON AP STACK
583 0B48 CD 00 00 E CALL DADDA 32 BIT FIXED ADD TO DATA AT HL; HL=HL+3
584 0B4B CD 00 00 E CALL TOS4 AP TOP OF STACK STORED IN RAM AT HL
585 0B4E 19 DAD D DE (+4) ADDED TO HL
586 0B4F 0D DCR C CHANNEL COUNT DECREMENTED
587 0B50 C2 42 00 JNZ CHCLP DO NEXT CHANNEL IF NOT FINISHED
588 0B53 C1 POP B RESTORE BC FROM STACK
589 0B54 05 DCR B DECREMENT NUMBER OF RDGS PER CHANNEL
590 0B55 C2 3C 00 JNZ SMCLP GO BACK TO SUB LOOP IF NOT DONE
591 0B58 C1 POP B FORMER HL IS POPPED INTO B, CLEARING STACK
592 0B59 3A 11 3C LDA CHANO THE CALIBRATION CH NO LOADED INTO A
593 0B5C 3C INR A INCREMENT CH NO.
594 0B5D FE 04 CPI NCALC ZERO BIT WILL BE SET WHEN CHANO=NCALC

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595 005F C2 1F 0D          JNZ CALP          LOOP BACK IF NOT DONE
596 0062 3A 10 3C          LRA TRPCT        LOAD THE NUMBER OF TIMES THRU CALB LOOP IN
597 0065 3D                DCR A            DECREMENT TIMES THRU LOOP
598 0066 C2 15 00          JNZ CALLP        GO BACK THRU CALIBRATION LOOP UNTIL DONE
599 0069 3E 07          MVI A,007H      LOAD 0000/0111 INTO A,CHART OFF,
600 006B D3 ED          OUT PORT2B      TURN CALIBRATOR RELAYS BACK OFF
601
602 ;
603 ;
604 006D 21 9C 3D          LXI H,CALRD*03H  LOAD ADDRESS OF FIRST RAW BYTE IN HL
605 0070 06 10          MVI B,10H       COUNTER IN B SET FOR 10H(24D) CORRECTIONS
606 0072 CD 00 00          E CALL2          CALL FLTDA       FLOAT RAW READINGS
607 0075 EB                XCHG            STORE HL IN DE TEMPORARILY
608 0076 21 4D 12          LXI H,CALFR*03  LOAD ADDRESS OF CALIB CORR FAC IN HL
609 0079 CD 00 00          E CALL FNULA     MULTIPLY READING BY CORRECTION FACTOR
610 007C EB                XCHG            RESTORE THE RAW CALIB DATA ADDR IN HL
611 007D CD 00 00          E CALL T004     STORE CORRECTED DATA BACK IN RAM
612 0080 23                INX H           HL INCRMTD 4 TIMES TO POINT TO NEXT ADDR
613 0081 23                INX H
614 0082 23                INX H
615 0083 23                INX H
616 0084 05                DCR B           DECREMENT COUNTER IN B
617 0085 C2 72 0D          JNZ CALL2       LOOP BACK IF NOT DONE
618 0088 21 99 3D          PROLB LXI H,CALRD     LOAD ADDRESS OF CALIBRATION RDGS IN HL
619 008D 11 04 06          LXI D,0004H     LOAD NO PER LINE,NO OF LINES IN DE
620 008E 01 04 05          LXI B,0004H     LOAD FIXED FORMAT,9 DIGS,4 AFTER DEC
621 0091 CD 00 00          E CALL PRNT     PRINT CALIBRATION RDGS ON CRT
622 0094 CD 00 00          E CALL CROUT   PRINT CARRIAGE RETURN,LINEFEED
623 0097 AF                XRA A           ZERO ACC SO MAIN LOOP WILL RUN CORRECT
624 0098 C9                RET             RETURN TO CALLING PROGRAM
625 ;
626 ;RECAL RECALIBRATION PROGRAM-MAKES A NEW SET OF CALIBRATION RDGS
627 ; AND DOES A LEAST SQUARES FIT OF THE NEW READINGS TO THE CALIBRATION
628 ; READINGS THAT WERE TAKEN BY TUBRDG & USED WHEN THE COEFFICIENTS WERE
629 ; CALCULATED BY TUDFIT.THE FIT IS DONE FOR NCHA DATA CHANNELS,FOR
630 ; KCALC CALIBRATION RDGS PER CHANNEL. CAL0=OFFST*0LOPER/CALCD
631 ;
632 0099 CD 0A 00          RECAL CALL CALIB   MAKE A NEW SET OF CALIBRATION READINGS
633 009C 06 06          MVI B,NCHA     NUMBER OF DATA CHANNELS IN REG B
634 009E 11 03 00          LXI D,03       DE WILL CONTAIN THE OFFSET FOR CALRD&CALU
635 00A1 AF                RECLP XRA A       ZERO ACCUMULATOR,WILL ZERO INITIAL VALUES
636 00A2 21 F9 3D          LXI H,SUM*XX   FIRST LOCATION TO BE ZEROED IN HL
637 00A5 0E 1C          MVI C,01CH    SET C COUNTER FOR 20 D BYTES TO BE ZEROED
638 00A7 CD 00 00          E CALL ZERO     ZERO SUMS
639 00AA 0E 04          MVI C,KCALC   THE NUMBER OF CALIB RDGS TO BE USED IN C
640 00AC 21 99 3D          RECL2 LXI H,CALRD    HL LOADED WITH ADDR OF 1ST CALIB RDG.
641 00AF 19                INR B          B BE OFFST ADDR,ADDRESSES CALRD(NCHA,KCALC)
642 00B0 CD 00 00          E CALL LUDA    LOAD DATA AT HL ADDR IN RAM ON APSTACK
643 00B3 CD 00 00          E CALL PYD     MAKE 2ND COPY OF CALRD ON APSTACK
644 00B5 CD 00 00          E CALL PYD     MAKE 3RD COPY OF CALRD ON APSTACK
645 00B9 CD 00 00          E CALL PYD     MAKE 4TH COPY OF CALRD ON APSTACK
646 00BC C9 00 00          E CALL PDEL   CALRD*2 ON TOP OF APSTACK
647 00BF 21 FC 3D          LXI H,CALRD*2  LOAD ADDR OF CALRD*2 SUM
648 00C2 CD 00 00          E CALL TRDRA   ADD CALRD*2 TO SUM

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649	0BC5	CD 00 00	E	CALL TOS4	STORE BACK IN RAM (CHECKS HL 3 TIMES)
650	0BC8	21 00 3E		LXI H,SUMX+03H	ADDR OF SUMX IN HL
651	0BC9	CD 00 00	E	CALL FADDA	CALRD + SUM OF CALRDS,HL DECRD BY 3
652	0BCE	CD 00 00	E	CALL TOS4	SUM CALRDS IN RAM,HL INCRD BY 3
653	0BD1	3A 2B 3E		LDA CLADR	PUT ADDR OF INIT CALIB RDS IN HL
654	0BD4	67		MOV H,A	
655	0BD5	AF		XRA A	ZERO LO BYTE
656	0BD6	6F		MOV L,A	
657	0BD7	19		DAD D	DE OFST ADDED,ADDR OF CALO(NCHA,NCALC) IN
658	0BD8	CD 00 00	E	CALL WRT4	CALO(NCHA,NCALC) ON TOP OF APSTACK
659	0BD8	CD 00 00	E	CALL PTOD	2ND COPY OF CALO ON APSTACK
660	0BDE	CD 00 00	E	CALL PTOD	3RD COPY OF CALO ON APSTACK
661	0BE1	CD 00 00	E	CALL FMUL	CALO**2 ON TOP OF APSTACK
662	0BE4	21 04 3E		LXI H,SUMY+03H	SUM OF CALDS**2 ADDR BY HL
663	0BE7	CD 00 00	E	CALL FADDA	CALO**2 ADDED TO SUM
664	0BE9	CD 00 00	E	CALL TOS4	SUM OF CALD**2S STORED BACK IN RAM
665	0BED	CD 00 00	E	CALL PTOD	2 COPIES OF CALO ON APSTACK NOW
666	0BF0	21 00 3E		LXI H,SUMY+03H	SUM OF CALDS ADDR BY HL
667	0BF3	CD 00 00	E	CALL FADDA	ADDED TO CALO ON APSTACK
668	0BF6	CD 00 00	E	CALL TOS4	STORED IN RAM
669	0BF9	CD 00 00	E	CALL FMUL	MULTIPLY CALD**CALRD
670	0BFC	21 0C 3E		LXI H,SUMXY+03H	ADDR OF CALD**CALRDS IN HL
671	0BFF	CD 00 00	E	CALL FADDA	CALD**CALRD+SUM OF CALD**CALRDS
672	0C02	CD 00 00	E	CALL TOS4	STORED BACK IN RAM
673	0C05	79		MOV A,E	MOVE OFFSET IN DE TO ACCUMULATOR
674	0C06	06 18		ADI 4*NCHA	INCREASE THE OFFSET TO NEXT NCALC RGE
675	0C08	5F		MOV E,A	STORE BACK IN DE
676	0C09	0D		DCR C	DECREMENT NCALC COUNTER IN C
677	0C0A	C2 AC 00		JNZ RECL2	LOOP BACK FOR NEXT CALCULATIONS & SUMS
678	0C0D	3E 04		MVI A,NCALC	DONE,LOAD NCALC INTO APSTACK & FLOAT
679	0C0F	D3 7E		OUT APDATA	NCALC SENT TO APSTACK
680	0C11	AF		XRA A	ZERO A
681	0C12	D3 7E		OUT APDATA	APSTACK HAS 16 BIT FIXED NO
682	0C14	CD 00 00	E	CALL FLTS	NCALC NOW A 32 BIT FLOATING BINARY NO
683	0C17	CD 00 00	E	CALL PTOD	2 COPIES ON APSTACK
684	0C1A	21 00 3E		LXI H,SUMX+03H	ADDR OF SUMX IN HL
685	0C1D	CD 00 00	E	CALL WRT4	SUMX 1ST ON APSTACK,NCALC 2ND,3RD
686	0C20	CD 00 00	E	CALL XCHD	NCALC 1ST,SUMX 2ND,NCALC
687	0C23	CD 00 00	E	CALL FDIV	SUMX/NCALC 1ST,NCALC 2ND
688	0C26	21 0D 3E		LXI H,XBAR	ADDR OF XBAR IN HL
689	0C29	CD 00 00	E	CALL TOS4	XBAR STORED IN RAM FROM APSTACK
690	0C2C	21 00 3E		LXI H,SUMY+03H	ADDR OF SUMY IN HL
691	0C2F	CD 00 00	E	CALL WRT4	LOADED ON APSTACK,SUMY 1ST,NCALC 2ND
692	0C32	CD 00 00	E	CALL XCHD	NCALC 1ST,SUMY 2ND
693	0C35	CD 00 00	E	CALL FDIV	SUMY/NCALC ON APSTACK
694	0C38	21 11 3E		LXI H,YBAR	ADDR OF YBAR IN HL
695	0C3B	CD 00 00	E	CALL TOS4	YBAR STORED IN RAM
696	0C3E	21 00 3E		LXI H,SUMX+03H	ADDR OF SUMX IN RAM
697	0C41	CD 00 00	E	CALL WRT4	SUMX ON APSTACK
698	0C44	CD 00 00	E	CALL PTOD	2ND COPY OF SUMX ON APSTACK
699	0C47	21 14 3E		LXI H,YBAR+03H	ADDR OF YBAR IN HL
700	0C4A	CD 00 00	E	CALL FMUL	YBAR*SUMX ON TOP OF APSTACK
701	0C4D	CD 00 00	E	CALL CNDF	-YBAR*SUMX ON APSTACK
702	0C50	21 0C 3E		LXI H,SUMXY+03H	HL ADDRESSES SUMXY

703	0C53	CD 00 00	E	CALL FADDA	SUMXY-SUM*YBAR ON TOP OF APSTACK
704	0C56	CD 00 00	E	CALL XADD	SUMX TOP OF APSTACK, SUMY-SUM*YBAR 2ND
705	0C59	21 10 3E		LXI H, XBAR+00H	ADDR OF XBAR IN HL
706	0C5C	CD 00 00	E	CALL FNULA	XBAR+SUNK TOP OF APSTACK
707	0C5F	CD 00 00	E	CALL CREF	-XBAR+SUNK TOP OF APSTACK
708	0C62	21 FC 3D		LXI H, SUNK+00H	SUNKX ADDR IN HL
709	0C65	CD 00 00	E	CALL FADDA	SUMXX-XBAR+SUNK TOS, SUMY-SUM*YBAR NEXT
710	0C68	CD 00 00	E	CALL FDIV	(SUMY-SUM*YBAR)/(SUMX-XBAR+SUNK) TOS
711	0C6B	CD 00 00	E	CALL P100	2ND COPY OF GAIN STORED
712	0C6E	3E 06		MVI A, NCHA	TOTAL NO OF CHANNELS IN A
713	0C70	90		SUB B	A-TOTAL CHA NUMBER - PRESENT COUNT IN B
714	0C71	87		ADD A	NCH*0, 4 BYTES FOR OFFSET, 4 BYTES FOR SLOP
715	0C72	87		ADD A	NCH*4 IN A
716	0C73	4F		MOV C, A	STORE A TEMP COPY OF #NCH IN C
717	0C74	87		ADD A	NCH*8 IN A
710	0C75	21 39 3C		LXI H, CRFRA+00H	HL ADDRESS 1ST BYTE OF 1ST SLOPE
719	0C78	5F		MOV E, A	D USE 0, CRFRA OFFSET MOVED TO E
720	0C79	19		ADD D	DE ADDED TO HL
721	0C7A	CD 00 00	E	CALL TOS4	SLOPE STORED IN RAM
722	0C7D	21 35 3C		LXI H, CRFRA	1ST BYTE OF 1ST OFFSET IN HL
723	0C80	19		ADD D	HL ADDRESSES OFFSET(NCH)
724	0C81	EB		MONG	TEMP STORE IN DE
725	0C82	21 10 3E		LXI H, XBAR+00H	ADDR OF XBAR IN HL
726	0C85	CD 00 00	E	CALL FNULA	GAIN=XBAR ON APSTACK
727	0C88	CD 00 00	E	CALL CREF	-GAIN=XBAR ON APSTACK
728	0C8B	21 14 3E		LXI H, YBAR+00H	YBAR ADDRESSED BY HL
729	0C8E	CD 00 00	E	CALL FADDA	YBAR-GAIN+YBAR ON APSTACK
730	0C91	EB		NCHA	HL ADDRESSES OFFSET(NCH)
731	0C92	CD 00 00	E	CALL TOS4	STORE OFFSET(NCH) IN RAM
732	0C95	79		MOV A, C	CALCULATE OFFSET AMOUNT FOR NCHS LOOP
733	0C96	C6 07		ADI 07H	OFFSET DE FOR NEXT NCHS LOOP, A=#NCH+3
734	0C98	5F		MOV E, A	DE = NCH OFFSET FOR NEXT ADDR
735	0C99	16 00		MVI D, 0	REZERO D FOR OFFSET VALUE
736	0C9B	05		DEC D	DECREMENT NCH COUNTER IN B REG
737	0C9C	C2 A1 0B		JNZ RECLP	LOOP BACK FOR NEXT CHANNEL IF NOT DONE
738	0C9F	11 2C 3E		LXI D, VOLNEW	ADDRESS IN RAM TO BE COPIED TO
739	0CA2	3A 44 3E		LMA VOLBYT	LOAD TEST BYTE INTO A
740	0CA5	FE AA		CFI GRAB	COMPARE TO AA, SEE IF TUBE STD WNS READ
741	0CA7	C2 D7 0C		JNZ RECLA	JUMP AROUND IF STD TUBE HASN'T BEEN READ
742	0CAA	0E 06		MVI C, NCHA	SET COUNTER FOR NO OF CHANNELS
743	0CAC	3A 2B 3E		LMA CLSBR	LOAD HI PART OF VOLSTD ADDR IN A
744	0CAF	07		MOV H, A	HD STORE IN H
745	0CB0	2E 77		MVI L, COLDET-COLOP-1	LOAD OFFSET TO LAST BYTE OF VOLSTD IN
746	0CB2	E5		SHR H	STORE ADDR ON STACK
747	0CB3	21 45 3E		LXI H, VOLNEW+17H	VALUE OF LAST BYTE TO BE CONNECTED
748	0CB6	11 64 3C		LXI D, CLSBR+00H	ADDR OF LAST BYTE OF SLOP
749	0CB9	CD 00 00	E	CALL FADDA	SLOP+VOLSTD ON APSTACK
750	0CBC	20		DCR H	HL ADDR OF SLOP
751	0CBD	20		DCR H	HL ADDR OF SLOP
752	0CBE	20		DCR H	INCR-1
753	0CBF	20		DCR H	HL ADDR OF SLOP
754	0CC0	E3		MHL	MOV ADDR OF 1ST BYTE OF SLOP ON STACK, SET
755	0CC1	CD 00 00	E	CALL FADDA	SLOP+VOLSTD+VOLSTD ON APSTACK
756	0CC4	CD 00 00	E	CALL CREF	VOLSTD-COLOP-VOLSTD ON APSTACK

757	0CC7	2B			DCX H	ADDR OF VOLSTDS+3 IN HL
758	0CC8	E3			XTHL	STORED BACK FOR NEXT ROUND, ADDR OF OFSE, 1ST
759	0CC9	CD 00 00	E		CALL TOS4	STR VOLSTDS-(SLOPG*VOLNEWS) AS NEW OFFSET
760	0CCC	1B			DCX D	DE ADDR VOLNEWS+3
761	0CCD	EB			XCHG	HL ADDR VOLNEWS, DE ADDR 4TH BYTE OF OFSE
762	0CCE	1B			DCX D	
763	0CCF	1B			DCX D	
764	0CD0	1B			DCX D	
765	0CD1	1B			DCX D	DE ADDR SLOPG+3
766	0CD2	0D			DCR C	CHECK COUNTER IN C
767	0CD3	C2 09 0C			JNZ RECL3	CALCULATE NEXT CORR FACTOR IF NOT DONE
768	0CD6	E1			POP H	GET STACK BACK RIGHT
769	0CD7	21 35 3C		RECL4	LXI H, CRFRA	WILL PRINT OUT CORRECTION FACTORS, OFFSET, SL
770	0CDA	11 06 02			LXI D, 0206H	PRINT 2 PER LINE, 6 LINES
771	0CDD	01 05 0A			LXI B, 0A05H	LOAD FIXED FORMAT, 10 DIGITS, 6 AFTER DEC
772	0CE0	CD 00 00	E		CALL PRINT	PRINT IN FIXED FORMAT
773	0CE3	CD 00 00	E		CALL CROUT	CALL CARRIAGE RETURN, LINEFEED
774	0CE6	0E 05			MVI C, 0C0A	MULTIPLY SLOPE BY CONVER FACTOR
775	0CE8	21 3C 3C			LXI H, CRFRA+07H	1ST SLOPE ADDR IN HL
776	0CEB	11 59 12		RECL5	LXI D, CRFRD+07H	CON FACT=5/(4095*NRDG)
777	0CEE	CD 00 00	E		CALL FMULD	CRFRA*5/(4095*NRDG) ON ASTACK
778	0CF1	EB			XCHG	XCHANGE HL&DE, B SUFFIX CALL REVERSED
779	0CF2	CD 00 00	E		CALL TOS4	SAVE NEW CORRFACOR IN RAM
780	0CF5	11 08 00			LXI D, 08H	ADD 8 TO ADDR OF HL
781	0CF8	19			DAD D	HL=ADDR OF NEXT SLOPE
782	0CF9	0D			DCR C	DECREMENT CHANNEL COUNT IN C, SEE IF WE ARE
783	0CFA	C2 EB 0C			JNZ RECL5	JUMP BACK IF NOT DONE
784	0CFD	AF			XRA A	ZERO ACC SO MAIN LOOP WILL RUN CORRECT
785	0CFE	C9			RET	RETURN TO CALLING ROUTINE
786			:			
787			:		DACON1	PROGRAM TO WRITE DATA OUT TO DIGITAL
788			:			TO ANALOG CONVERTERS, DATA STORED AT PROPA
789			:			IS MULTIPLIED BY DAFAC AND OUTPUTTED, CHANN
790			:			ADDRESSED BY VALUE AT POSCH IS ADDED TO TH
791			:			FORMER RDG FOR THAT CHANNEL & OUTPUTTED
792			:			
793	0CFF	21 19 3E		DACON1	LXI H, PROPA+3	ADDR OF PROPERTY TO BE CALCULATED
794	0D02	11 59 12			LXI D, DAFAC+3	DE CONTAIN CONVERSION FACTOR ADDR
795	0D05	CD 00 00	E		CALL FMULB	FLOATING MULTIPLICATION PERFORMED
796	0D08	CD 00 00	E		CALL FIXS	CONVERTED NO FIXED
797	0D0B	21 66 3C			LXI H, DACOFFS+1	LOAD ADDRESS OF OFFSET INTO HL
798	0D0E	3A 5F 3E			LDA DACCH	LOAD DAC CHANNEL NO INTO A
799	0D11	87			ADD A	DOUBLE A
800	0D12	5F			MOV E, A	MOVE ADDR OFFSET TO E
801	0D13	16 09			MVI D, 0	DE CONTAINS OFFSET
802	0D15	19			DAD D	INCREMENT HL BY 2*DACCH
803	0D16	CD 00 00	E		CALL SADDA	ADD OFFSET
804	0D19	CD 00 00	E		CALL PTOS	SAVE A COPY OF NEW RDG ON ASTACK
805	0D1C	2A 5D 3E			LRLD POSOAD	LOAD ADDR FOR OLD RDGS
806	0D1F	CD 00 00	E		CALL SADDA	ADD NEW VAL TO OLD, RESULT ON ASTACK
807	0D22	23			INX H	INCREMENT HL THREE TIMES
808	0D23	23			INX H	CONTAINS VALUE OF ADDR OF
809	0D24	23			INX H	NEXT OLD RDG
810	0D25	22 5D 3E			SHLD POSOAD	STORE FOR NEXT TIME

811	0D28	DB 7E		IN APDATA	HI ORDER BYTE FROM APSTACK TO A REG
812	0D2A	FE 00		CPI 000H	IF HI BYTE,GE. 00H NUMBER IS NEG
813	0D2C	D2 65 0D		JHD D7AH	SET DATA TO MINIMUM VALUE (0)
814	0D2F	FE 10		CPI 000H	IF HI BYTE,GE. 10,NUMBER,GT.4000
815	0D31	D2 6D 0D		JHD D7AH	SET DATA TO 4000 (0000/1111 1111/1111)
816	0D34	D3 FC	DAL 12	OUT PORTIC	OUTPUTTED TO PORTIC,DAC LINES
817	0D36	FE 07		CPI 07H	COMPARE HI ORDER BYTE TO 0000/0111;1792 DE
818	0D39	D4 7A 0D		CNC ALARM	SET ALARM BIT IF DAC VAL. GE. 1792(44 MILS)
819	0D3B	DB 7E		IN APDATA	LOW ORDER BYTE FROM APSTACK TO A REG
820	0D3D	D3 F4		OUT PORTIC	LATCHED ON PORTIC,DAC LINES
821	0D3F	2A 5B 3E		LHLD POSCH	LOAD ADDRESS OF NEW RDGS IN HL
822	0D42	CD 00 00	E	CALL TUSA	SAVE NEW CALL AS OLD VALUE
823	0D45	20		DCX H	DECREMENT HL TWICE TO ADDRESS
824	0D46	20		DCX H	HI BYTE OF NEXT NEW RDG
825	0D47	20		DCX H	
826	0D49	22 5B 3E		SHLD POSCH	SAVE AS NEW ADDR
827	0D4B	3A 5F 3E		LDA DACCH	LOAD DAC CHANNEL NUMBER INTO A
828	0D4E	3C		INR A	INCREMENT DAC CHANNEL NO
829	0D4F	32 5F 3E		STA DACCH	STORE BACK IN RAM
830	0D52	3D		DCR A	DECREMENT A,BACK TO ORIG CH COUNT
831	0D53	FE 05		CPI 05	SEE IF IT IS LARGER THAN 5
832	0D55	D4 76 0D		CNC DACSET	USE VALUE OF POSCH IF DACCH<=5
833	0D58	C6 05		MVI 000H	ADD 1000/0000,EL,0000 SELECTED,TR HI
834	0D5A	D5 F3		OUT PORTIB	CONTROL LINES SET FOR DAC
835	0D5C	3E 60		MVI 0,000H	STROBE DACS LO,THEN HI
836	0D5E	D3 EE		OUT PORTIC	DAC LOAD ON PORTIC
837	0D60	3E 70		MVI 0,070H	TAKE 0111/0000 HI
838	0D62	D3 EE		OUT PORTIC	
839	0D64	C9		RET	RETURN TO CALLING ROUTINE
840	0D65	D0 7E	D7AH	IN APDATA	CLEAR LOW ORDER BYTE OUT OF AP
841	0D67	AF		MVA A	ZERO ACCUMULATOR
842	0D68	D3 7E		OUT APDATA	ZERO 2ND BYTE IN APSTACK
843	0D6A	C3 34 0D		JMP ALARM	GO BACK AND OUTPUT ZERO
844	0D6D	D0 7E	D7AH	IN APDATA	CLEAR LOW ORDER BYTE OUT OF AP
845	0D6F	3E FF		MVI A,0FFH	SET ACC ALL ONES
846	0D71	D3 7E		OUT APDATA	SET 2ND BYTE IN APSTACK TO ONES
847	0D73	C3 34 0D		JMP DALF2	GO BACK AND OUTPUT MAX VALUE(4095)
848	0D76	3A 45 3E	DACSET	LDA POSCH	LOAD VALUE OF POSITION CHANNEL INTO A
849	0D79	C9		RET	
850	0D7A	3E 40	ALARM	MVI A,040H	SET DG,0100/0000
851	0D7C	32 60 3E		STA ALADD	STORE IN ALARM ADDRESS
852	0D7F	C9		RET	
853					
854				NEED0	CALCULATES ORNSU=0FOLD*0F0-(0IOLD*-
					BINSU)*.5 USED TO PUT ACC OUT AT .020
855	0D80	21 5A 3E	NEED0	LXI H,D80LD+2*POSCH+1	
856	0D83	22 5D 3E		SHLD POSCH	STORED FOR NEW RDGS ADDR
857	0D86	21 4B 3E		LXI H,D80LD+1	LO ORDER BYTE OF 1ST RDG
858	0D89	22 5D 3E		SHLD POSCH	STORED FOR OLD ADDR ADDR
859	0D8C	AF		MVA A	ORIG ACCUMULATOR
860	0D8D	32 5F 3E		STA DACCH	LOAD DAC CHANNEL NUMBER
861	0D90	2A 5D 3E	NEED1	LHLD POSCH	LOAD ADDR FOR OLD RDGS
862	0D93	ED		INLD	MOVE TO DE
863	0D94	2A 5D 3E		LHLD POSCH	LOAD ADDR FOR NEW RDGS
864	0D97	CD 69 0D	E	CALL SADD	ADD NEW TO OLD RDGS

865	0D9A	23		INX H	OLD ADDR COUNTS UP-INCREMENT 3X
866	0D9B	23		INX H	
867	0D9C	23		INX H	
868	0D9D	22 5D 3E		SHLD POSDAD	STORE BACK IN RAM
869	0DA0	EB		MCRG	SWITCH NEW ADDR INTO HL
870	0DA1	2B		DCX H	DECREMENT NEW ADDR COUNTS DOWN
871	0DA2	22 5D 3E		SHLD POSNAD	RESTORE NEW POSITION ADDRESS
872	0DA5	3E 02		MVI A,02H	LOAD 2 INTO APSTACK
873	0DA7	D3 7E		OUT APDATA	
874	0DA9	AF		RRA A	
875	0DAA	D3 7E		OUT APDATA	
876	0DAC	CD 00 00	E	CALL SDIV	DIVIDE SUM OF OLD&NEW RDG BY 2
877	0DAF	CD 00 00	E	CALL CHSS	CHANGE AVERAGE TO NEGATIVE
878	0DB2	3A 5F 3E		LDA DACCH	LOAD DAC CHANNEL NO INTO A
879	0DB5	07		ADD A	DOUBLE A
880	0DB6	21 03 12		LXI H,DACOFF+1	BASE ADDR OF DAC ZERO OFFSETS
881	0DB9	5F		MOV E,A	MOVE ADDR OFFSET TO E
882	0DBA	16 00		MVI D,0	DE CONTAINS OFFSET
883	0DBC	19		INR D	INCREMENT HL BY 2*DACCN
884	0DBD	CD 00 00	E	CALL SADDA	APSTACK =DACOFF+DSUM/2
885	0DC0	21 66 3C		LXI H,DACOFF+1	BASE ADDR OF OLD DACOFFSET RDGS
886	0DC3	19		INR D	INCREMENT BY CHANNEL COUNT
887	0DC4	CD 00 00	E	CALL SADDA	APSTACK=DACOFFOLD+DACOFF+DSUM/2
888	0DC7	CD 00 00	E	CALL TOSZ	SAVE NEW DACOFFSET AT PROPER RAM ADDR
889	0DCA	3A 5F 3E		LDA DACCH	
890	0DCD	FE 09		CPI POSCHN	COMPARE TO NO OF POSITION CHS
891	0DCF	D0		RNC	RETURN IF COUNT.GE.NO POS CHS
892	0DD0	3C		INR A	INCREMENT CHANNEL COUNT
893	0DD1	32 5F 3E		STA DACCH	STORE BACK IN RAM
894	0DD4	C3 90 0D		JMP REZRL1	LOOP BACK UNTIL DONE
895			:		
896			:	CARRET	HANG HERE UNTIL A CARRIAGE RETURN IS TYPED
897			:		
898	0DD7	CD 00 00	E	CARRET	CALL GETCH
899	0DDA	CD 00 00	E		CALL ECHO
900	0DDD	79		MOV A,C	STICK IT IN A
901	0DDE	FE 0D		CPI CR	SEE IF IT WAS A CARRIAGE RETURN
902	0DE0	C2 D7 0D		JNZ CARRET	LOOK AGAIN IF NOT
903	0DE3	C9		RET	RETURN IF IT WAS
904			:		
905			:	DACALB	PROGRAM TO CALIBRATE DAC'S
906			:		
907	0DE4	3E 77		DACALB	MVI A,077H
908	0DE6	D3 E0			OUT PORT2D
909	0DE0	3E 00			MVI A,PORT10
910	0DEA	D3 F7			OUT PORT1
911	0DEC	21 15 3E			LXI H,PROPA
912	0DEF	0E 00			MVI C,4*PROPN
913	0DF1	AF			RRA A
914	0DF2	CD 00 00	E		CALL ZERO
915	0DF5	21 09 00			LXI H,POSCHN
916	0DF8	22 45 3E			SHLD POSCH
917	0DFB	21 59 3E			LXI H,DACOLD+2*POSCHN
918	0DFE	22 5B 3E			SHLD POSDAD

919	0E01	21 48 3E		LXI H,DAOLD+1	LO ORDER BYTE OF 1ST RDG
920	0E04	22 5D 3E		SHLD POSOAD	STORED FOR OLD ADDR RDGS
921	0E07	21 0F FF		LXI H,OFFOPH	LOAD MAX VALUE IN HL
922	0E0A	22 61 3E		SHLD THMIN	STORE 4995 AS MINIMUM THICKNESS
923	0E0D	AF		XRA A	ZERO ACCUMULATOR
924	0E0E	32 5F 3E		STA DACCH	ZERO DAC CHANNEL NUMBER
925	0E11	CD FF 6C	DACAL1	CALL DACONI	CONVERT TO ANALOG & SEND TO RECORDER
926	0E14	21 10 3E		LXI H,PROPA+3	ADDRESS OF CALIBRATION PROP IN HL
927	0E17	CD 4E 0E		CALL DACONS	SEND TO CHANNEL ?
928	0E1A	21 45 3E		LXI H,POSCH	LOAD HL WITH CHANNEL POSITION INDEX
929	0E1D	35		DCR H	DECREMENT INDEX
930	0E1E	F2 11 0E		JP DACAL1	LOOP BACK FOR ALL POSITION CHANNELS
931	0E21	21 18 3E		LXI H,PROPA+3	PRINT DECIMAL VALUE OF PROPERTIES
932	0E24	CD 00 00	E	CALL MATH	
933	0E27	CD 00 00	E	CALL PTDD	PUP TOP OF STACK,SET STATUS BITS
934	0E2A	01 03 05		LXI B,000H	ON TERMINAL
935	0E2D	CD 00 00	E	CALL PRINTF	
936	0E30	21 43 12		LXI H,DACCH	DAC CALIB MSG IN HL
937	0E33	06 07		MVI B,LDACNS	LENGTH OF MESSAGE IN B
938	0E35	CD 4D 0F		CALL MSGOUT	PRINT MESSAGE ON TERMINAL
939	0E38	21 18 3E		LXI H,PROPA+3	
940	0E3B	11 05 12		MVI B,THMIN+5	INCREMENT PROPERTY RDGS BY TEN MILS
941	0E3E	CD 00 00	E	CALL PRDD	ADD 0.01 TO VALUES
942	0E41	EB		XORG	HL ADDRESSES PROPA
943	0E42	CD 00 00	E	CALL RASH	SAVE PROPA+0.01 IN RAM
944	0E45	CD D7 0D		CALL GARRET	HANG UP UNTIL A CR IS TYPED
945	0E48	C3 F5 0D		JMP DACCL2	
946			:		
947			:	DACCH2	END DAC PROG.,CAL LACK-OF-PENETRATION
948			:		MINIMUM VALUE STORED AS THMIN.
949			:		OUTPUT AND RESET EACH CHANNELS ARE RESEY
950			:		
951	0E49	21 1C 3E	DACCH2	LXI H,PROPA+7	ADDR OF 2ND PROPERTY TO BE CALCULATED
952	0E4E	11 9D 12	DACONS	LXI B,DAPAC2+5	BE CONTAIN 2ND CONVERSION FACTOR ADDR
953	0E51	CD 00 0A	E	CALL FIMLB	FLOATING MULTIPLICATION PERFORMED
954	0E54	CD 00 00	E	CALL FINS	CONVERTED NO FIXED
955	0E57	CD 00 00	E	CALL PTDS	SAVE A COPY OF NEW RDG ON ASTACK
956	0E5A	21 62 3E		LXI H,MINH+1	ADDR OF MINIMUM RDG IN HL
957	0E5D	CD 00 00	E	CALL NSUCH	CUR VAL-THMIN ON ASTACK
958	0E60	DB 7E		IN APTDTH	HI ORDER OR BYTE IN A
959	0E62	FE 83		ORI 000H	IF HI BYTE,GE,00H,CUR VAL<LT,THMIN
960	0E64	DB 7E		IN APTDTH	FLUSH LOW BYTE
961	0E66	D4 00 00	E	CDC TH32	COPY NEW MIN INTO THMIN IF NEW VAL LESS
962	0E69	3A 45 3E		LDA POSCH	LOAD A WITH POSITION CHANNEL NO.
963	0E6C	3D		DCR A	DECREMENT A
964	0E6D	F0		RP	RETURN IF POS:POSCH WASN'T ZERO
965	0E6E	21 61 3E		LXI H,THMIN	ADDR OF MIN THICKNESS INTO HL
966	0E71	7E		MVI A,H	HI ORDER BYTE LOADED INTO A
967	0E72	D3 F6		OUT PORTIC	OUTPUTTED TO PORTIC,DAC LINES
968	0E74	FE 04		ORI 04H	COMPARE TO 0004/0100,SET ALARM
969	0E76	DC 7A 0D		DC ALARM	IF L-OP,LE,00 MILS.
970	0E79	23		INX H	INCREMENT COUNTER
971	0E7A	7E		MVI A,H	LO ORDER BYAL PRINTED
972	0E7D	D3 F4		OUT PORTIC	LATCHED ON PORTIC,DAC LINES

973	0E7D	3E 07		MVI A,0E7H	VALUE FOR ADC CH 7
974	0E7F	D3 F5		OUT PORT1B	CONTROL LINES SET FOR DAC
975	0EB1	3E 60		MVI A,0E0H	STROBE DACS LO, THEN HI
976	0E83	D3 EE		OUT PORT2C	DAC LOAD ON PORT2C
977	0E85	3E 70		MVI A,070H	TAKE 0111/0000 HI
978	0E87	D3 EE		OUT PORT2C	
979	0E89	C9		RET	RETURN TO CALLING ROUTINE
980			:	DACONS	PROGRAM TO DRIVE ADC/DACS
981			:		FOR WELD REPAIR INSPECTION
982			:		
983	0E8A	21 24 3E		LXI H,PROPA+15	LAST BYTE OF CAL PROP=PROPA+4*PROPN+7
984	0E8D	0E 04		MVI C,PROPN+2	REG C CONTAINS NO OF PROPS FOR SQRWLD
985	0E8F	06 00		MVI B,00H	REG BC CONTAINS PROP NO INDEX
986	0E91	11 9D 12	DALPS1	LXI D,DACCF2+3	DE CONTAINS CONVERSION FACTOR INDEX ***
987	0E94	CD 00 00	E	CALL FNU0B	FLOATING MULTIPLY PERFORMED
988	0E97	CD 00 00	E	CALL FIX0B	CONVERTED TO FIXED NO
989	0E9A	21 0D 12		LXI H,DACCF+11	LOAD ADDR OF OFFSETS (START AT 7TH) IN HL
990	0E9D	09		DAD B	DACCF+11+2*PROPN IN HL
991	0E9E	09		DAD B	STORED AS PROPN1,PROPN2,... VAL*01000
992	0E9F	CD 00 00	E	CALL SADD0	SUBTRACT OFFSET
993	0EA2	DB 7E		IN APDATA	HI ORDER BYTE FROM APSTACK TO A REG
994	0EA4	FE 00		CPI 000H	IF HI BYTE.GE. 00H NUMBER IS NEG
995	0EA6	D2 C9 0E		JNC DTMIN5	SET DATA TO MINIMUM VALUE (0)
996	0EA9	FE 10		CPI 010H	IF HI BYTE.GE. 10,NUMBER>ST.4095
997	0EAB	D2 D1 0E		JNC DTMAX5	SET DATA TO 4095 (0000/1111 1111/1111)
998	0EAE	D3 F6	DALPS2	OUT PORT1C	OUTPUT TO DAC LINES
999	0EB0	DB 7E		IN APDATA	LOW ORDER BYTE LOADED FROM APSTACK
1000	0EB2	D3 F4		OUT PORT1A	OUTPUT TO LOW ORDER DAC LINES
1001	0EB4	79		MOV A,C	LOAD CH NO IN A
1002	0EB5	3D		DCR A	CH COUNT STARTS AT 0
1003	0EB6	C6 00		ADI 000H	ADD 1000/000,01,03040 SELECTED,TR HI
1004	0EB9	D3 F5		OUT PORT1B	CONTROL LINES SET FOR DAC
1005	0EBA	3E 60		MVI A,0E0H	STROBE DACS LO, THEN HI
1006	0EBC	D3 EE		OUT PORT2C	DAC LOAD ON 2C
1007	0EBE	3E 70		MVI A,070H	TAKE 0111/0000 HI
1008	0EC0	D3 EE		OUT PORT2C	
1009	0EC2	EB		XCHG	EXCHANGE HL&DE(FNU0B EXCHANGED ONCE)
1010	0EC3	2B		DCX H	HL DECREMENTED FOR NEXT PROPERTY
1011	0EC4	0D		DCR C	PROPERTY NUMBER COUNTER DECREMENTED
1012	0EC5	C2 91 0E		JNZ DALPS1	LOOP BACK IF NOT DONE
1013	0EC8	C9		RET	RETURN IF DONE
1014	0EC9	D0 7E	DTMIN5	IN APDATA	CLEAR LOW ORDER BYTE OUT OF AP
1015	0ECD	AF		XRA A	ZERO ACCUMULATOR
1016	0ECC	D3 7E		OUT APDATA	ZERO 2ND BYTE IN APSTACK
1017	0ECE	C3 AE 0E		JMP DALPS2	GO BACK AND OUTPUT ZERO
1018	0ED1	D0 7E	DTMAX5	IN APDATA	CLEAR LOW ORDER BYTE OUT OF AP
1019	0ED3	3E FF		MVI A,0FFH	SET ACC ALL ONES
1020	0ED5	D3 7E		OUT APDATA	SET 2ND BYTE IN APSTACK TO ONES
1021	0ED7	C3 AE 0E		JMP DALPS2	GO BACK AND OUTPUT MAX VALUE(4095)
1022			:		
1023			:	OUTLIF	PROGRAM TO OUTPUT LIFTOFF
1024			:		EVERY F TIMES,BELL RINGS IF LIFTOFF
1025			:		IS BELOW LIFMIN.
1026			:		

1027			;OUTLIF	LHLD COUNT	COUNT NUMBER LOADED INTO HL
1028			:	MOV A,H	LAST BYTE OF COUNT NO LOADED INTO ACC
1029			:	ANI 0FH	DUMP 4 HI ORDER BITS
1030			:	RZC	RETURN IF NOT ZERO
1031			:	LXI H,PROG4+11	ADDR OF LIFTOFF IN HL
1032			:		
1033			:	RDSTD	PROGRAM READS NOMINAL TUBE STD
1034			:		STORES DATA IN RAM AT VOLNEW.SETS VSTBYT=A
1035			:		
1036	0EDA	3E 99	RDSTD	MVI A,PR11	LOAD PROGRAM WORD FOR A&C INPUT,B OUTPUT
1037	0EDC	D3 F7		OUT PORT1	SEND TO PORT 1
1038	0EDE	3E 90		MVI A,0DCH	LOAD PROGRAM WORD,A=INPUT,B&C=OUTPUT
1039	0EE0	D3 EF		OUT PORT2	SEND TO PORT2.
1040	0EE2	3E 79		MVI A,070A	SET P&S TAPE READ,WRITE,D&C LATCH HI
1041	0EE4	D3 EE		OUT PORT2C	LEAVE STROBE LINES HI
1042	0EE6	3E 07		MVI A,0711	SET CALIBRATOR RELAYS FOR PROBE RDGS
1043	0EE8	D3 ED		OUT PORT2D	SET CALIBRATOR ADDRESSES
1044	0EEA	01 08 00		LXI B,0800	LOAD DELAY FOR DC
1045	0EEB	CD 00 00		CALL DELAY	DELAY FOR 150 NS TO ALLOW RDGS TO SETTLE
1046	0EF0	CD 00 00		CALL DELAY	DELAY FOR 150 NS TO ALLOW RDGS TO SETTLE
1047	0EF3	06 00		MVI B,000H	MAKE 128 READINGS OF THE STANDARDS
1048	0EF5	0E 05		MVI C,06H	READ 6 CHANNELS
1049	0EF7	CD AE 0A		CALL SHDRT	DATA SUMMED & STORED
1050	0EFA	0E 06		MVI C,06	5 RAW DATA WORDS WILL BE FLOATED & CONVYTD
1051	0EFC	11 40 3E		LXI D,VOLNEW+14H	
1052	0EFF	21 32 3C		LXI H,RAWDA+17H	HL=LAST RAW DATA VALUE,LAST BYTE
1053	0F02	CD 00 00	E	CALL FLTDA	FLOAT DOUBLE WORD
1054	0F05	E5		PUSH H	STORE ADDR ON STACK
1055	0F06	21 51 12		LXI H,CALSR+3	ADDR OF CALIBRATION STANDARD FACTOR LOADED
1056	0F09	CD 00 00	E	CALL FLDLA	SPSTACK =VOLNEW
1057	0F0C	EB		XCHG	ADDR OF VOLNEW IN HL
1058	0F0D	CD 00 00	E	CALL TUS4	STORED IN RAM
1059	0F10	11 F9 FF		LXI D,0FFFFH-6	SUBTRACT 6 FROM HL
1060	0F13	19		DAD D	HL= ADDR OF NEXT VOLNEW WORD
1061	0F14	EB		XCHG	STORED IN DE
1062	0F15	E1		POP H	
1063	0F16	2B		DCX H	HL ADDR NEXT RAW DATA WORD
1064	0F17	0D		DCR C	DECREMENT C COUNTER
1065	0F18	C2 02 0F		JNZ RDSTD	
1066	0F1B	01 04 03		LXI B,000AH	B,C=XXXX,XXXX PRINT FORMAT
1067	0F1C	11 01 00		LXI D,000H	PRINT 6 PER LINE,1 LINE
1068	0F21	21 2C 3E		LXI H,VOLNEW	PRINT VALUES READ FOR VOLNEW ON TERM
1069	0F24	CD 00 00	E	CALL PRINT	
1070	0F27	3E AA		MVI A,0AAH	
1071	0F29	32 44 3E		STA VSTBYT	SET VSTBYT=AA,SHOW THAT STANDARD HAS BEEN
1072	0F2C	C3 00 00	E	JMP GETCH	RETURN TO DIGITOR
1073			:		
1074			:	PCALP	PROGRAM TO PRINT CALCULATED
1075			:		PROPERTIES
1076			:		
1077	0F2F	2A 19 3C	PCALP	LHLD COUNT	LOAD COUNT NUMBER FROM RAM
1078	0F32	7C		MOV A,H	MOVE TO ACCUMULATOR
1079	0F33	CD 00 00	E	CALL PRINT	PRINT HI 16N BYTE
1080	0F36	7D		MOV A,L	MOVE LOW BYTE TO ACC

1081	0F37	CD 00 00	E	CALL NMOUT	PRINT OUT
1082	0F3A	0E 20		MVI C,000H	LOAD A SPACE
1083	0F3C	CD 00 00	E	CALL CD	PRINT A SPACE
1084	0F3F	21 15 3E		LXI H,PROPA	1ST PROP CAL IN HL
1085	0F42	16 02		MVI D,PROPA	LOAD NUMBER PER LINE INTO D
1086	0F44	1E 01		MVI E,01	LOAD 1 LINE INTO C
1087	0F46	01 04 00		LXI B,0004H	LOAD FORMAT IN BC
1088	0F49	CD 00 00	E	CALL PRINT	PRINT PROP NOS IN 00.4 FORMAT
1089	0F4C	C9		RET	RETURN TO CALLING PROGRAM
1090			:		
1091			:	MSGOUT	ROUTINE TO PRINT ASCII ON TTY
1092			:		ADDR OF MESSAGE IN HL, LENGTH IN CHARS IN B
1093			:		
1094	0F4D	4E		MSGOUT	MOV C,M
1095	0F4E	CD 00 00	E	CALL CD	GET NEXT CHAR
1096	0F51	23			INX H
1097	0F52	05		DCR B	POINT TO NEXT CHAR
1098	0F53	C2 4D 0F		JNZ MSGOUT	UPDATE BYTE COUNTER
1099	0F56	C9		RET	KEEP GOING UNTIL B=0
1100			:		RETURN TO CALLER
1101			:		
1102			:		
1103			:	WRTAP	PROGRAM TO WRITE DATA ON MAG TAPE
1104			:		DATA IS WRITTEN FROM BC THROUGH DE ON THE TAPE
1105	0F57	3E 06		WRTAP	USE DAC LOAD & 0205 LHIP ADDR.
1106	0F59	D3 F5			SELECT TAPE DRIVE,SET UP FOR WRITE
1107	0F5B	2A 63 3E			SEND TO PORT 10
1108	0F5E	0A		WRTLP	LOAD BYTE COUNT FOR MAG TAPE IN HL
1109	0F5F	D3 F4			LOAD BYTE ADDR BY BC INTO A
1110	0F61	CD 02 0F			SEND OUT TO TAPE DATA
1111	0F64	D2 5E 0F			STROBE ANOTHER BYTE OUT TO TAPE
1112	0F67	22 63 3E			LOOP BACK IF NOT DONE
1113	0F6A	C9			STORE BYTE COUNT BACK IN RAM
1114			:		RETURN TO CALLING ROUTINE WHEN DONE
1115			:		
1116			:	RDTAP	PROGRAM TO READ DATA FROM TAPE INTO RAM
1117			:		FROM DC THROUGH DE
1118	0F6B	2A 63 3E		RDTAP	GET BYTE COUNT FOR MAG TAPE INTO HL
1119	0F6E	DB DC		RDTAPL	IN PORT10
1120	0F70	02			READ DATA FROM TAPE
1121	0F71	CD 02 0F			STORE A IN RAM ADDR BY BC
1122	0F74	D2 5E 0F			STROBE TAPE TO READ
1123	0F77	22 63 3E			LOOP BACK IF NOT DONE
1124	0F7A	C9			STORE BYTE COUNT IN RAM
1125			:		RETURN TO CALLING ROUTINE WHEN DONE
1126			:		
1127			:	WRTAPE	FAST VERSION OF WRITE TAPE,USED FOR PATH R
1128	0F7B	3E 06		WRTAPE	SELECT TAPE DRIVE,SET UP FOR WRITE
1129	0F7D	D3 F5			SEND TO PORT 10
1130	0F7F	2A 63 3E			LOAD BYTE COUNT FOR MAG TAPE IN HL
1131	0F82	0A		WRTLFF	LOAD BYTE ADDR BY BC INTO A
1132	0F83	D3 F4			LOAD BYTE ADDR BY BC INTO A
1133	0F85	CD 02 0F			SEND OUT TO TAPE DATA
1134	0F88	0A			STROBE ANOTHER BYTE OUT TO TAPE

1135	0F89	D3 F4	OUT PORT1A	SEND OUT TO TAPE DATA
1136	0F8D	CD D2 0F	CALL STBTAP	STROBE ANOTHER BYTE OUT TO TAPE
1137	0F9E	03	INX B	INCREMENT BC COUNTER TWICE,SKIP
1138	0F8F	03	INX B	TWO RAM LOCATIONS
1139	0F90	D2 02 0F	JRC WRTLFF	LOOP BACK IF NOT DONE
1140	0F93	22 63 3E	SHD BYCNT	STORE BYTE COUNT BACK IN RAM
1141	0F96	C9	RET	RETURN TO CALLING ROUTINE WHEN DONE
1142				
1143			RDRAPP	FAST VERSION OF READ TAPE,USED FOR MAIN RU
1144				
1145	0F97	2A 63 3E	RDRAPP	GET BYTE COUNT FOR TWO TAPE INTO HL
1146	0F9A	D8 DC	IN PORTEA	READ DATA FROM TAPE
1147	0F9C	02	STAX B	STORE A IN RAM ADDR BY DC
1148	0F9D	CD B2 0F	CALL STBTAP	STROBE TAPE TO READ
1149	0FA0	D8 DC	IN PORTA	READ DATA FROM TAPE
1150	0FA2	02	STAX B	STORE A IN RAM ADDR BY DC
1151	0FA3	AF	XRA A	ZERO A,WILL ZERO NEXT 2 RAM LOCS
1152	0FA4	03	INX B	INCREMENT BC COUNTER
1153	0FA5	02	STAX B	ZERO RAM LOCATION
1154	0FA5	03	INX B	INCREMENT BC COUNTER
1155	0FA7	02	STAX B	ZERO RAM LOCATION
1156	0FA8	CD D2 0F	CALL STBTAP	STROBE TAPE TO READ
1157	0FAB	D2 9A 0F	JRC RDTFL	LOOP BACK IF NOT DONE
1158	0FAE	22 63 3E	SHD BYCNT	STORE BYTE COUNT IN RAM
1159	0FB1	C9	RET	RETURN TO CALLING ROUTINE WHEN DONE
1160				
1161			SYBTAP	STROBE TAPE TO READ OR WRITE,CARRY SET LINE
1162				
1163	0FB2	AF	STBTAP	STROBE AND LINE LD,TRSH HI
1164	0FB3	D3 EE	OUT PORTC	
1165	0FB5	3E 10	MVI A,10H	
1166	0FB7	D3 EE	OUT PORTC	
1167	0FB9	23	INX H	ADD ONE BYTE TO THE BYTE COUNT
1168	0FBA	03	INX B	INCREMENT BC COUNTER
1169	0FBB	7B	RAY A,E	TEST TO SEE IF BC.GT.DE
1170	0FBC	91	SUB C	SUBTRACT DC FROM DE,GET A BORROW WHEN
1171	0FBD	7A	RAY A,D	DC.GT.DE(CARRY IS SET)
1172	0FBE	98	SUB B	
1173	0FBF	C9	RET	
1174				
1175			RDLTAP	READS RAW DATA FROM MAG TAPE &
1176				CALCULATES PROPS, THEN DISPLAYS THEM ON
1177				THE TERMINAL.
1178				
1179	0FC0	3E 08	RDLTAP	SET PORTS FOR DAD OUTPUT
1180	0FC2	D3 F7	OUT PORT1	SEND CONTROL WORD TO PORT 1
1181	0FC4	3E 05	MVI A,05H	SELECT TAPE ACTIVE,SET UP FOR READ
1182	0FC6	D3 F5	OUT PORT1	WORD TO PORT 1
1183	0FC8	21 00 00	MVI H,0000H	INIT BYTE COUNT TO 00 00 00 IN INTEGER
1184	0FCD	22 63 3E	SHD BYCNT	BRACK UP COUNTER FOR KEEP THE 00'S STRG
1185	0FCE	21 00 11	MVI H,0001H	ADDRESS OF THE FIRST MESSAGE
1186	0FD1	06 1C	MVI D,0006H	LENGTH OF FIRST MESSAGE
1187	0FDC	CD 4D 0F	CALL PRINT	PRINT MESSAGE
1188	0FDE	CD 0F 11	CALL READ	READ TITLE FROM TAPE(IST LINE)

1189					
1190				FILEPR	FILE PROCESSOR PROGRAM SKIPS TO GIVEN RECD
1191					STARTS PROCESSING THE FILE
1192					
1193	0FD9	21 01 12	PROPPR	LXI H,PROPR	PROMPT FOR PROPERTY TO BE DISPLAYED
1194	0FDC	06 22		MVI B,LPROPR	LENGTH OF PROMPT
1195	0FDE	CD 4D 0F		CALL MSGOUT	
1196	0FE1	0E 01		MVI C,01H	
1197	0FE3	CD 00 00	E	CALL GETNM	GET HEX NO FROM TERMINAL
1198	0FE6	E1		POP H	RESTORE PROP NO TO HL
1199	0FE7	22 6A 3E		SHLD HPROP	STORE PROPERTY NO TO BE CALCULATED IN RAM
1200	0FEA	01 99 3D		LXI B,CALRD	LOAD ADDR OF CALB RDGS IN BC
1201	0FED	11 F0 3D		LXI D,CALRD+05FH	50H BYTES OF CALB RDGS TO BE STORED
1202	0FF0	CD 6B 0F		CALL RDTAP	DATA FROM BC THROUGH DE STORED
1203	0FF3	CD 00 00		CALL PRCALB	PRINT CALIBRATION READINGS
1204	0FF6	01 35 3C		LXI B,CRFRA	ADDRESS OF CORRECTION FACTORS IN BC
1205	0FF9	11 64 3C		LXI D,CRFRA+02FH	LAST CRFRA ADDR IN DE
1206	0FFC	CD 6B 0F		CALL RDTAP	CORRECTION FACTORS FROM RECALIB ON TAPE
1207	0FFF	21 35 3C		LXI B,CRFRA	WILL PRINT OUT CORRECTION FACTORS,OFFSET,SL
1208	1002	11 06 02		LXI D,0200H	PRINT 2 PER LINE,6 LINES
1209	1005	01 06 0A		LXI B,0000H	LOAD FIXED FORMAT,10 DIGITS,6 AFTER DEC
1210	1008	CD 00 00	E	CALL PRINT	PRINT IN FIXED FORMAT
1211	100B	21 01 00		LXI H,00001H	SET COUNT NO TO 1
1212	100E	22 19 3C		SHLD CNTN	SET IN RAM
1213	1011	01 00 30		LXI D,TAPDAT	WE WILL DUMP 1ST BLOCK OF
1214	1014	11 79 30		LXI D,TAPDAT+079H	DATA FROM TAPE SINCE IT
1215	1017	CD 6B 0F		CALL RDTAP	HAS THE MDRHC COUNT NO.
1216	101A	21 45 3E	RESTRI	LXI H,POSCH	LOAD HL WITH POS CHAN ADDR
1217	101D	CD 59 10		CALL RESET1	START WITH POSCH SET TO POSCHH
1218	1020	01 10 3C	CALTL	LXI B,RAWDA	LOAD STARTING ADDR INTO BC
1219	1023	AF		MVA A	ZERO ACCUMULATOR
1220	1024	02		STAX B	ZERO 1ST RAW DATA BYTE
1221	1025	03		INX B	MOVE TO 2ND RAW DATA BYTE
1222	1026	02		STAX B	ZERO IT
1223	1027	03		INX B	MOVE TO 3RD RAW DATA ADDRESS
1224	1028	11 32 3C		LXI D,RAWDA+17H	STOP AFTER ALL RAW RDGS
1225	102B	CD 97 0F		CALL RDTAP	READ RAW DATA FROM TAPE INTO RAM
1226	102E	CD 7F 00		CALL FLTCLR	FLOAT AND CORRECT RAW READINGS
1227	1031	3A 6A 3E		LDA HPROP	LOAD NO OF PROP TO BE CALCULATED
1228	1034	CD 30 0A		CALL POLSM	CAL PROP.VALUE ON ASTACK
1229	1037	21 15 3E		LXI H,PROPA	WRITE PROPERTY AT 1ST PROPA LOC IN RAM
1230	103A	CD 00 00	E	CALL TOS4	STORE TOP OF ASTACK IN RAM
1231	103D	CD FF 0C		CALL DACON1	SEND PROPERTY TO 5 CHANNEL DAC,STRIP CHART
1232	1040	3E 05		MVI A,05H	SELECT TAPE DRIVE,SET UP FOR READ
1233	1042	D3 F5		OUT PORT10	SEND TO PORT 10
1234	1044	21 45 3E		LXI H,POSCH	LOAD HL WITH CHANNEL POSITION ADDR
1235	1047	35		DCR H	DECREMENT CHANNEL POSITION INDEX IN MEM
1236	1048	FC 69 10		ON RESET1	RESET POS CH,INR COUNT NO.
1237			:	CALL *CALF	PRINT PROPERTIES ON TERMINAL
1238	104B	C3 20 10		JMP CALTL	STAY IN LOOP UNTIL DONE
1239	104E	01 99 3D	CALTC	LXI B,CALRD	LOAD ADDRESS OF CALIBRATION RDGS IN BC
1240	1051	11 F0 3D		LXI D,CALRD+05FH	50 BYTES OF CALB RDGS TO BE STORED
1241	1054	CD 6B 0F		CALL RDTAP	DATA FROM BC THROUGH DE STORED
1242	1057	CD 00 00		CALL PRCALB	PRINT CALIBRATION READINGS

1243	105A	CD 36 11		CALL DUMBUF	FINISH OUT CURRENT BUFFER AND EOF BUF
1244	105D	21 01 00		LXI H,0001	LOAD 0001 INTO HL
1245	1060	22 63 3E		SHLD B,YCNT	STORE CH BYTE COUNT
1246	1063	CD 36 11		CALL DUMBUF	READ EOF BUFFER
1247	1066	C3 00 00	E	JMP GETCH	RETURN TO MONITOR
1248				:	
1249	1069	36 09		RESET:	RESET POSITION CHANNEL NO
1250	106B	2A 19 3C		LHLD CONTH	LOAD COUNT NUMBER FROM RAM
1251	106E	23		INX H	INCREMENT COUNT NUMBER
1252	106F	E5		PUSH H	STORE COUNT NUMBER ON STACK
1253	1070	01 19 3C		LXI B,CONTH	LOAD COUNT NO ADDR INTO BC
1254	1073	11 1A 3C		LXI D,CONTH+1	END OF COUNT NO IN DE
1255	1076	CD 60 0F		CALL RDYTP	READ COUNT NO FROM TAPE
1256	1079	2A 19 3C		LHLD CONTH	LOAD TAPE COUNT NUMBER FROM RAM
1257	107C	D1		POP D	COUNT NO FROM RAM IN DE
1258	107D	7A		MOV A,D	MOVE HI BYTE OF RAM CT NO TO A
1259	107E	DC		CMP H	COMPARE TO H,HI BYTE FROM TAPE
1260	107F	C2 90 10		JNE STOP	ENTER STOP ROUTINE IF.NE.
1261	1082	70		MOV A,E	MOVE LD BYTE FROM RAM TO A
1262	1083	0D		CMP L	COMPARE TO L,LC BYTE FROM TAPE
1263	1084	C2 90 10		JNE STOP	GO TO STOP ROUTINE IF.NE.
1264	1087	21 52 3E		LXI H,DWORD4ADR+POSCCH	
1265	108A	22 50 3E		SHLD POSRAD	STORED FOR NEW RDGS ADDR
1266	108D	21 40 3E		LXI H,DWORD5+1	LC ORDER BYTE OF 1ST RDG
1267	1090	22 50 3E		SHLD POSRAD	STORED FOR OLD ADDR RDGS
1268	1093	AF		MVI H	ZERO ADDEND/ADDER
1269	1094	32 5F 3E		JMP DADRCH	ZERO DAD CHANNEL NUMBER
1270	1097	C9		RET	
1271				:	
1272				:	
1273				STOP	ROUTINE TO STOP TAPE IF COUNT NOS
1274				:	DID NOT MATCH
1275	1098	C1		STOP	
1276	1099	23		POP B	POP STACK-GET SET TO STOP
1277	109A	7A		INX H	INCREMENT TAPE CT NO,SEE IF AT END
1278	109B	BC		MOV A,D	MOVE HI BYTE OF RAM CT NO TO A
1279	109C	C2 A7 10		CMP H	COMPARE TO H,HI BYTE FROM TAPE
1280	109F	70		JNE STOP1	ENTER STOP ROUTINE IF.NE.
1281	10A0	0D		MOV A,E	MOVE LG BYTE FROM RAM TO A
1282	10A1	C2 A7 10		CMP L	COMPARE TO L,LC BYTE FROM TAPE
1283	10A4	C3 40 10		JNE STOP1	GO TO STOP ROUTINE IF.NE.
1284	10A7	21 23 12	STOP1	JMP CALTC	WE WERE AT END OF TAPE-READ CALIB
1285	10AA	06 20		LXI H,STPHS	ADDRESS OF TAPE DATA MESSAGE
1286	10AC	CD 40 0F		MVI B,LSSTPHS	LENGTH OF MESSAGE
1287	10AF	C3 00 00	E	CALL MSGOUT	
1288				JMP GETCH	RETURN TO MONITOR
1289				:	
1290				RESTR	ATTEMPTS TO START READING TAPE AGAIN
1291				:	AFTER AN ERROR AND HALT
1292				:	
1292	10B2	3E 00		RESTR:	SET PORTS FOR END OUTPUT
1293	10B4	D3 F7		OUT PORT1	SEND CONTROL WORD TO PORT 1
1294	10B5	3E 90		MVI A,0000	LOAD ADDRESS WORD,A=INPUT,B=OUTPUT
1295	10B8	D3 EF		OUT PORT1	SEND TO PORT1.
1296	10BA	3E 07		MVI A,0000	LOAD 0000/0111 INTO AL-CARRY OFF.

1297	10BC	D3	ED		OUT PORT2B	TURN CALIBRATOR RELAYS OFF
1298	10BE	3E	70		MVI A,079H	SET MAG TAPE READ,WRITE,DAC LATCH HI
1299	10C0	D3	EE		OUT PORT2C	LEAVE STROBE LINES HI
1300	10C2	3E	93		MVI A,PRT3	LOAD WORD FOR A OUT, B INPUT,C 1/0
1301	10C4	D3	DF		OUT PORT3	
1302	10C6	3E	05		MVI A,05H	SELECT TAPE DRIVE,SET UP FOR READ
1303	10C8	D3	F5		OUT PORT1B	SEND TO PORT 1B
1304	10CA	01	00	30	LXI B,TAPDAT	ADDRESS OF FIRST BYTE IN BC
1305	10CD	11	E7	30	LXI D,TAPDAT+1E7H	ADDRESS OF LAST BYTE TO BE READ
1306	10D0	CD	6B	0F	CALL RDTRP	READ 400 BYTES OF DATA INTO RAM
1307	10D3	21	00	30	LXI H,TAPDAT	SET UP HL TO CONTAIN 1ST BLOCK
1308	10D6	01	7A	30	LXI D,TAPDAT+07AH	BC ADDR OF NEXT BLOCK
1309	10D9	11	F4	30	LXI D,TAPDAT+0F4H	DE ADDR OF 3RD DATA BLOCK
1310	10DC	AF			XRA A	ZERO ACCUMULATOR
1311	10DD	32	6C	3E	STA RCNT	STORE RDC COUNT NO. IN RAM
1312	10E0	0A			LDAX B	LOAD LO BYTE AT BC INTO A
1313	10E1	3D			DCR A	LOW BYTE SHOULD BE ONE GREATER THAN L
1314	10E2	BE			CHP H	COMPARE TO LO BYTE AT HL
1315	10E3	C2	14	11	JNZ INCRM	JUMP AROUND IF LO.HL,LO-1
1316	10E6	1A			LDAX D	LOAD LO BYTE ADDR BY DE INTO A
1317	10E7	3D			DCR A	LO BYTE AT DE SHOULD BE 2 GT HL
1318	10E8	3D			DCR A	
1319	10E9	BE			CHP H	SEE IF LO BYTES .EQ.
1320	10EA	C2	14	11	JNZ INCRM	JUMP AROUND IF LO.HL,LO-2
1321	10ED	23			INX H	LO BYTES CHECKED,LOOK AT HI BYTES
1322	10EE	03			INX D	
1323	10EF	13			INX D	
1324	10F0	0A			LDAX B	MOVE BYTE AT BC ADDR INTO A
1325	10F1	BE			CHP H	COMPARE BYTE AT ADDR BC TO ADDR HL
1326	10F2	C2	17	11	JNZ INCRM1	JUMP AROUND IF HI BYTE .NE.
1327	10F5	1A			LDAX D	LOAD BYTE ADDR BY DE INTO A
1328	10F6	BE			CHP H	COMPARE HI BYTE ADDR BY DE TO ADDR HL
1329	10F7	C2	17	11	JNZ INCRM1	JUMP AROUND IF HI BYTE .NE.
1330	10FA	67			MOV H,A	HI ORDER BYTE COUNT IN H
1331	10FB	1B			DCX D	BACK UP FOR LOW ORDER BYTE
1332	10FC	1A			LDAX D	LOAD ACC WITH LOW ORDER BYTE
1333	10FD	6F			MOV L,A	STORE IN L
1334	10FE	23			INX H	INCREMENT COUNT-THERE ARE 4 COUNTS IN RAM
1335	10FF	22	19	3C	SHLD CONTN	STORE IN RAM
1336	1102	01	00	30	LXI D,TAPDAT	WILL READ TAPE UNTIL WE GET TO NEXT CONTN
1337	1105	3A	6C	3E	LDI RCNT	NUMBER OF RDCS NEEDED IN A
1338	1108	11	00	30	LXI D,TAPDAT	BE SAME AS BC
1339	110D	03			ADD E	A CONTAINS OFFSET ADDR FOR DE
1340	110C	3D			DCR A	DECREMENT A
1341	1100	5F			MOV E,A	DE CONTAINS RDCS TO BE MADE
1342	110E	F4	6B	0F	CP RDTRP	MAKE REQUIRED NO OF TAPE RDCS
1343	1111	C3	10	10	JMP RDCYS1	JUMP INTO CALCULATION LOOP
1344						
1345						
1346	1114	23			INCRM	SUBROUTINE TO INCREMENT ADDRESSES
1347	1115	03			INX H	INCREMENT HL,DC,BC TO POINT TO NEXT BYTES
1348	1116	13			INX C	
1349	1117	3A	6C	3E	INX D	
1350	111A	3C			LDI RCNT	ENTER HERE IF WE HAVE ALREADY INCREMENTED
					INR A	ADVANCE READING COUNTER

SRLP

;
;
INCRM

INCRM1

1351	111D	32 6C 3E		STA RCHT	STORE BACK IN RAM
1352	111E	FE 7A		CPI 07AH	COMPARE TO 122 (07AHX)
1353	1120	CA D2 10		JZ RESTR	JUMP TO RESTART PROG TO READ MORE DATA
1354	1123	C3 E0 10		JMP SRLP	GO BACK TO SEARCH LOOP
1355			:		
1356			:	RDCHRS	PROGRAM TO READ IN ASCII CHARACTERS
1357			:		LAST 4 CHRS IN HLDE, LAST IN E
1358			:		
1359	1126	65	RDCHRS	MOV H,L	SAVE PRIOR CHARACTERS
1360	1127	6A		MOV L,D	
1361	1129	53		MOV D,E	4TH CHARACTER FROM LAST IN H, LAST IN E
1362	1129	59		MOV E,C	
1363	112A	CD 00 00	E	CALL GETCH	GET CHARACTER FROM TERMINAL
1364	112D	CD 00 00	E	CALL ECHO	PRINT CHARACTER ON TERMINAL
1365	1130	FE 0A		CPI LF	COMPARE CHARACTER TO LINE FEED
1366	1132	C2 26 11		JNZ RDCHRS	GO BACK & GET NEXT CHARACTER
1367	1135	C9		RET	A CR WAS DETECTED, RETURN TO CALLING ROUTINE
1368			:		
1369			:	DUMPDF	DUMP REST OF BUFFER TO MAKE 4096
1370			:		WILL STROBE READ IF PORT1D=05, WRITE=066H
1371			:		
1372	1136	2A 63 3E	DUMPDF	LHLD BYCNT	LOAD BYTE COUNT INTO HL
1373	1139	7D	FINDUF	MOV A,L	SEE IF BYTE COUNT (LO 8 BITS) IS 512D
1374	113A	FE 00		CPI 00H	
1375	113C	C2 43 11		JNZ TOG2	
1376	113F	7C		MOV A,H	CHECK HI BIT TOO
1377	1140	E6 0F		ANI 0FH	DUMP HI ORDER BITS
1378	1142	C8		RC	RETURN TO CALLER IF A MULTIPLE OF 4096
1379	1143	AF	TOG2	XRA H	NOU TOGGLE IN ANOTHER BYTE
1380	1144	D3 EE		OUT PORT2C	
1381	1146	3E 10		MVI A,10H	
1382	1148	D3 EE		OUT PORT2C	
1383	114A	23		INX H	INCREMENT BYTE COUNT BY ONE
1384	114B	C3 39 11		JMP FINDUF	GO BACK AND CHECK COUNT AGAIN
1385			:		
1386			:	WEOF	TOGGLE RAC LINE LOW, THEN BACK HI
1387			:		TO WRITE AN END OF FILE ON THE TAPE
1388			:		
1389	114E	3E 05	WEOF	MVI A,05H	SELECT TAPE DRIVE, SET UP TO WRITE
1390	1150	D3 F5		OUT PORT1D	END OF FILE, SEND TO PORT 1D
1391	1152	01 01 00		LXI D,0001	LOAD BIG DELAY IN DC
1392	1155	CD 00 00		CALL DELAY	
1393	1158	0F		XRA H	STROBE RAC LINE LO, THEN HI
1394	1159	D3 EE		OUT PORT2C	
1395	115B	CD 00 00		CALL DELAY	ALLOW TIME FOR EOF TO BE WRITTEN
1396	115E	3E 10		MVI A,10H	
1397	1160	D3 EE		OUT PORT2C	
1398	1162	C9		RET	RETURN TO CALLING ROUTINE
1399			:		
1400			:	STOGRF	STROBE GO TO NEXT FILE
1401			:		
1402	1163	3E 00	STOGRF	MVI A,00	STROBE GO TO NEXT FILE LINE LO
1403	1165	D3 DE		OUT PORT3C	OUTPUT TO PORT3C
1404	1167	3E 20		MVI A,20H	LEAVE LINE HI

1405	1169	D3 DE		OUT PORT3C	
1406	116B	C9		RET	RETURN TO CALLING ROUTINE
1407			:		
1408			:	WRITE ID ON TERMINAL AND TAPE	
1409			:		
1410	116C	21 D8 11		WRTID: LXI H,MIDI	GET ADDR OF 1ST ID REQUEST MSG
1411	116F	06 0D		MVI B,L,MIDI	GET # OF CHARS IN MSG
1412	1171	CD 4D 0F		CALL MSGOUT	PRINT IT ON TTY
1413	1174	3E 06		MVI A,000H	SELECT TAPE ONLY
1414	1176	D3 F5		OUT PORT1D	
1415	1178	3E 01		MVI A,001H	
1416	117A	D3 EE		OUT PORT2C	LEAVE REC HI
1417	117C	CD 00 11		CALL GETID	
1418	117F	C9		RET	
1419			:		
1420			:	GETID	ROUTINE TO READ CHARS FROM TTY AND PRINT
1421			:		THEM AT THE CURRENT POSITION ON THE MSG TAPE.
1422			:		<CR> TERMINATES.
1423			:		
1424	1180	2A 63 3E		GETID	LHLD BYCNT
1425	1183	CD 00 00	E	GETID0	CALL GETCH
1426	1186	CD 00 00	E		CALL ECHO
1427	1189	79			PRINT IT ON TTY
1428	118A	D3 F4		MOV A,C	GET ID CHAR INTO A
1429	118C	3E 00		OUT PORT1A	PUT IT ON TAPE WRITEDATA PORT
1430	118E	D3 EE		MVI A,00H	STROBE REC LO THEN HI
1431	1190	3E 10		OUT PORT2C	
1432	1192	D3 EE		MVI A,10H	
1433	1194	23		OUT PORT2C	
1434	1195	3E 0D		INX H	INCREMENT RECORD BYTE COUNT
1435	1197	B9		MVI A,0DH	
1436	1198	C2 83 11		CMP C	WAS LAST CHAR A <CR>?
1437	119B	22 63 3E		JNZ GETID0	NO-GET ANOTHER CHAR
1438	119E	C9		SHLD BYCNT	STORE BYTE COUNT BACK IN RAM
1439			:	RET	YES-RETURN TO CALLER
1440			:		
1441			:	READID	ROUTINE TO READ IDENTIFICATION DATA FROM TAPE
1442			:		AND PRINT IT ON THE TTY
1443	119F	CD 00 00	E	READID	CALL CROUT
1444	11A2	CD 00 00	E		CALL CROUT
1445	11A5	2A 63 3E		RDD:	MAKE FORMAT LOOK NICE
1446	11A8	23			TWO LINE FEEDS
1447	11A9	22 63 3E			LOAD BYTE COUNT INTO HL
1448	11AC	D8 DC		LHLD BYCNT	INCREMENT BYTE COUNT
1449	11AE	4F		INX H	INCREMENT BYTE COUNT
1450	11AF	CD 00 00	E	SHLD BYCNT	STORE BACK IN RAM
1451	11B2	FE 0D		IN PORT3A	READ A CHAR FROM TAPE
1452	11B4	CA C3 11		MOV C,A	
1453	11B7	53		CALL CD	OUTPUT IT TO TTY
1454	11B8	59		CPI CR	WAS IT A <CR>?
1455	11B9	AF		JZ RETRN	YES-FINISH UP A RETURN
1456	11BA	D3 EE		MOV D,E	LAST TWO CHARACTERS BEFORE CR SAVED IN DE
1457	11BC	3E 10		MOV E,C	CHARACTER JUST PRINTED MOVED TO E
1458	11BE	D3 EE		XRA A	NO-READ ANOTHER CHAR
				OUT PORT2C	STROBE RAC LO THEN HI
				MVI A,10H	
				OUT PORT2C	

```

1459 1109 C3 A5 11
1460 1103 EB
1461 1104 22 66 3E
1462 1107 7D
1463 1109 E6 0F
1464 110A 07
1465 110D C6 19
1466 110D 32 2B 3E
1467 1109 AF
1468 11D1 D3 EE
1469 11D3 3E 10
1470 11D5 D3 EE
1471 11D7 C9
1472
1473
1474
1475 11D0 0D 0A 45 4E
1476 11D0 54 45 52 20
1477 11E0 49 44 3A 20
1478 11E4 20
1479 000D
1480 11E5 0D 0A 53 57
1481 11E9 49 54 43 4B
1482 11ED 20 54 41 5B
1483 11F1 45 20 54 4F
1484 11F5 20 52 45 41
1485 11F9 44 2C 4F 4E
1486 11FD 4C 4D 4E 4D
1487 001C
1488 1201 0D 0A 4A 4D
1489 1205 53 50 20 30
1490 1209 2E 4C 4F 50
1491 120D 20 31 2E 49
1492 1211 44 45 45 20
1493 1215 32 2E 4C 4F
1494 1219 46 45 20 35
1495 121D 2E 4F 44 4D
1496 1221 46 20
1497 0022
1498 1223 0D 0A 54 41
1499 1227 50 45 20 45
1500 122B 52 52 4F 52
1501 122F 20 2D 20 44
1502 1233 4F 20 4D 41
1503 1237 4E 55 41 4C
1504 123B 20 52 45 53
1505 123F 54 41 52 54
1506 0020
1507
1508 1243 20 4D 49 4C
1509 1247 53 0D 0A
1510 0007
1511 124A 71 A0 0A 00
1512 124E 70 A0 0A 00

```

```

JIP R00
XCRG
SHLD COILNT
MOV R,L
ORI GRH
RLC
RMI 10H
STH CLADR
XCA A
OUT PORT2C
XVI A,10H
OUT PORT2C
RET
RETURN TO CALLER
;
; DATA STORAGE FOR MESSAGES
;
MID1 DD CR,LF,"ENTER ID:"
LNID1 EQU $-MID1 LENGTH OF MESSAGE MID1
TAPPR DD CR,LF,"SWITCH TAPE TO READ.ONLINE"
LTAPPR EQU $-TAPPR LENGTH OF TAPE PROMPT MESSAGE
PROPR DD CR,LF,"DISP O.LOFF 1.IDEF 2.LOFF 3.OADR"
LPROPR EQU $-PROPR LENGTH OF PROPERTY PROMPT
STPRB DD CR,LF,"TAPE ERROR - DO MANUAL RESTART"
LSTPRB EQU $-STPRB LENGTH OF STOP PROMPT
;
;
DWDIS DD " HILS",CR,LF
LDWDIS EQU $-DWDIS
CALPR DD 07H,0A0H,0A0H,0A ;CALIB CUN PWD #5*(0055*10*4)
CALGR DD 07H,0A0H,0A0H,0A ;CALIB STD PWD #5*(0055*120)

```

```

1513
1514
1515
1516
1517 1252 00 00 00 00
1518 1256 77 A0 0A 00
1519 125A 00 00 00 00
1520 125E 77 A0 0A 00
1521 1262 00 00 00 00
1522 1266 77 A0 0A 00
1523 126A 00 00 00 00
1524 126E 77 A0 0A 00
1525 1272 00 00 00 00
1526 1276 77 A0 0A 00
1527 127A 00 00 00 00
1528 127E 77 A0 0A 00
1529 1282 01 99 01 99
1530 1286 01 99
1531 1288 01 99 01 99
1532 128C 01 99
1533 128E 01 99 01 99
1534 1292 01 99
1535 1294 01 99
1536 1296 0F 9F F6 00
1537 129A 10 9F F6 00
1538 129E 01 06 10 20
1539 12A2 7A A3 D7 0C
1540
1541
1542 1800
1543 1060
1544 1070
1545
1546
1547 190C

;
; SLOPE EXPONENTS WRS 077H BUT THE NO OF RDCN,NRDS,
; HAS BEEN DIVIDED INTO SLOPE,OR A SUB FROM EXPT,WHERE
; 2**N=NRDS
CRFRO DB 0,0,0,0,077H,0A0H,0AH,0 ;1ST OFS=0,1ST,SLP=S/4095*NRDS
DB 0,0,0,0,077H,0A0H,0AH,0 ;2ND OFS=0,2ND,SLP=S/4095*NRDS
DB 0,0,0,0,077H,0A0H,0AH,0 ;3RD OFS=0,3RD,SLP=S/4095*NRDS
DB 0,0,0,0,077H,0A0H,0AH,0 ;4TH OFS=0,4TH,SLP=S/4095*NRDS
DB 0,0,0,0,077H,0A0H,0AH,0 ;5TH OFS=0,5TH,SLP=S/4095*NRDS
DB 0,0,0,0,077H,0A0H,0AH,0 ;6TH OFS=0,6TH,SLP=S/4095*NRDS
DACDF DB 1,099H,1,099H,1,099H ;DAC OFFSET,1ST,2ND,3RD,VAL*DAFAC
DB 1,099H,1,099H,1,099H ;DAC OFFSET,4TH,5TH,6TH
DB 1,099H,1,099H,1,099H ;DAC OFFSET,7TH,8TH,9TH
DAFAC DB 1,099H 10TH
DAFAC2 DB 0FH,09FH,0F6H,0H ;D TO A FACTOR = 40950
SPEED0 DB 10H,09FH,0F6H,0H ;2ND DAC FACOR=01000
SPEED0 DB 01H,06H,016H,02BH ;SPEEDS FOR PUSH/PULL SLOWEST FIRST
TENNIL DB 07AH,0A3H,0D7H,0CH ;0.01
ORG 1000H START DATA AT 1000 IN FOURTH FROM.
; SET NCOED IN TUBFIT=DEC VAL OF ADDR OF 1ST CAL0 VALUE
CAL0 DS 060H INITIAL CALIBRATION READINGS
VOLSTD DS 016H INITIAL READINGS ON NOMINAL TUBE STANDARD
CUCDT DS 114H ;PROPERTY COEFFICIENTS,270 BYTES.
;LAST PROPERTY SET IN TUBFIT IS FIRST
;ON CRT AND GRAPH-FIRST IN LAST OUT.

END

```

ASSEMBLER ERRORS = 0

SYMBOL TABLE

A	0007	ADBUS	0AF4	ADRBC	0ADC	ALADD	3E68
ALARM	0D7A	APDATA	007E	APSTS	007F	B	0000
BYCNT	3E63	C	0001	CALO	1000	CALFR	124A
CALID	0B0A	CALL2	0B72	CALLP	0B15	CALPR	002B
CALPRL	0B06	CALPRO	0B98	CALRD	0D99	CALSFR	124E
CALTC	104E	CALTL	1020	CARRET	0D07	CHALP	0B1F
CHAND	3C11	CHCLP	0B42	CHLUP	0AC5	CHSD	E 0000
CHSDA	E 0001	CHSF	E 0002	CHSFA	E 0003	CHSS	E 0004
CHSSA	E 0005	CL0ADR	3E20	CO	E 0000	COEDT	1070
COEOF	003D	COILHT	3E63	CONTH	3C19	COPDT	E 0050
CORLP	0A95	COS	E 0005	COSN	E 0007	CR	000D
CRFAC	0A0F	CRFRA	3C35	CRFR0	1252	CROUT	E 0057
D	0002	DACAL1	0E11	DADALB	0DE4	DACCH	3E5F
DACCL2	0DF5	DACMS	1243	DACOF	12B2	DACCF5	3C65
DACOH1	0CFF	DACOH2	0E40	DACOH3	0E4E	DACONS	0E0A
DACSET	0D76	DADD	E 0009	DADDA	E 0009	DADDB	E 000A
DAFAC	1296	DAFAC2	129A	DALP2	0E34	DALPS1	0E01
DALPS2	0EAE	DAOLD	3E47	DDIV	E 000B	DDIVA	E 000C
DDIVB	E 000D	DECHO	E 000E	DELAY	0E00	DNUL	E 000F
DNULA	E 0010	DNULB	E 0011	DNUB	E 0012	DNUBA	E 0013
DNUBB	E 0014	DSPAD	3C12	DSUB	E 0015	DSUBA	E 0016
DSUBB	E 0017	DTMAX	0D6D	DTMAX3	0E01	DTMIN	0D65
DTMINS	0EC9	DUMPDF	1135	E	0003	ECHO	E 00G2
EPRNT	E 005C	EXP	E 0010	EXP10	E 001A	EXFA	E 0019
FADD	E 0010	FADDA	E 001C	FADDB	E 001D	F0IV	E 001E
FDIVA	E 001F	FDIVB	E 0020	FILECT	3E05	FILENL	0FD6
FINBUF	1139	FIXD	E 0021	FIXDA	E 0022	FING	E 0023
FIXSA	E 0024	FLTCOR	007F	FLTD	E 0025	FLTDA	E 0026
FLTS	E 0027	FLTSA	E 0028	FMUL	E 0029	FMULA	E 002A
FMULB	E 002B	FPRNT	E 005D	FSUB	E 002C	FSUBA	E 002D
FSUBB	E 002E	GETCH	E 0053	GETCH	E 0059	GETHX	E 0064
GETID	1180	GETID0	1103	GETHM	E 005F	H	0004
INCRM	1114	INCRM1	1117	L	0005	LFACTS	0007
LF	000A	LMID1	000D	LN	E 002F	LNA	E 0030
LOG	E 0031	LOGA	E 0032	LPSH	0004	LPROPR	0002
LSTPMS	0020	LTAPPR	001C	M	0006	MAIND	0042
MDAD	E 0033	MEMORY	M 0000	MID1	1100	MEGOUT	0F40
NCALC	0004	NCHA	0006	MINDT	E 0061	ISPROP	3E0A
NRDG	0001	PCAL1	3C15	PCAL2	3C16	PCAL3	3C17
PCAL4	3C10	PCALN	3C14	PCALP	0F2F	PCLLP	0A02
POLSM	0A33	POPD	E 0034	POPS	E 0035	PORT1	00F7
PORT1A	00F4	PORTID	00F5	PORTIC	00F6	PORT2	00EF
PORT2A	00EC	PORT2D	00ED	PORTOC	00EE	PORT3	00EF
PORT3A	00DC	PORT3D	00DD	PORTOC	00EE	PUSCH	3E45
POSCH	0009	POSHAD	3E30	POSHAD	3E30	PSCLO	0000
PRINT	E 005A	PRINTF	E 005D	PRDPA	3E48	PRFHI	0002
PROPPR	0F09	PROPR	0001	PKY11	0000	PKY30	0000
PRT3	0040	PRTSU	0100	PLM	0000	PT00	E 0030
PTOS	E 0037	POPI	E 0030	PAR	E 0037	PLA	E 003A
PUBB	E 0030	RADUB	007C	RADDA	3C10	RENT	0000
R00	1140	R0CHR0	1140	RADDA	007C	REOF	0000
R0STD	0E0A	RDSTL	0000	RDSTP	0000	RDSTP	0007
RDTAPL	0F6E	RDTFL	0F9A	READID	110F	RECAL	0B99
RECL2	0BAC	RECL3	0CB9	RECL4	00A7	RECL5	0CE0
RECLP	0DA1	RECHO	3E60	RESET	0007	RESET1	1000
RESTR	1002	RESTR1	1010	RETRN	1105	REZRL1	0000
REZRU	0D00	RUNH	000D	RUNH1	1000	RUSHO	000E
RUNHS1	0D05	RWCLTP	0F00	SADD	E 000C	SADDA	E 000D
SADD	E 003E	SDIV	E 003F	SDIVA	E 0040	SDIVB	E 0041
SIN	E 0042	SINA	E 0043	SNCLP	000C	SNBAT	0A0E
SNCLP	0ABE	SNUL	E 0044	SNULA	E 0045	SNULD	E 0046
SNUB	E 0047	SNUBA	E 0048	SNUBB	E 0049	SY	0000
SPECDO	129E	SQRT	E 004A	SORTY	E 004D	SILP	10E0
SSUB	E 004C	SSUBA	E 004D	SOUND	E 004E	STACK	S 0000
STUBHF	1163	STDTAP	0F00	STOP	1000	STUP1	1007
STUPR	092C	STPMD	1223	STUP	0000	STUP2	0000
SUPRY	3E09	SUPY	3E05	SWAP	1001	SW	E 004F
TANA	E 0050	TAPDWT	3E00	TAPPR	1000	TICHTL	1000
TANH	3E61	T000	1140	T000	E 0051	T000	E 0050
TRNCT	3C10	Y000	0000	MALNUM	0000	MALNUM	1000
VSTUVT	3C10	UB00	1140	UB00	E 0000	UB00	S 0000
UNTRP	0F57	URTRPF	0F50	UNTRP	1000	UNTRP	0F00
URTRPF	0F00	X000	0000	UNTRP	E 0000	UNTRP	E 0000
YBAR	3E11	Z000	E 0000				

Appendix F

PROCEDURE FOR PERFORMING THE AUTOMATED MULTIFREQUENCY EDDY-CURRENT
INSPECTION OF THE SHEATH WELD ON THE SUPERCONDUCTOR CABLE

This procedure describes the techniques used to perform the eddy-current inspection of the sheath weld on the production line as the superconductor cable is being fabricated. The procedure provides guidelines for the necessary steps and the order of performance required to set up and calibrate the equipment, verify the test sensitivity, and perform the inspection to evaluate the quality of the gas tungsten arc weld in the steel sheath for the superconductor cable for the Fusion Energy Program. The procedure was written with the assumption that the operator is familiar with the test equipment and its operation.

1. EQUIPMENT

Multifrequency eddy-current instrument

Eddy-current probe and cable

Probe drive mechanism

Transceiver unit

Video terminal and keyboard

Remote control box (RCB)

Six-channel analog recorder

Magnetic tape recorder

Assorted nonconducting shims in the 25- to 250- μm (0.001- to 0.010-in.)
range

Reference standards

Isolation transformer

2. ELECTRICAL POWER

2.1 Before connecting power to the eddy-current instrument, make sure that the three toggle switches on the phase calibrator module are in the "down" position (i.e., "MAG-LO," "PH-LO," and "OPERATE" positions), and make sure that an eddy-current probe is connected to the correct jacks on the calibrator module.

2.2 Connect electrical power to *all* instruments [eddy current (only on isolation transformer), two recorders, transceiver, video terminal, and probe drive mechanism], turn the equipment on, and allow at least 4 h for the instruments to warm up and stabilize.

3. DURING THE WARM-UP PERIOD

3.1 Check all cables and electrical connections to make sure that they are correct (see Fig. F.1).

3.2 Check the switches on all modules and instruments to assure they are in the normal position, per Tables F.1 and F.2.

3.3 Place standard tube 1 (with inner surface defects) in the probe drive unit. [Under normal conditions the probe has a 88.9- μm -thick (0.0035-in.) tape on face.] Place a 76.2- μm -thick (0.0030-in.) nonconducting shim between the probe face and the tube and mechanically adjust the lift-off. Connect hold-down spring to V-block.

3.4 Turn on the probe drive mechanism and let it run for a brief period to assure that it operates freely and correctly.

3.5 *Display Raw Readings.* Set the remote control box (RCB) function switch to position 3. When the cursor symbol appears on the video display, press the "reset" switch on the RCB. The statement "NDT COMP9" should appear on the video display. Next, press the "interrupt" switch on the RCB, and the raw readings will be continuously displayed on the video terminal. Check the raw readings to see if any are either zero or 4.999. If so, there is probably something wrong with the eddy-current instrument, and it should be corrected before proceeding. Press the "reset" switch on the RCB to stop the readings, and go to the next step.

3.6 *Check the analog recording system.* Set the (RCB) function switch to position 7. Press a chart speed switch to start the analog recorder chart drive. Use a slow chart speed (5 mm/s or less). Press the "interrupt" switch on the RCB and set all recorder pens to the zero reference value on each chart scale by use of zero adjustments on the recorder. The zero reference value for the five defect channels is 10 minor divisions to the left of the right-hand chart margin. [Each minor division represents 51 μm (0.0020 in.). The chart range is -0.51 to +2.03 mm (-0.020 to +0.080 in.).] The zero reference value for the lack-of-penetration channel is the right-hand chart margin. [Each minor division

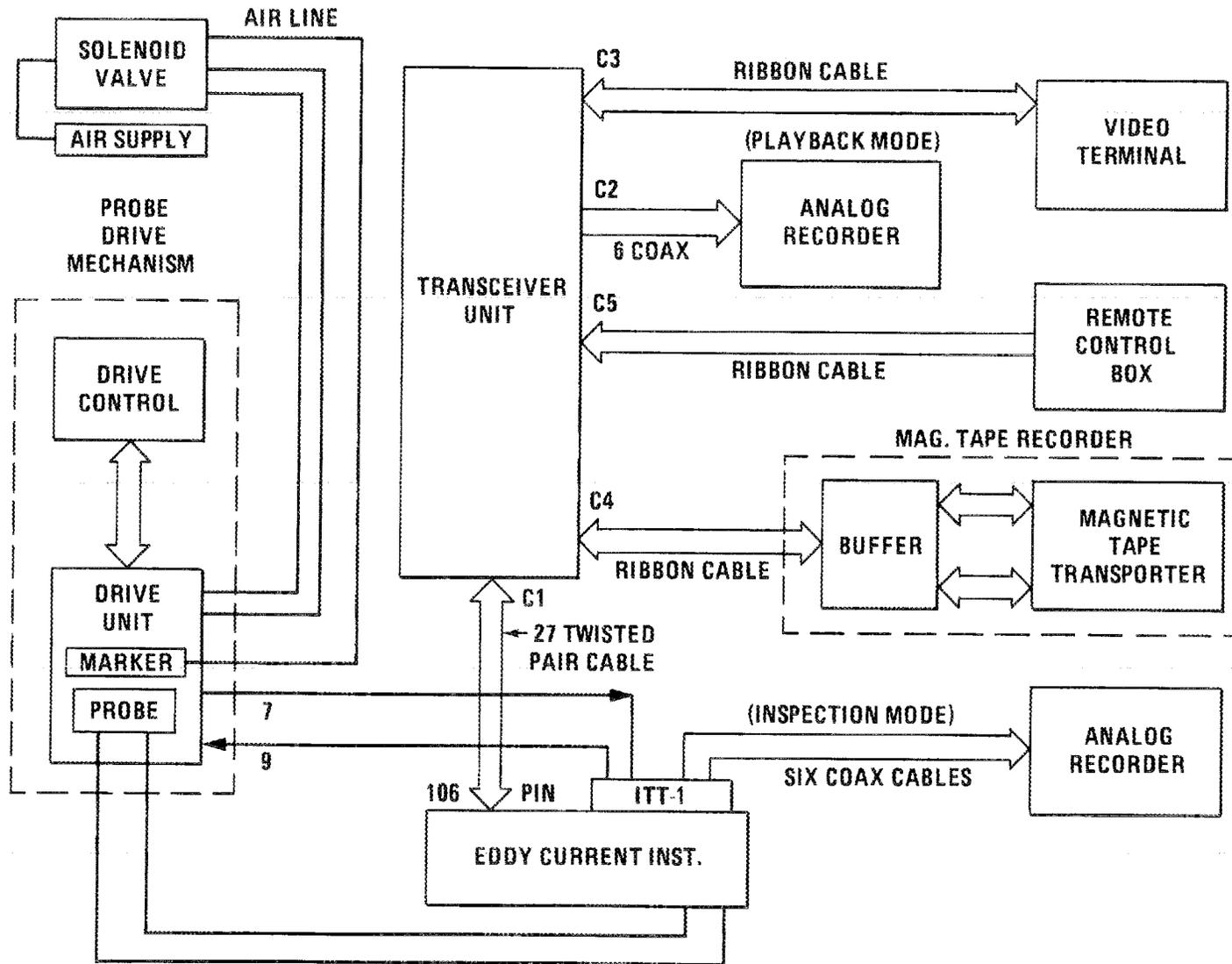


Fig. F.1. Block diagram of instruments showing cable connections.

Table F.1. Normal instrument settings

Instrument	Modular ^a position	Switch identity	Correct switch setting
<u>Eddy-Current Instrument</u>			
Power on-off			
Power Oscillator	M1	High frequency (top)	500 kHz
		Median frequency (middle)	100 kHz
		Low frequency (bottom)	20 kHz
Bandpass Amplifier	M4	Low frequency	20 kHz
	M6	Mid frequency	100 kHz
	M8	High frequency	500 kHz
Discriminators ^b	M3	Coarse lift-off	518
	M3	Coarse balance	714
	M5	Coarse lift-off	512
	M5	Coarse balance	682
	M7	Coarse lift-off	507
	M7	Coarse balance	920
<u>Analog Recorder</u>			
Power on-off			
Sensitivity -- coarse			100 mV/div
Sensitivity -- fine			Maximum CW
Chart speed			5 mm/div
<u>Probe Drive Control</u>			
Power on-off			
Speed adjustment			124-128
Scale selector (torque/speed)			Speed
Direction (CW/stop/CCW)			CW

^aThe eddy-current instrument chassis has 10 modular positions. They are identified as M1 to M10 from right to left when facing the instrument. The computer module occupies two positions, M9 and M10.

^bAdjustments of the lift-off and balance controls on the discriminators may sometimes be necessary to calibrate the eddy-current instrument. These adjustments should be made by using only the fine controls (screwdriver adjustments). If a change in the coarse control setting becomes necessary, notify your supervisor.

Table F.2. Instrument switches and functions

Instrument	Switch	Position(s)	Function and comments
<u>Eddy Current Control Module</u>	Function	0-9	Selects correct PROM to match the eddy-current probe (00 for 454, 01 for 460, and 02 for 459)
	Interrupt		DO NOT USE
	Reset		DO NOT USE
<u>Magnetic Tape Recorder</u>			
Transporter	Power	On-Off	
Transporter	Load	On-Off	Used to load tape
Transporter	On-Line	On-Off	Use for recording and reading
Transporter	Rewind	On-Off	Used to rewind tape
Transporter	Write ring		See Appendix A
Buffer	Power	On-Off	
Buffer	EOF	On-Off	See Appendix A
Buffer	Mode	Record	Used to record data
Buffer	Mode	Read	Used to read tape
Buffer	Mode	Continuous	DO NOT USE
Buffer	Mode	Remote	DO NOT USE
<u>Transceiver</u>			
	Power	On-Off	
	Selector	DX	Select external computer, used to record data (in eddy-current instrument)
	Selector	Local	Select internal computer, used to read tape
	Function	0-9	Always set on 1
<u>Video Terminal</u>			
	Power	On-Off	Located in back of instrument
	Keyboard		Transmits information and commands to computer

represents 51 μm (0.0020 in.). The chart range is 0 to 2.54 mm (0 to 0.1 in.).] The actual value recorded on each recorder channel is also displayed on the video monitor. After zeroing all pens, press the "return" key on the keyboard. All recorder pens should step five minor chart divisions to the left on the respective chart scales, representing an increase of 0.25 mm (0.010 in.). Press the "return" key a total of eight times, representing an increase of 2.03 mm (0.080 in.). All five defect channel recorder pens should now be at the left margin of their respective chart scales. If any of these recorder pens are not at the left margin, check the recorder sensitivity adjustments for that recorder channel (see Table F.1). Note the variable sensitivity adjustment must be set at maximum (fully clockwise) for that recorder channel to be calibrated. Press the "return" key twice more to check the calibration on the lack-of-penetration channel. [If the incremented steps between zero and maximum are not linear (i.e., five divisions per step), something is wrong with the recorder.] Press the "reset" switch on the RCB to stop this check, press the "STOP" switch on the analog recorder, and go to the next step.

3.7 Check the magnetic tape recorder according to the procedure described in Supplement 1.

4. AFTER THE EDDY-CURRENT TEST SYSTEM HAS COMPLETED A 4-h WARM-UP PERIOD, COMPLETE THE FOLLOWING CHECKOUT SEQUENCE

4.1 Set the transceiver selector switch to "DX." Set the transceiver function switch to "1."

4.2 *Check the analog recording system.* Set the (RCB) function switch to position 7. Press a chart speed switch to start the analog recorder chart drive. Use a slow chart speed (5 mm/s or less). Press the "interrupt" switch on the RCB and set all recorder pens to the zero reference value on each chart scale by use of zero adjustments on the recorder. The zero reference value for the five defect channels is 10 minor divisions to the left of the right-hand chart margin. [Each minor division represents 51 μm (0.0020 in.). The chart range is -0.51 to +2.03 mm (-0.020 to +0.080 in.).] The zero reference value for the lack-of-penetration channel is the right-hand chart margin. [Each minor division

represents 51 μm (0.0020 in.).] The chart range is 0 to 2.54 mm (0 to 0.1 in.). The actual value recorded on each recorder channel is also displayed on the video monitor. After zeroing all pens, press the "return" key on the keyboard. All recorder pens should step five minor chart divisions to the left on the respective chart scales, representing an increase of 0.25 mm (0.010 in.). Press the "return" key a total of eight times, representing an increase of 2.03 mm (0.080 in.). All five defect channel recorder pens should now be at the left margin of their respective chart scales. If any of these recorder pens are not at the left margin, check the recorder sensitivity adjustments for that recorder channel (see Table F.1). Note that the variable sensitivity adjustment must be set at maximum (fully clockwise) for that recorder channel to be calibrated. Press the "return" key twice more to check the calibration on the lack-of-penetration channel. [If the incremented steps between zero and maximum are not linear (i.e., five divisions per step), something is wrong with the recorder.] Press the "reset" switch on the RCB to stop this check, press the "STOP" switch on the analog recorder, and go to the next step.

4.3 *Perform and Display Calibration.* Set the RCB function switch to position 5. Press the "interrupt" switch on the RCB. You should hear relays clicking, and about 10 s later the computer will display four lines of data on the video monitor. Let the display repeat about four or five times and press the "reset" switch on the RCB to stop. Evaluate the data. High magnitudes (columns 1, 3, and 5) should be 4.50 ± 0.02 V. High phases (even columns) should be 4.00 ± 0.02 V, except PH3 = 4.50 V. The phase difference between high magnitude and low magnitude readings on the first two lines of phase data should be less than ± 10 mV. *If not, refer to the instrument calibration procedure. (Important: Do not leave the calibration system running for long periods of time because the relays could be damaged.)*

4.4 *Read Reference Standard.* [The probe should have the 88.9- μm -thick (0.0035-in.) Teflon tape on its face.] Using the square tube standard D, position the probe over the reference reading mark [centered over the weld and 76.2 mm (3 in.) from the end toward defect 1].

Select a lift-off shim to obtain a Mag 2 reading within ± 0.1 V of the Mag 2 reading in Table F.3 (readings from nominal tube sample, third column) for the coil being used. This is done in the function 3 position of the RCB. Example: Probe 454-00 should read 3.6 V (3.5 ± 0.1 V) with a 0.102-mm (0.004-in.) shim. Press reset on RCB.

Select function 2 on the RCB. Using the shim size determined above, hold the probe over the reference reading mark with the shim between the probe face and sample. Press the "interrupt" switch on the RCB. One line of data should be shown on the video display. Press the "interrupt" switch again and another line of data will appear. Repeat until at least five lines of data are obtained or until the last two lines of data agree to within ± 2 mV. Check the Mag 2 reading (third column) and compare with the Mag 2 reading for the nominal tube sample for the probe being used. See Table F.3.

4.5 Place probe in scanning fixture with a 76.2- μm -thick (0.003-in.) shim between the probe and tube and the shim not touching the nylon V-block. Fix the probe at this lift-off and remove the 76.2- μm (0.003-in.) shim. Record the last set of readings obtained in the test log book. Press the "reset" switch on the RCB to return the computer to normal operation.

4.6 *Display Raw Readings.* Set the remote control box (RCB) function switch to position 3. Press the "reset" switch on the RCB. The statement "NDT COMP9" should appear on the video display. Next, press the "interrupt" switch on the RCB, and the raw readings will be continuously displayed on the video terminal. Check the raw readings to see if any are either zero or 4.999. If so, check the eddy-current probe to see if it is properly seated on the standard test tube. If it is, something is probably wrong with the eddy-current instrument, and it should be corrected before you proceed. Press the "reset" switch on the RCB to stop the readings and go to the next step.

4.7 *Main Running Loop.* Calibration and test data are recorded during this sequence, which is described in general as follows:

- a. Precalibration -- Run each of the round calibration standards and record the data on the analog recorder and magnetic tape.

Table F.3. Eddy-current probe, PROM code, and calibration readings

Average and standard deviations of calibration readings (V) for each frequency						
	20 kHz		100 kHz		500 kHz	
	MAG1	PHA1	MAG2	PHA2	MAG3	PHA3
Probe 454, code 00						
S.D.	4.5004 0.0000	4.0004 0.0000	4.5022 0.0000	3.9945 0.0023	4.5023 0.0000	4.4958 0.0032
S.D.	2.4591 0.0023	3.9989 0.0032	2.3132 0.0000	3.9933 0.0000	2.4104 0.0016	4.4956 0.0045
α	4.2220	2.5743	3.5361	2.8298	3.6230	1.0296
Probe 460, code 01						
S.D.	4.4977 0.0045	4.0047 0.0032	4.4985 0.0032	4.0118 0.0032	4.5007 0.0000	4.4878 0.0064
S.D.	2.4601 0.0016	4.0047 0.0032	2.3095 0.0000	4.0103 0.0045	2.4042 0.0000	4.4864 0.0064
α	4.3142	3.0158	3.8659	2.9747	3.7303	1.0510
Probe 459, code 02						
S.D.	4.4974 0.0045	4.0006 0.0045	4.4976 0.0000	4.0110 0.0084	4.5197 0.0032	4.4953 0.0084
S.D.	2.4592 0.0000	3.9997 0.0032	2.3090 0.0016	4.0176 0.0055	2.4158 0.0016	4.4947 0.0084
α	4.5155	2.9760	4.1346	2.9136	4.1158	0.9058

^aReadings from nominal tube sample.

- b. Perform Test on Sheath Weld -- Record the data on both analog and magnetic tape recorders.
- c. Postcalibration -- Check the calibration standard and record the data on both analog and magnetic tape recorders.

These steps are described in detail in the following sections.

5. PRECALIBRATION

5.1 Install a new magnetic tape on the tape transporter and label the trailing end of the BOT marker with "1."

5.2 Place the inner surface calibration standard (tube 1) in the probe drive unit and center the probe over the area marked "start."

5.3 Operate the "reset" switch on the RCB. (Check for the correct coefficient code on the control module.)

5.4 Set the RCB function switch to \emptyset . Switch the magnetic tape recorder buffer to "record" and place the transporter "on line."

5.5 Operate the "interrupt" switch on the RCB. The instruction "enter ID" will appear on the video display. Enter the following information from the keyboard: PRE-CAL, standard number, date, superconductor number, probe number, and code.

5.6 Operate the 5-mm/s chart speed switch on the analog recorder.

5.7 Press the "return" key on the keyboard. The eddy-current computer will perform a recalibration and display the raw magnitude and phase readings along with the calculated coefficients on the video terminal. At the end of the display, the computer enters the "running" mode, and the eddy-current system starts recording data. Raw data are presented to the magnetic tape recorder, and calculated data are presented to the analog (strip-chart) recorder. (The data will be recorded only if the respective recorder is activated.)

5.8 Start the probe drive mechanism.

5.9 Using a slow and steady speed, manually pull the standard tube through the probe drive unit. Maintain the alignment of the weld on top of the tube and centered under the eddy-current probe.

5.10 Observe the analog recorder as you pull the standard tube through the drive unit. All five defect channel recorder pens should write between 5 and 25 minor divisions [-0.25 to $+0.76$ mm (-0.010 to $+0.030$ in.)] to the left of the right-hand margin on the recorder chart except when defect indications are obtained. (Inside-surface defects are recorded on the analog recorder.) Note: Signals greater than 0.76 mm (0.030 in.) (15 divisions) on the recorder chart should operate the indication marker that identifies the area on the superconductor sheath where the indication is located.

5.11 Identify this recording on the analog recorder as the "Precalibration Test" and record the date, the examiner's initials, and the identification of the superconductor sheath being examined.

5.12 When the precalibration of tube 1 is complete:

- a. Set the RCB function switch to 1.
- b. Stop the analog chart recorder and the probe drive mechanism.
- c. After the EOF on the buffer illuminates, switch the magnetic tape recorder to "off line." Operate reset on the RCB.
- d. Add a new BOT marker at "tape cleaner" and the outside edge of the tape. Turn the transporter off, rewind the tape reel about 1 turn, and turn the transporter on. Operate the "load" switch; the transporter should advance the tape to the new BOT marker. Label the BOT marker "A," and repeat steps 5.3 through 5.12 using the inner surface standard. Be sure to add a new BOT marker after standard A. Remove the tape reel and label as follows: "Standard Readings for Conductor Identity _____, Date _____, and Probe Identity _____."

6. PERFORM THE TEST

6.1 Place the probe drive unit on the superconductor cable, position the drive unit against the stop on the mill, and reconnect V-block and spring.

6.2 Turn on the probe drive mechanism and let it run for a brief period to assure that it operates freely and correctly.

6.3 Operate the "reset" switch on the RCB.

6.4 Set the RCB function switch to \emptyset .

6.5 Prepare magnetic tape recorder:

- a. Install a new tape reel.
- b. Verify "write" enable.
- c. Check for correct "BOT" position.
- d. Set selector switch on buffer to "record."
- e. Set transporter to "on line" and verify.

Note: Never operate a "reset" switch when the magnetic tape recorder is on-line and in the "record" mode.

6.6 Operate the "interrupt" switch on the RCB. The instruction "enter ID" will appear on the video display, and the EOF enable indicator will go out.

6.7 Type in the test identification (ID) on the keyboard as follows and in order: (date, AIRCO + tube number, and eddy-current probe serial number and PROM coefficient code).

Probe serial number	454	460	459
PROM coefficient code	00	01	02

6.8 Manually hold the eddy-current probe off the tube until the plug at the start of the superconductor is about 0.30 m (12 in.) away from the first drive unit rollers. Then seat the probe holder and

- a. turn on the probe drive control,
- b. press the "return" key on the keyboard,
- c. operate the 5-mm/s chart speed switch on the analog recorder.

The eddy-current computer will perform a recalibration and display the magnitude and phase readings along with the calculated coefficients on the video terminal.

At the end of the display, the computer enters the "running" mode, and the eddy-current system starts recording data. Raw data are recorded on the magnetic tape recorder, and calculated data are recorded on the analog (strip-chart) recorder.

6.9 Observe the analog recorder. All six recorder pens should write on scale on the recorder chart. If the pen on one of the defect channels goes off scale and stays, press the "zero" switch on the RCB to bring all

defect channels back to the zero reference line on the recorder. Record the time of this "zero" shift along with the operator's initials on the analog recorder chart and in the eddy-current log book.

6.10 Observe the equipment as the test is being conducted to make sure that all systems operate correctly. Watch for probe wear. Check both recorders periodically to see that they are recording properly and that the recorder pens remain on scale. If test indications are obtained, check the indication marker to see that it correctly identifies the area on the sheath. Record any unusual events (such as power outages and equipment breakdowns) on the chart and in the log book.

6.11 When the test is complete, do the following:

- a. Set the RCB function switch to 1.
- b. Turn off the analog recorder drive and probe drive mechanism.
- c. Remove the probe drive unit from the superconductor cable.

6.12 Check the magnetic tape recorder; the end-of-file (EOF) indicator should be lit.

- a. If the EOF indicator stays lit, you are ready to perform a post-calibration test (step 7.0).
- b. If the EOF indicator does *not* stay lit, there may be problems with the recorder or eddy-current computer, or both. In either case, make a record in the log book.
- c. Rewind the tape, remove it, label the tape reel, and remove the write ring.

7. POSTCALIBRATION

7.1 Replace the calibration tape made in step 5.

7.2 Advance the tape beyond the second BOT marker. Turn the recorder "off," then "on," and operate the "load" switch. The transporter should advance the tape to the third BOT marker and stop.

7.3 Repeat the calibration steps described in Section 5.

7.4 Place the calibration standard (identity) in the probe drive unit, and center the probe over the area marked "start."

7.5 Set the RCB function switch to \emptyset .

7.6 Operate the "interrupt" switch on the RCB. The instruction "enter ID" will appear on the video display.

7.7 Type in the test identification (ID) on the keyboard as follows and in order: (date, AIRCO + tube number, and eddy-current probe serial number). Note: Do *not* operate a "reset" switch when the magnetic tape recorder is "on-line" and in the "record" mode.

7.8 Operate the 5-mm/s chart speed switch on the analog recorder.

7.9 Press the "return" key on the keyboard. The eddy-current computer will perform a recalibration and display the raw magnitude and phase readings along with the calculated coefficients on the video terminal similar to step 4.7 of this procedure. At the end of the display, the computer enters the "running" mode and the eddy-current system starts recording data.

7.10 Start the probe drive mechanism.

7.11 Using a slow and steady speed, manually pull the standard tube through the probe drive mechanism. Maintain the alignment of the weld on top of the tube and centered under the eddy-current probe.

7.12 Observe the analog recorder as you pull the standard tube through the drive unit. All five defect channel recorder pens should write between 5 and 25 minor divisions [-0.25 to $+0.76$ mm (-0.010 to $+0.030$ in.)] to the left of the right-hand margin on the recorder chart except when defect indications are obtained. If not, recheck the recorder calibration and zero reference settings.

7.13 Identify this recording on the analog recorder as the "Postcalibration Test" and record the date, the examiner's initials, and the identification of the superconductor sheath being examined.

8. WHEN THE POSTCALIBRATION TEST IS COMPLETE, DO THE FOLLOWING

8.1 Set the RCB function switch to 1.

8.2 Stop the analog recorder drive and the probe drive mechanism.

8.3 Check the magnetic tape recorder. The EOF indicator should be lit. If it is, proceed to the next step. If it does not light, wait a brief period. If it still does not light, check for problems and mention this in the log book.

8.4 Operate "rewind" switch on transporter. At this point, either remove or read the tape per instructions in Supplement 1. To remove the tape, operate the "rewind" switch again and remove the tape reel when rewinding is complete. Remove the "write" ring from the tape reel and save. Place a protective collar over the tape reel. Identify the tape reel.

If there are no more tests to perform, turn all power off and secure the equipment.

Supplement 1 (to Appendix F)

TAPE RECORDER OPERATION

1. GENERAL

The read and record operations of this tape recorder are performed with the aid of computers. The read computer is located in the transceiver unit, while the record computer is in the eddy-current instrument. In order to read a tape, the read computer must have the same program (EPROM 0800 and 1000) in it that was in the record computer when the tape was written. Do not operate the "reset" switch on the remote control box (RCB) or the control module in the eddy-current instrument if the transporter is "on-line" and the buffer mode switch is on "record." This causes the record computer to lose synchronization with the tape position. The tape beyond the point where the "reset" switch is operated cannot be read from this tape recorder.

2. LOAD TAPE ON THE TRANSPORTER

2.1 Turn on the power to the transport and buffer. A 30-min warm-up period is recommended.

2.2 Remove write ring if reading a prerecorded tape.

2.3 Install the write ring if writing on a prerecorded tape or leave the write ring in place if writing on a new tape. (The write ring is a plastic insert on the back of the reel.)

2.4 Seat the tape reel on the supply hub, push the hub in, and thread the tape as shown on the transporter. The power to the transporter should be on and the "load" lamp out when the tape is being threaded.

2.5 Operate the "load" switch to advance the tape to the beginning of tape (BOT) marker. The BOT marker is a piece of reflective tape, 25 by 6 mm (1 × 1/4 in.), on the outside edge of the tape.

2.6 The "write enable" or "write ring" lamp will be on if the write ring is in place.

3. RECORDING ON TAPE

3.1 Do not operate the "reset" switch on the RCB or on the control module in the eddy-current instrument if the transporter is "on line" and the buffer mode switch is on "record."

3.2 Set the selector switch on the transceiver unit to "DX."

3.3 Operate the "reset" switch on the RCB (transporter "off line").

3.4 Set the function switch on the RCB to "Ø."

3.5 Select "record" on the buffer mode switch.

3.6 Set the function switch on the control module in the eddy-current instrument according to the eddy-current probe being used (see Table F.3).

3.7 Operate the "on line" switch on the transporter. The EOF switch should illuminate, the "on line" light should illuminate, and the tape should advance smoothly. If all three actions do not occur, operate "rewind" and try again. This indicates that the EOF is enabled, both buffers are empty, and the tape recorder is ready to receive data.

3.8 Operate the "INT" switch on the RCB. The EOF enable should go out, and "enter ID" will be printed on the video display.

3.9 Type one space, then enter the correct test identification data and probe serial number.

3.10 Operate the keyboard "return" key when you are ready to start recording on the tape. The record computer in the eddy-current instrument will be acquiring and recording the data. The transporter should advance the tape in smooth rhythmic steps.

3.11 To stop the test, select "1" on the RCB. The computer will fill the last buffer and transfer the buffer contents onto the tape. The EOF enable will illuminate to indicate that both buffers are empty. The computer will then issue a write end-of-file (WRT EOF) command. The tape recorder will record an EOF. The EOF enable light will go out, the tape will advance, and EOF enable will illuminate again, and verify will be indicated with a period followed by the cursor on the video display. The tape recorder will stop and await further instructions.

3.12 Operate the "on line" switch to "off line."

4. REWIND TAPE

4.1 Operate the "rewind" switch. The transporter will rewind the tape until the BOT marker is located and then stop.

4.2 Operate the "rewind" switch again. The transporter will rewind the remaining portion of the tape and stop.

4.3 Pull the supply hub out to unlock the reel and remove the tape.

4.4 Place the protective collar around the reel.

4.5 Identify the reel.

4.6 Remove the write ring.

5. READ TAPE

5.1 Equipment required:

- a. Transporter
- b. Buffer
- c. Terminal
- d. Transceiver unit
- e. Strip-chart recorder

5.2 Remove the strip-chart recorder cable from the eddy-current instrument and connect to C2 of the transceiver unit.

5.3 Remove the write ring from the reel.

5.4 Seat the reel on the supply hub, push the hub in, and thread the tape as shown on the transporter. The power to the transporter should be on and the "load" lamp out when the tape is being threaded.

5.5 Operate the "load" switch on the transporter to advance the tape to the beginning of tape (BOT) marker.

5.6 Select "local" on the transceiver unit selector switch.

5.7 Set the function switch on the transceiver unit to "1."

5.8 Operate the "reset" switch on the transceiver unit. "NDT COMP9" should be displayed on the terminal.

5.9 Operate the "INT" switch on the transceiver unit. The following will be displayed on the video screen: "switch tape to read, on line."

5.10 Select "read" on the buffer mode switch.

5.11 Operate the "on line" switch on the transporter. The "on line" light should illuminate. The tape should advance smoothly.

5.12 Respond to statement printed on the CRT. Type in one of four codes — 0, 1, 2, 3 — and operate the return key on the keyboard.

5.13 The tape will be read, and calculated data will be recorded on the strip-chart recorder.

5.14 To prevent damage to the tape, remove it from the transporter and replace the protective collar.

5.15 Turn off equipment.

Appendix G

PROCEDURE TO CHECK DIGITAL RECORDING SYSTEM

This procedure describes the operation of the digital recording system for the superconductor sheath weld inspection and describes the steps necessary to check the operation of the system before performing the eddy-current inspection. The computer program CHECK associated with this test is described in Appendix H. The procedure is self-explanatory but should be read completely before attempting the check.

1.0 GENERAL

The following is a description of the digital recording system and the steps necessary to check the operation of the system.

Refer to Fig. G.1, block diagram of the digital recording system. Each multifrequency eddy-current (MFEC) test system has two identical microcomputer circuit boards, one located in the control module of the eddy-current instrument and one in the transceiver unit. A computer program designed to check the operation of the digital recording system is stored on PROM chips in each microcomputer circuit board. The two PROM chips are identical and interchangeable.

Initiation of the program starts a counting program in each computer that counts (in hexadecimal) from 0000 to FFFF. The four-digit hexadecimal number that is generated is described in Fig. G.2. The low byte (X_1 and X_2) represent the count (from 00 to FF), and the high byte (X_3 and X_4) represent the number of times the count has been repeated.

The low byte is transmitted through the transceiver unit and through the "write" portion of the logic package to the tape transporter, where it is stored on magnetic tape. When the tape is played back, the data bytes are transmitted from the magnetic tape through the "read" portion of the logic package to the computer board located in the transceiver.

The computer program in the transceiver unit generates a four-digit hexadecimal count identical to the one generated by the control module microcomputer. When the data bytes stored on magnetic tape are received by the computer in the transceiver unit, they will be compared with the

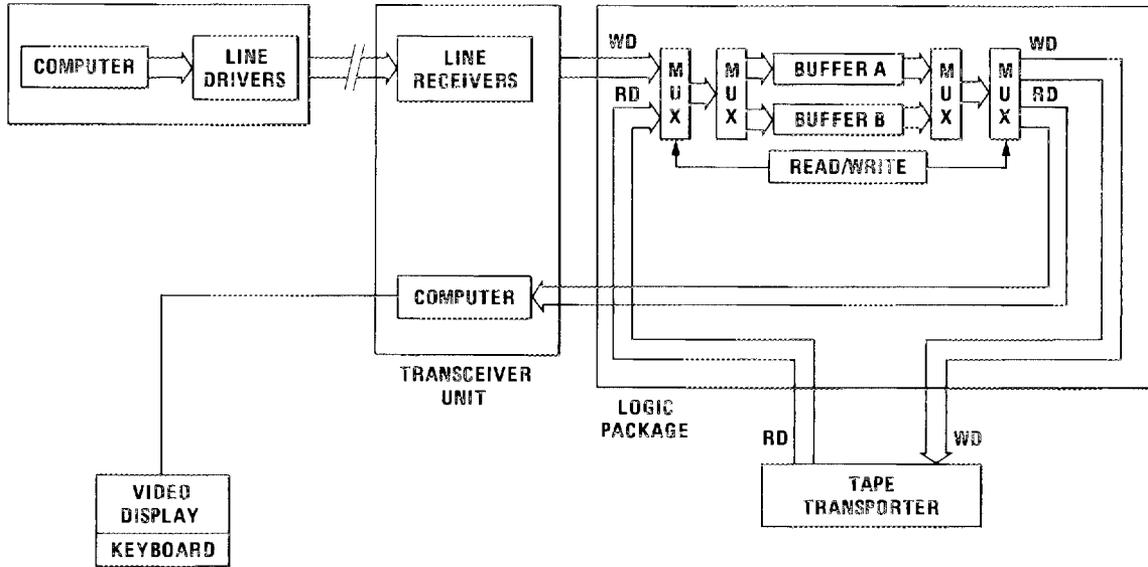
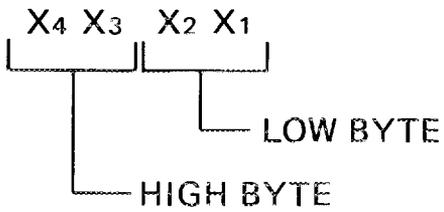


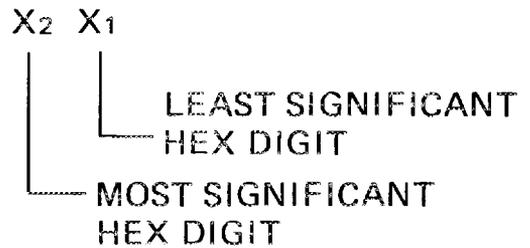
Fig. G.1. Block diagram of the digital recording system.

FIRST COLUMN SET



COUNT NUMBER

SECOND COLUMN SET



DATA BYTE

Fig. G.2. Video display of the hexadecimal numbers.

corresponding low byte generated by the count program in the transceiver microcomputer, and either one or two columns of data will be displayed on the video terminal.

If the two bytes are identical, then only the one column set of four hex numbers (the transceiver computer count number) will be displayed on the video terminal. If the received byte is not identical with the low byte generated by the transceiver computer, a second column set of two hex digits (the data byte) will be displayed on the video terminal. The appearance of the second column set of data is a positive indication that something is wrong in the digital recording system. The manner in which the numbers are presented in the second column set of data provides information that can be used to determine the general location of the problem.

To use the information presented in the second column set, the operator must understand hexadecimal and binary numbers and have a general knowledge of how the recording system works. The following is a brief description of how the system works (refer to Fig. G.1).

The data bytes (X_1 and X_2) are transmitted from the control module over the respective data lines (Fig. G.3) to the two recorder buffers, A and B. The same buffers are used to "write" data on the magnetic tape and to "read" data off the tape. The two buffers are like one-way streets, and data always travel through the buffers in the same direction whether the recorder is reading or writing.

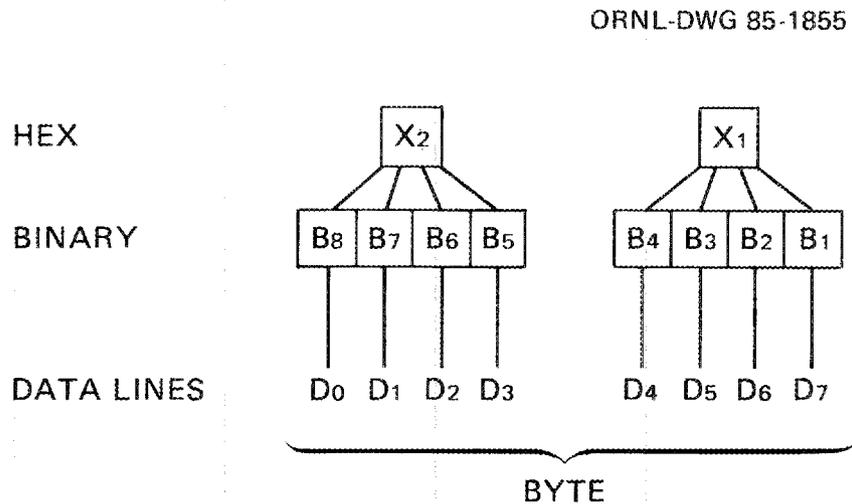


Fig. G.3. Eight data lines used to transmit two hexadecimal digits.

A single buffer has a limited capacity for data. When a buffer is filled with data, it must dump those data onto the next process in the system before it can accept more data. If only one buffer is used, no data can be transferred into or out of the recorder while the buffer is dumping. If two buffers are used, then one buffer can be receiving data while the other is dumping, and the recording process is continuous. The multiplexers select which buffer receives data according to the amount of data received. The program always starts with buffer A; when that buffer is filled, the multiplexer will switch to buffer B. By the time buffer B is filled, buffer A will be ready to receive data. Each buffer can hold 4K of memory (0FFF in hexadecimal). Table G.1 shows the four-digit hexadecimal count and which buffer will be used. If one of the buffers is not operating, for example, then all the data bytes transmitted through that buffer will be incorrect and will differ from the count number. Incorrect hex numbers will be printed in the second column set on the video display.

Table G.1. Recorder buffers used for particular sets of hexadecimal numbers

Hexadecimal count	Buffer used	Hexadecimal count	Buffer used
0000-0FFF	A	8000-8FFF	A
1000-1FFF	B	9000-9FFF	B
2000-2FFF	A	A000-AFFF	A
3000-3FFF	B	B000-BFFF	B
4000-4FFF	A	C000-CFFF	A
5000-5FFF	B	D000-DFFF	B
6000-6FFF	A	E000-EFFF	A
7000-7FFF	B	F000-FFFF	B

Four binary digits are required to express each hexdigit (see Fig. G.3); therefore, eight data lines are required to transmit one data byte through the recording system. These data lines are fixed (hard wired) and will always represent the same binary digit; therefore, if a

particular binary digit is missing in the output data, we can trace it back to a particular data line, and this will help locate the problem.

By examination of the data in the second column set displayed on the video screen, the operator can determine if the digital recording system is operating properly or not, and, if not, he can determine whether the problem is in one of the buffers or a data line and can isolate which buffers or which data line is not operating properly. In addition, the program will let the operator know if the problem is caused by an operator error.

2. EQUIPMENT REQUIRED

- Eddy-current instrument
- Transceiver unit
- Remote control box (RCB)
- Tape transporter
- Tape buffer logic package
- Video terminal

3. INITIAL SETUP

- 3.1 Apply power to the equipment.
- 3.2 Operate the select switch to "DX" on the transceiver unit.
- 3.3 Operate the reset switch on the RCB and verify response (NDT-COMP9) on the video terminal.

4. SET UP TAPE RECORDER

- 4.1 Select a new reel of magnetic tape, make sure the write ring is properly in place, and install the reel on the transporter.
- 4.2 Operate the select switch to "record" on the buffer logic package.
- 4.3 Operate the "load" switch on the transporter (tape will advance to BOT marker).
- 4.4 Verify that the "WRITE ENABLE" lamp is illuminated.
- 4.5 Operate the "ON LINE" switch on the transporter and verify that the EOF lamp on the buffer logic package is illuminated.

5. STORE THE DATA ON MAGNETIC TAPE

5.1 Type G154A and carriage return on the keyboard. The EOF lamp should go out; the terminal will display the prompt "Hit carriage return to start."

5.2 Respond to the prompt on the video terminal (type a carriage return). The transporter should begin advancing tape in rhythmic steps and will continue for 1 to 2 min. Data generated by the counting program in the control module computer are stored on the magnetic tape. When this program loop is completed, the transporter will stop advancing and the EOF lamp on the buffer will illuminate. The line "rewind, SW to local, read, G158F, on line, CR to start" will be displayed on the terminal. *Do not respond at this time; go to the next step.*

6. IDENTIFY AND REWIND THE TAPE

6.1 Operate the "EOF" switch on the buffer logic package. This will write an "END OF FILE" mark on the magnetic tape, and the tape will be advanced a short length. Operate the "EOF" switch again to place a second "END OF FILE" mark on the tape.

6.2 Operate the "ON LINE" switch on the transporter to "OFF LINE."

6.3 Install a BOT marker on the outer edge of the tape in the area near the tape cleaner.

6.4 Operate the "REWIND" switch on the transporter.

6.5 Identify the BOT marker at the start of the record.

7. PLAY THE TAPE BACK AND CHECK THE DIGITAL RECORDING SYSTEM

7.1 Operate the select switch to "READ" on the buffer logic package.

7.2 Operate the select switch to "LOCAL" on the transceiver unit.

7.3 Operate the "RESET" switch on the transceiver unit and verify response (NDT-COMP9) on the video terminal.

7.4 Type G158F and a carriage return on the keyboard.

7.5 Operate the "ON LINE" switch on the transporter.

7.6 Press the "CARRIAGE RETURN" key on the keyboard. A check of the digital recording system will begin. A column set of four hexadecimal

numbers counting from 0000 to FFFF will be displayed on the video terminal. The total display will take about 9 min. The count can be stopped by pressing any character on the keyboard and can be resumed by pressing the "CARRIAGE RETURN" key.

The manner in which these data are displayed on the video terminal lets the operator know whether the digital recording system is operating properly or not. If the digital recording is not operating properly, a second column set of two hexadecimal numbers will be displayed on the video terminal. Perform the following data checks in the order listed to localize the problem area.

CHECK 1: LOOK FOR THE SECOND COLUMN OF NUMBERS

If only one column set of four hexadecimal numbers is displayed, and the numbers count from 0000 to FFFF, the digital recording system is operating properly and is ready for use.

All other checks apply to conditions under which a second column set of two hexadecimal numbers is printed out on the video terminal and some problem exists.

CHECK 2: EXAMINE THE LEAST SIGNIFICANT HEX DIGIT (LSHD) (RIGHT NUMBER) IN THE SECOND COLUMN SET

a. If the LSHD (X_1) in the second column set increases consecutively from 0 to F, and the number is one higher than the respective hex digit in the first column set, the problem is operational. Return to step 3.2 of this procedure and repeat the procedure.

b. If the LSHD in the second column set does not increase consecutively or if certain numbers are skipped, determine which numbers are skipped and go to check 3.

NOTE: If the data byte is properly transmitted through the digital recording system and if it properly matches the low byte in the count generated by the transceiver, no data will be displayed in the second column set. This will be true for all or part of the data transmitted.

CHECK 3: EXAMINE THE MOST SIGNIFICANT HEX DIGIT (MSHD) (LEFT NUMBER) IN COLUMN 2

a. Determine whether the MSHD (X_2) in the second column set matches the corresponding hex digit (X_2) in the first column set; also determine if any digits are skipped.

b. Arbitrarily select two or three values of X_2 and X_1 from the first column set and the second column set and write them down on a sheet of paper.

c. Convert the two sets of hex numbers into their binary equivalents in the manner shown in Fig. G.3.

d. Examine the binary digits to see if one or more remain set at 0 or 1 throughout the count. Also determine if that digit can explain the difference in the count between the two column sets. If so, the problem is in the data line corresponding to that binary digit (Fig. G.3).

CHECK 4: CHECK THE BUFFERS

If one of the buffers is bad, the data in the second column set will be discontinuous, and large sets of numbers will appear to be missing. The missing numbers will correspond to the good buffer. (If data are properly transmitted through the digital recording system, no values will appear in the second column set.) The bad buffer can be determined by relating the hex digit (X_4) in the second column set to the corresponding hex digit (X_4). If X_4 in the second column set is zero or an even number (hexadecimal), the problem is in buffer A. If X_4 is an odd number, the problem is in buffer B.

To check the buffers, let the data count run long enough to make sure that some numbers are (or are not) getting through each buffer.

If any numbers get through a particular buffer, that buffer can be assumed to be operating properly.

Appendix H
PROGRAM CHECK

The program CHECK (written in machine language) generates counting programs in the two microcomputers located in the control module and the transceiver units of the MFEC instrument. Each counting program generates a set of hexadecimal numbers from 0000 to FFFF. The hex numbers generated in the control module microcomputer are transmitted through the transceiver unit and tape buffers to the tape transporter, where they are recorded by the magnetic tape recorder. The numbers are then read back from the magnetic tape through the tape buffers and transceiver unit and are compared with the number set generated by the transceiver unit microcomputer. The results of the comparison are displayed on the video terminal. If the two sets of hex numbers are exactly identical, then only one column set of four numbers (0000 to FFFF) will be displayed. If the two sets of numbers are not identical, a second column set of two numbers (00 to FF) will be displayed. This procedure provides a means to check the operation of the digital recording system, including the magnetic tape recorder. The procedure that outlines the steps required to perform this system check is provided in Appendix G.

```

1          TITLE 'COMP9 CHECKOUT PROGRAM VERSION 12 APRIL 84'
2          LIST  D,C,D,T
3          ;      LIST  I,M,S
4          ORG 2000H          START PROGRAM IN 5TH PROM.
5          ; SYMBOL DEFINITIONS
6          ;
7          ; DEFINE PORT ADDRESSES
8          ; NORMAL COMP9 PORT ADDRESSES
9          ;
10         ;PORT1      EQU 0F7H          PORT 1 CONTROL WORD ADDRESS
11         ;PORT1A     EQU 0F8H          PORT1A ADDRESS
12         ;PORT1D     EQU 0F9H          PORT1D ADDRESS
13         ;PORT1C     EQU 0FAH          PORT1C ADDRESS
14         ;PORT2      EQU 0E7H          PORT 2 CONTROL WORD ADDRESS
15         ;PORT2A     EQU 0E8H          PORT2A ADDRESS
16         ;PORT2B     EQU 0E9H          PORT2B ADDRESS
17         ;PORT2C     EQU 0EAH          PORT2C ADDRESS
18         ;PORT3      EQU 0D7H          PORT 3 CONTROL WORD ADDRESS
19         ;PORT3A     EQU 0D8H          PORT3A ADDRESS
20         ;PORT3B     EQU 0D9H          PORT3B ADDRESS
21         ;PORT3C     EQU 0DAH          PORT3C ADDRESS
22         ;APDATA     EQU 07EH          ARITHMETIC PROCESSOR DATA PORT
23         ;USSTS      EQU 0F6H          USART CONTROL/STATUS ADDRESS
24         ;
25         ; PORT ADDRESSES FOR COMP9 WITH CP16 BOARD
26         ;
27         00CF      PORT1      EQU 0CFH          PORT 1 CONTROL WORD ADDRESS
28         00CC      PORT1A     EQU 0CCH          PORT1A ADDRESS
29         00CD      PORT1D     EQU 0CDH          PORT1D ADDRESS
30         00CE      PORT1C     EQU 0CEH          PORT1C ADDRESS
31         00D7      PORT2      EQU 0D7H          PORT 2 CONTROL WORD ADDRESS
32         00D4      PORT2A     EQU 0D4H          PORT2A ADDRESS
33         00D5      PORT2B     EQU 0D5H          PORT2B ADDRESS
34         00D6      PORT2C     EQU 0D6H          PORT2C ADDRESS
35         00E7      APDATA     EQU 0E7H          ARITHMETIC PROCESSOR DATA PORT
36         00EF      APSTAT     EQU 0EFH          ARITHMETIC PROCESSOR STATUS PORT
37         00C6      USCTS      EQU 0C6H          USART CONTROL/STATUS ADDRESS
38         00E7      RTCC0T0    EQU 0E7H          REAL TIME CLOCK CHANNEL
39         00E4      RTCC0T0    EQU 0E4H          REAL TIME CLOCK COUNTER 0
40         00E5      RTCC0T1    EQU 0E5H          REAL TIME CLOCK COUNTER 1
41         00E6      RTCC0T2    EQU 0E6H          REAL TIME CLOCK COUNTER 2,USED FOR BRUD RA
42         ;
43         00D0      BUSPRT     EQU 0D0H          EDGE ADDR OF CP16 LMS
44         00D8      BUSIN      EQU 0D8H          DATA IN FROM BUS LOCK
45         00D8      BUSOUT     EQU 0D8H          DATA OUT TO BUS LOCK
46         00D9      S1        EQU 0D9H          INTERRUPT STATUS REGISTER ADDR
47         00D9      INTEN1     EQU 0D9H          INTERRUPT ENABLE REGISTER 1 ADDR
48         0002      BSH        EQU 02          BYTE OUT INTR MASK,BYTE
49         ;
50         0001      DIN        EQU 01          BYTE IN INTR MASK,BYTE SHOULD
51         ;
52         0010      ENDIRK     EQU 10H          BE READ FROM LMSH REGISTER
53         0000      CPT        EQU 00H          END INTERRUPT MASK
54         ;
55         REG #2 INTERRUPTS

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55 00DA      INTER      EQU 00DAH      INTERRUPT REGISTER 2 ADDR
56          ;
57 00DC      ADDRMD     EQU 00DCH      ADDRESS MODE REGISTER ADDR
58 00DD      TON        EQU 00DDH      TALK ONLY, NOT LISTEN MODE
59 0040      LOH        EQU 0040H      LISTEN ONLY, NOT TALK MODE
60 00C0      TLOH       EQU 00C0H      TALK AND LISTEN ONLY MODE
61 0001      MODE1      EQU 01H        MODE 1 ADDRESSING
62          ;
63 00DC      ADST      EQU 00DCH      ADDRESS STATUS REGISTER ADDR
64 0020      EOYST     EQU 0020H      END OR IDENTIFY MASK
65 0002      TA        EQU 002H      TALKER ADDR OR ACT;SER POLL-TADS TACS SPAS
66 0004      LA        EQU 004H      LISTENER ADDRESSED OR ACTIVE-LADS OR LACS
67 0001      MJMN      EQU 01H        MAJOR OR MINOR TALKER/LISTENER, 1=MINOR
68          ;
69 00DD      AUXID     EQU 00DDH      AUXILLARY MODE REG ADDR
70 0022      CLKRT     EQU 0022H      CLOCK SET FOR 2MHZ
71 0003      FNHSHK    EQU 003H      FINISH HANDSHAKE AUX COMMAND
72 0006      SDEOI     EQU 006H      SEND END OR IDENTIFY WITH NEXT BYTE
73 0000      AXRA      EQU 0000H      WRITE DDDDD INTO AUX REGISTER A
74 0001      HOHSHK    EQU 01H        HOLD OFF HANDSHAKE ON ALL BYTES
75 0002      HOEND     EQU 002H      HOLD OFF HANDSHAKE ON END BYTE
76 0003      CAHCY     EQU 003H      CONTINUOUS ACCEPTOR HANDSHAKE CYCLING
77 0004      EDEDS     EQU 004H      END ON EOS RECEIVED DAT REG MATCHES EOS RE
78 0000      EOIS      EQU 000H      OUTPUT EOI ON EOS SENT
79 0040      EOSDC     EQU 0040H      EOS FUNCTIONS AS FULL 8-BIT REG
80 000F      VSCMD     EQU 000FH      VALID COMMAND PASS THROUGH
81 0007      HVCMD     EQU 007H      INVALID COMMAND PASS THROUGH
82 00A0      AKRS      EQU 0A0H      AUXILLARY REG B PATTERN
83 0001      CPTEN     EQU 01H        COMMAND PASS THROUGH ENABLE
84          ;
85 00DD      CPTRG     EQU 00DDH      ADDR TO READ COMMAND PASS THROUGH
86          ;
87 00DE      ADDR01    EQU 00DEH      ADDR 0/1 REG CONSTANTS
88 0060      DTDL1     EQU 0060H      COMP 9 GPIB ADDRESSES
89 00E0      DTDL2     EQU 00E0H      DISABLE MAJOR TALKER/LISTENER
90 0005      ADRTL     EQU 005H      DISABLE MINOR TALKER/LISTENER
91          ;
92 00DF      EOSR      EQU 00DFH      TALKER LISTENER ADDRESS SET TO 5
93          ;
94          ; SYMOL DEFINITIONS
95          ;
96 000D      CR        EQU 00DH      CARRIAGE RETURN DEFINED
97 000A      LF        EQU 00AH      LINE FEED DEFINED
98 0070      DISBLK    EQU 0070H      JUMP INTO DISPLAY DATA ROUTINE
99 0F60      RDTAP     EQU 0F60H      ADDRESS OF READ TAPE ROUTINE
100         ;
101         ; MATH SUBROUTINES FOR THE COMP 9 ARE STORED AS PUBLIC.ANY ROUTINE
102         ; CAN BE CALLED USING AN "EXTRN" STATEMENT.
103         ;
104         EXTRN      ADDS,ASIN,ATAN,ATANM,BIDEC,BIDECF
105         EXTRN      CHSD,CHSDA,CHSF,CHSFA,CHSS,CHSSA,COS,COSA
106         EXTRN      DADD,DADDA,DADD,DDIV,DDIVA,DDIVB,DECNO
107         EXTRN      DMUL,DMULA,DMULB,DMU,DMUA,DMUB,DSUB,DSUBA,DSUBB
108         EXTRN      EXP,EXPA,EXP10,FADD,FADDA,FADD,FDIV,FDIVA,FDIVB

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109          EXTRN          FIXD, FIXDA, FIXS, FIXSA, FLTD, FLTDA, FLTS, FLTSA
110          EXTRN          FMUL, FMULA, FMULB, FSUB, FSUBA, FSUBB, LN, LNA, LOG, LOGA
111          EXTRN          MDAD, NOP, POPD, POPS, PTOD, PTOS, PUP1, PUR, PURA, PURB
112          EXTRN          SADD, SADDA, SADDR, SDIV, SDIVA, SDIVB, SIF, SINA
113          EXTRN          SIUL, SMULA, SMULB, SNUU, SNUUA, SNUUB, SURT, SURTH
114          EXTRN          SSUB, SSUBA, SSUBB, TAN, TANA, TOS1, TOS2, TOS4
115          EXTRN          WRT1, WRT2, WRT4, XCHD, XCHS
116          EXTRN          CROUT, COPDT, GETCM, PRINT, PRINTF, EPRNT, FPRNT, ZERO
117          EXTRN
118          ;
119          ;          I/O PORTS CHECKOUT ROUTINE
120          ;          TRANSMITT FROM DATA PORT1 TO PORT2, FROM PORT1 TO
121          ;          PORT3, THEN BACK. PRINT OUT MESSAGE IF OK OR ERROR.
122          ;
123          2000 3E 00          CKPT1A          MVI A, 000H          PROGRAM PORT1A FOR ALL TRANSMITT
124          2002 D3 CF          OUT PORT1
125          2004 3E 9B          MVI A, 000H          PROGRAM WORD FOR RECEIVE
126          2006 D3 D7          OUT PORT2          PORT2 PROGRAMED TO RECIEVE
127          ;          OUT PORT3          PORT3 PROGRAMED TO RECIEVE
128          2008 16 00          MVI D, 0          D REG ZEROED
129          200A 06 0C          MVI B, 12          LENGTH OF MESSAGE IN D
130          200C 7A          LOP1          MOV A, D          MOVE FROM D REG TO A REG
131          200D D3 CC          OUT PORT1A          OUTPUT TO PORT1A
132          200F AF          XRA A          ZERO ACCUMULATOR
133          2010 DB D4          IN PORT2A          INPUT FROM PORT2A
134          2012 BA          CIP D          REG A COMPARED TO REG D
135          2013 C2 62 21          JNZ E12A          JUMP TO ERROR IF NOT EQUAL
136          2016 14          INR D          INCREMENT D REG
137          2017 C2 0C 20          JNZ LOP1          LOOP BACK IF NOT DONE
138          201A 21 AB 22          LXI H, POK1A          OK MESSAGE FOR PORT1A
139          201D CD 58 21          CALL PRTOK          PRINT MESSAGE
140          2020 3E 00          CKPT1B          MVI A, 000H          PROGRAM PORT1B FOR ALL TRANSMITT
141          2022 D3 CF          OUT PORT1
142          2024 3E 9B          MVI A, 000H          PROGRAM WORD FOR RECEIVE
143          2026 D3 D7          OUT PORT2          PORT2 PROGRAMED TO RECIEVE
144          2028 16 00          MVI D, 0          D REG ZEROED
145          202A 06 0C          MVI B, 12          LENGTH OF MESSAGE IN D
146          202C 7A          LOP2          MOV A, D          MOVE FROM D REG TO A REG
147          202D D3 CD          OUT PORT1B          OUTPUT TO PORT1B
148          202F AF          XRA A          ZERO ACCUMULATOR
149          2030 DB D5          IN PORT2B          INPUT FROM PORT2B
150          2032 BA          CIP D          REG A COMPARED TO REG D
151          2033 C2 6B 21          JNZ E10B          JUMP TO ERROR IF NOT EQUAL
152          2036 14          INR D          INCREMENT D REG
153          2037 C2 2C 20          JNZ LOP2          LOOP BACK IF NOT DONE
154          203A 21 07 22          LXI H, POK1B          OK MESSAGE FOR PORT1B
155          203D CD 58 21          CALL PRTOK          PRINT MESSAGE
156          2040 3E 00          CKPT1C          MVI A, 000H          PROGRAM PORT1C FOR ALL TRANSMITT
157          2042 D3 CF          OUT PORT1
158          2044 3E 9B          MVI A, 000H          PROGRAM WORD FOR RECEIVE
159          2046 D3 D7          OUT PORT2          PORT2 PROGRAMED TO RECIEVE
160          2048 16 00          MVI D, 0          D REG ZEROED
161          204A 06 0C          MVI B, 12          LENGTH OF MESSAGE IN D
162          204C 7A          LOP3          MOV A, D          MOVE FROM D REG TO A REG

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163	204D	D3	CE	OUT PORT1C	OUTPUT TO PORT1C
164	204F	AF		XRA A	ZERO ACCUMULATOR
165	2050	DB	D6	IN PORT2C	INPUT FROM PORT2C
166	2052	BA		CMF D	REG A COMPARED TO REG D
167	2053	C2	74 21	JNZ E12C	JUMP TO ERROR IF NOT EQUAL
168	2056	14		INR D	INCREMENT D REG
169	2057	C2	4C 20	JNZ LOP3	LOOP BACK IF NOT DONE
170	205A	21	C3 22	LXI H,POK1C	OK MESSAGE FOR PORT1C
171	205D	CD	58 21	CALL PRTOK	PRINT MESSAGE
172	2060	3E	90	MVI A,000H	PROGRAM PORT2A FOR ALL TRANSMITT
173	2062	D3	D7	OUT PORT2	
174	2064	3E	9B	MVI A,090H	PROGRAM WORD FOR RECEIVE
175				OUT PORT3	PORT3 PROGRAMED TO RECIEVE
176	2066	D3	CF	OUT PORT1	PORT1 PROGRAMED TO RECIEVE
177	2068	16	00	MVI D,0	D REG ZEROED
178	206A	06	0C	MVI B,12	LENGTH OF MESSAGE IN B
179	206C	7A		MOV A,D	MOVE FROM D REG TO A REG
180	206D	D3	D4	OUT PORT2A	OUTPUT TO PORT2A
181	206F	AF		XRA A	ZERO ACCUMULATOR
182	2070	DB	CC	IN PORT1A	INPUT FROM PORT1A
183	2072	BA		CMF D	REG A COMPARED TO REG D
184	2073	C2	7D 21	JNZ E21A	JUMP TO ERROR IF NOT EQUAL
185	2075	14		INR D	INCREMENT D REG
186	2077	C2	6C 20	JNZ LOP4	LOOP BACK IF NOT DONE
187	207A	21	F3 22	LXI H,POK2A	OK MESSAGE FOR PORT2A
188	207D	CD	58 21	CALL PRTOK	PRINT MESSAGE
189	2080	3E	80	MVI A,000H	PROGRAM PORT2B FOR ALL TRANSMITT
190	2082	D3	D7	OUT PORT2	
191	2084	3E	9B	MVI A,090H	PROGRAM WORD FOR RECEIVE
192	2086	D3	CF	OUT PORT1	PORT1 PROGRAMED TO RECIEVE
193	2088	16	00	MVI D,0	D REG ZEROED
194	208A	06	0C	MVI B,12	LENGTH OF MESSAGE IN B
195	208C	7A		MOV A,D	MOVE FROM D REG TO A REG
196	208D	D3	D5	OUT PORT2B	OUTPUT TO PORT2B
197	208F	AF		XRA A	ZERO ACCUMULATOR
198	2090	DB	CD	IN PORT1B	INPUT FROM PORT1B
199	2092	BA		CMF D	REG A COMPARED TO REG D
200	2093	C2	06 21	JNZ E21B	JUMP TO ERROR IF NOT EQUAL
201	2096	14		INR D	INCREMENT D REG
202	2097	C2	0C 20	JNZ LOP5	LOOP BACK IF NOT DONE
203	209A	21	FF 22	LXI H,POK2B	OK MESSAGE FOR PORT2B
204	209D	CD	58 21	CALL PRTOK	PRINT MESSAGE
205	20A0	3E	80	MVI A,000H	PROGRAM PORT2C FOR ALL TRANSMITT
206	20A2	D3	D7	OUT PORT2	
207	20A4	3E	9B	MVI A,090H	PROGRAM WORD FOR RECEIVE
208	20A6	D3	CF	OUT PORT1	PORT1 PROGRAMED TO RECIEVE
209	20A8	16	00	MVI D,0	D REG ZEROED
210	20AA	06	0C	MVI B,12	LENGTH OF MESSAGE IN B
211	20AC	7A		MOV A,D	MOVE FROM D REG TO A REG
212	20AD	D3	D6	OUT PORT2C	OUTPUT TO PORT2C
213	20AF	AF		XRA A	ZERO ACCUMULATOR
214	20B0	DB	CE	IN PORT1C	INPUT FROM PORT1C
215	20B2	BA		CMF D	REG A COMPARED TO REG D
216	20B3	C2	0F 21	JNZ E21C	JUMP TO ERROR IF NOT EQUAL

217	2006	14	INR D	INCREMENT D REG
218	2007	C2 AC 20	JNZ LOOP	LOOP BACK IF NOT DONE
219	200A	21 00 23	LXI H,PORTC	OK MESSAGE FOR PORTC
220	200D	0D 58 21	CALL PRINTK	PRINT MESSAGE
221			;DKPTCA: LXI B,COUNT	PROGRAM PORTC FOR ALL TRANSMIT
222			; OUT PORTC	
223			; MVI A,000H	PROGRAM SEND FOR RECEIVING
224			; OUT PORT1	PORT1 PROGRAMED TO RECEIVE
225			; OUT PORT2	PORT2 PROGRAMED TO RECEIVE
226			; MVI D,0	D REG ZEROED
227			; MVI B,12	LENGTH OF MESSAGE IN D
228			;LOOP: MOV A,D	MOVE FROM D REG TO A REG
229			; OUT PORT0A	OUTPUT TO PORT0A
230			; XRA A	ZERO ACCUMULATOR
231			; IN PORT1B	INPUT FROM PORT1B
232			; CMP D	REG A COMPARED TO REG D
233			; JNZ E01H	JUMP TO ERROR IF NOT EQUAL
234			; INR D	INCREMENT D REG
235			; JNZ LOOP	LOOP BACK IF NOT DONE
236			; LXI H,PORTA	OK MESSAGE FOR PORTA
237			; CALL PRINTK	PRINT MESSAGE
238			;DKPTCB: LXI B,COUNT	PROGRAM PORTC FOR ALL TRANSMIT
239			; OUT PORTC	
240			; MVI A,000H	PROGRAM SEND FOR RECEIVING
241			; OUT PORT1	PORT1 PROGRAMED TO RECEIVE
242			; MVI D,0	D REG ZEROED
243			; MVI B,12	LENGTH OF MESSAGE IN D
244			;LOOP: MOV A,D	MOVE FROM D REG TO A REG
245			; OUT PORT0B	OUTPUT TO PORT0B
246			; XRA A	ZERO ACCUMULATOR
247			; IN PORT1B	INPUT FROM PORT1B
248			; CMP D	REG A COMPARED TO REG D
249			; JNZ E01H	JUMP TO ERROR IF NOT EQUAL
250			; INR D	INCREMENT D REG
251			; JNZ LOOP	LOOP BACK IF NOT DONE
252			; LXI H,PORTC	OK MESSAGE FOR PORTC
253			; CALL PRINTK	PRINT MESSAGE
254			;DKPTCC: LXI B,COUNT	PROGRAM PORTC FOR ALL TRANSMIT
255			; OUT PORTC	
256			; MVI A,000H	PROGRAM SEND FOR RECEIVING
257			; OUT PORT1	PORT1 PROGRAMED TO RECEIVE
258			; MVI D,0	D REG ZEROED
259			; MVI B,12	LENGTH OF MESSAGE IN D
260			;LOOP: MOV A,D	MOVE FROM D REG TO A REG
261			; OUT PORT0C	OUTPUT TO PORT0C
262			; XRA A	ZERO ACCUMULATOR
263			; IN PORT1C	INPUT FROM PORT1C
264			; CMP D	REG A COMPARED TO REG D
265			; JNZ E01H	JUMP TO ERROR IF NOT EQUAL
266			; INR D	INCREMENT D REG
267			; JNZ LOOP	LOOP BACK IF NOT DONE
268			; LXI H,PORTC	OK MESSAGE FOR PORTC
269			; CALL PRINTK	PRINT MESSAGE
270	2000	C3 C3 20	JMP BACK	CHECK KEY

325	2137	C3 00 00	E		JMP GETCH	
326				:		
327				:	MEMR	MEMORY ERROR ROUTINE-PRINTS CHIP ADDR
328				:		IN 1K INCREMENTS & CONTINUES TEST
329				:		
330	213A	1E 00		MEMR	MVI E,0	ZERO E
331	213C	7C			MOV B,H	MOVE H TO B
332	213D	E6 FC			ANI 0FCH	DUMP 2 LOWER BITS OF H
333	213F	57			MOV D,A	RESTORE TO D
334	2140	21 98 22			LXI H,ERRM	MEMORY ERROR MESSAGE LOADED
335	2143	06 13			MVI B,19	19 CHARACTERS WILL BE PRINTED
336	2145	CD 58 21			CALL PRTOK	CHARACTERS PRINTED
337	2148	7A			MOV A,D	
338	2149	CD 00 00	E		CALL MOUT	NUMBER IN B PRINTED
339	214C	7D			MOV A,E	
340	214D	CD 00 00	E		CALL MOUT	
341	2150	7A			MOV A,D	HI ORDER ADDR LOADED BACK IN H
342	2151	C6 04			ADI 04H	MEM ADDR INCREASED TO NEXT THAT
343	2153	67			MOV H,A	HAVE HI ORDER + ADDR BACK IN H
344	2154	6B			MOV L,E	HL HAS ADDR OF NEXT RMT
345	2155	C3 E0 20			JMP HLTS	GO TEST NEXT RMT
346				:		
347				:	PRTOK	PROGRAM PRINTS MESSAGE ADDRESSED
348				:		BY HL THAT IS B CHARACTERS LONG
349				:		
350	2158	4E			MOV C,H	GET CHARACTER TO BE PRINTED
351	2159	CD 00 00	E		CALL C0	SEND CHARACTER TO PRINTER
352	215C	23			INX H	GO TO NEXT CHARACTER
353	215D	05			DEC B	DECREMENT BYTE COUNTER
354	215E	C2 58 21			JRZ PRTOK	GO BACK FOR NEXT CHARACTER IF NOT DONE
355	2161	C9			RET	RETURN TO CALLER IF DONE
356	2162	21 CF 22	E12A		LXI H,ERR1A	PORT12A BAD ERROR MESSAGE
357	2165	CD 58 21			CALL PRTOK	PRINT MESSAGE
358	2168	C3 20 20			JMP CKPT1B	TEST NEXT SET OF PORTS
359	216B	21 DB 22	E12B		LXI H,ERR1B	PORT12B BAD ERROR MESSAGE
360	216E	CD 58 21			CALL PRTOK	PRINT MESSAGE
361	2171	C3 48 20			JMP CKPT1C	TEST NEXT SET OF PORTS
362	2174	21 E7 22	E12C		LXI H,ERR1C	PORT12C BAD ERROR MESSAGE
363	2177	CD 58 21			CALL PRTOK	PRINT MESSAGE
364	217A	C3 60 20			JMP CKPT1A	TEST NEXT SET OF PORTS
365	217D	21 17 23	E21A		LXI H,ERR2A	PORT21A BAD ERROR MESSAGE
366	2180	CD 58 21			CALL PRTOK	PRINT MESSAGE
367	2183	C3 08 20			JMP CKPT1D	TEST NEXT SET OF PORTS
368	2186	21 23 23	E21B		LXI H,ERR2B	PORT21B BAD ERROR MESSAGE
369	2189	CD 58 21			CALL PRTOK	PRINT MESSAGE
370	218C	C3 A0 20			JMP CKPT1E	TEST NEXT SET OF PORTS
371	218F	21 2F 23	E21C		LXI H,ERR2C	PORT21C BAD ERROR MESSAGE
372	2192	CD 58 21			CALL PRTOK	PRINT MESSAGE
373				:	JMP CKPT1F	TEST NEXT SET OF PORTS
374	2195	21 5F 2C	E21D		LXI H,ERR2D	PORT21D BAD ERROR MESSAGE
375	2198	CD 58 21			CALL PRTOK	PRINT MESSAGE
376				:	JMP CKPT1G	TEST NEXT SET OF PORTS
377	219B	21 6D 2C	E21E		LXI H,ERR2E	PORT21E BAD ERROR MESSAGE
378	219E	CD 58 21			CALL PRTOK	PRINT MESSAGE

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379          ; JMP CKPT3C          TEST NEXT SET OF PORTS
380 21A1 21 77 23      E31C      LXI H,P0D3C      PORT31C BAD ERROR MESSAGE
381 21A4 CD 58 21      CALL PRTOK      PRINT MESSAGE
382 21A7 C3 C3 20      JMP RAMCK      TEST NEXT CIRCUITS
383          ;
384 21AA 21 75 22      APUER      LXI H,ERAPU      HL LOADED WITH APU ERR MSG ADR
385 21AD 06 10          MVI B,015      14 CHARACTERS,CR,LF TO BE PRINTED
386 21AF CD 58 21      CALL PRTOK      MESSAGE PRINTED
387 21B2 C3 00 00      E      JMP GETCH
388          ;
389          ;
390          ; TSTTAP          PROGRAM TO TEST AIRCO TAPE DATA
391 21B5 3E 00          TSTTAP      MVI A,000H      PORT1 WILL BE SET FOR OUTPUT
392 21B7 D3 CF          OUT PORT1      SET PORT1 FOR OUTPUT
393 21B9 3E 90          MVI A,090H      PORT2 SET
394 21BB D3 D7          OUT PORT2      CONTROL WORD SENT
395 21BD 3E 07          MVI A,07H      CHART OFF SIGNAL
396 21BF D3 D5          OUT PORT2B     TURN OFF CALIBRATOR RELAYS
397 21C1 3E 70          MVI A,070H     SET MAG TAPE READ,WRITE,DAC LATCH HI
398 21C3 D3 D6          OUT PORT2C     LEAVE STROBE LINES HI
399 21C5 3E 93          MVI A,093H     LOAD WORD FOR A OUT,B INPUT,C I/O
400          ; OUT PORT3
401 21C7 3E 05          MVI A,05H      SELECT TAPE DRIVE,SET UP FOR READ
402 21C9 D3 CD          OUT PORT1B     SEND TO PORT 1B
403 21CB 01 00 30      TAP1      LXI B,03000H   BLOCK OF DATA TO BE READ INTO RAM
404 21CE C5            PUSH B         STORE ON STACK
405 21CF 11 F3 30      LXI D,03BF3H   END OF DATA BLOCK
406 21D2 D5            PUSH D         STORE ON STACK
407 21D3 CD 68 0F      CALL RDTAP     READ 244 BYTES OF DATA FROM TAPE
408 21D6 C3 70 00      JMP DISBLK     DISPLAY BLOCK OF DATA FROM TAPE
409          ;
410          ;
411          ; BUFCK          PROGRAM TO CHECK THE BUFFER
412          ; IN THE TAPE FORMATTER FOR
413          ; WRITES A 54K BLOCK TO TAPE
414          ; TAPE SHOULD BE RECORD,ONLINE BEFORE GO
415          ; IS TYPED.
416          ;
417 21D9 21 03 23      BUFUCK      LXI H,TWRP     LOAD ADDR OF PROMPT MSG IN HL
418 21DB 06 1E          MVI B,TWRPL    LOAD LENGTH OF PROMPT MSG IN B
419 21DE CD 58 21      CALL PRTOK     PRINT B CHARACTERS,ADDR BY HL
420 21E1 21 00 00      LXI H,0H       ZERO BYTE COUNT IN HL
421 21E4 3E 00          MVI A,000H     SET PORT1 FOR OUTPUT
422 21E6 D3 CF          OUT PORT1      TO MAG TAPE
423 21E8 3E 90          MVI A,090H     SET PORT2 FOR OUTPUT
424 21EA D3 D7          OUT PORT2
425 21EC 3E 06          MVI A,060H     SELECT TAPE DRIVE
426 21EE D3 CD          OUT PORT1B     SEND TO PORT1B
427 21F0 3E 07          MVI A,07H      TURN OFF CHART SIGNAL
428 21F2 D3 D5          OUT PORT2B     CALIBRATOR RELAYS
429 21F4 CD 68 22      CALL CARRET    HANG HERE UNTIL READY
430 21F7 7D          MOV A,L        LOAD LOW BYCOUNT FROM HL
431 21F8 D3 CC          OUT PORT1A     SEND OUT TO PORT1A
432 21FA AF          XRA A         ZERO A,STROBE RAC LINE

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433	21FB	D3 D6		OUT PORT2C	LO,THEN HI
434	21FD	3E 10		MVI A,10H	
435	21FF	D3 D6		OUT PORT2C	
436	2201	0E 20		MVI C,020H	LOAD ASCII CHARACTER FOR SPACE IN C
437	2203	CD 00 00	E	CALL CO	PRINT A SPACE
438	2206	23		INX H	INCREMENT BYTE COUNT
439	2207	7C		MOV A,H	CHECK HI BYTE
440	2208	FE 00		CPI 0	BOTH HI & LO BYTE
441	220A	C2 F7 21		JNZ TULP	ZERO WHEN DONE
442	220D	7D		MOV A,L	CHECK LO BYTE
443	220E	FE 00		CPI 0	
444	2210	C2 F7 21		JNZ TULP	
445			;		WRITE IS DONE,PROMPT FOR READBACK
446	2213	21 01 23		LXI H,INDP	LOAD ADDR OF TAPE READ PRO MSG
447	2216	06 32		MVI 0,TRDPL	LENGTH OF MSG IN 0
448	2218	CD 50 21		CALL PRTOK	PRINT ON TERMINAL
449	221B	C3 00 00	E	JMP GETCH	RETURN TO MONITOR
450			;		
451			;	BUFCK	PROGRAM TO CHECK THE BUFFER
452			;		IN THE TAPE FORMATTER FOR READS
453			;		OF 64K DATA BLOCK,ERRORS PRINTED
454	221E	21 01 00	BUFCK	LXI H,1H	SET BYTE COUNT
455	2221	3E 00		MVI A,003H	SET PORT1 FOR OUTPUT
456	2223	D3 CF		OUT PORT1	TO MAG TAPE
457	2225	3E 00		MVI A,090H	SET PORT2 FOR OUTPUT
458	2227	D3 D7		OUT PORT2	
459	2229	3E 07		MVI A,07H	TURN OFF CHART SIGNAL
460	222B	D3 D5		OUT PORT2D	CALIBRATOR RELAYS
461	222D	3E 93		MVI A,093H	LOAD WORD FOR A OUT,B IN C I/O
462			;	OUT PORT3	SEND TO PORT3
463	222F	3E 05		MVI A,05H	SELECT TAPE DRIVE,SET UP FOR READ
464	2231	D3 CD		OUT PORT1B	SEND TO PORT 10
465	2233	CD 60 22		CALL CARRT	HANG HERE UNTIL READY
466	2236	CD 00 00	E	CALL CROUT	CR,LF
467	2239	7C		MOV A,H	MOVE TO ACC TO PRINT
468	223A	CD 00 00	E	CALL NROUT	PRINT H
469	223D	7D		MOV A,L	MOVE L TO ACC
470	223E	CD 00 00	E	CALL NROUT	PRINT L
471	2241	0E 20		MVI C,020H	LOAD ASCII CHARACTER FOR SPACE IN C
472	2243	CD 00 00	E	CALL CO	PRINT A SPACE
473			;	IN PORT3A	READ BYTE FROM TAPE BUFFER TO ACC
474	2246	0D		CMP L	COMPARE TAPE DATA TO BYTE COUNT
475	2247	C4 00 00	E	CNZ NROUT	PRINT IT IF.NE.BYTECOUNT
476	224A	D0 C6		IN USST5	CHECK USART FOR CHARACTER
477	224C	E6 02		ANI 02H	
478	224E	C4 60 22		CNZ CARRT	HANG FOR CARRIAGE RETURN IF CHARACTER
479	2251	AF		XRA A	ZERO ACCUMULATOR
480	2252	D3 D6		OUT PORT2C	SEND NEG LINE LOW
481	2254	3E 10		MVI A,10H	SEND LINE BACK HI
482	2256	D3 D6		OUT PORT2C	
483	2258	23		INX H	INCREMENT BYTE COUNT
484	2259	7C		MOV A,H	CHECK HI BYTE
485	225A	FE 00		CPI 0	BOTH HI & LO BYTE
486	225C	C2 36 22		JNZ TRLP	ZERO WHEN DONE

487	225F	7D				MOV A,L	CHECK LO BYTE
488	2260	FE 00				CPI 0	
489	2262	C2 36 22				JNZ TRLP	
490	2265	C3 00 00	E			JMP GETCM	RETURN TO MONITOR
491				:			
492				:		CARRET	HANGS PROGRAM HERE UNTIL CR TYPED
493				:			
494	2260	CD 00 00	E		CARRET	CALL GETCH	GET A CHARACTER FROM TERMINAL
495	226B	CD 00 00	E			CALL ECHO	PRINT IT OUT
496	226E	79				MOV A,C	STICK IT IN ACC
497	226F	FE 0D				CPI CR	COMPARE TO CARRIAGE RETURN
498	2271	C2 68 22				JNZ CARRET	LOOK AGAIN IF NOT CR
499	2274	C9				RET	RETURN IF IT WAS
500				:			
501	2275	0D 0A 45 52			ERAPU	DB CR,LF,'ER IN 9511 APU'	
502	2279	20 49 4E 20					
503	227D	39 35 31 31					
504	2281	20 41 50 55					
505				:			
506	2285	0D 0A 52 41			RANCP	DB CR,LF,'RAM TEST COMPLETE'	
507	2289	4D 20 54 45					
508	228D	53 54 20 43					
509	2291	4F 4D 50 4C					
510	2295	45 54 45					
511	2298	0D 0A 4D 45			ERRM	DB CR,LF,'MEMORY ERROR AT	
512	229C	4D 4F 52 59					
513	22A0	20 45 52 52					
514	22A4	4F 52 20 41					
515	22A8	54 20 20					
516	22AB	0D 0A 50 4F			POK1A	DB CR,LF,'PORT12A OK'	
517	22AF	52 54 31 32					
518	22B3	41 20 4F 40					
519	22B7	20 20 50 4F			POK1B	DB ' PORT12B OK'	
520	22BB	52 54 31 32					
521	22BF	42 20 4F 40					
522	22C3	20 20 50 4F			POK1C	DB ' PORT12C OK'	
523	22C7	52 54 31 32					
524	22CB	43 20 4F 40					
525	22CF	0D 0A 45 52			PUD1A	DB CR,LF,'OK PORT12A'	
526	22D3	20 50 4F 52					
527	22D7	54 31 32 41					
528	22DB	20 20 45 52			PBD1B	DB ' ER PORT12B'	
529	22DF	20 50 4F 52					
530	22E3	54 31 32 42					
531	22E7	20 20 45 52			PBD1C	DB ' ER FORT12C'	
532	22EB	20 50 4F 52					
533	22EF	54 31 32 43					
534	22F3	0D 0A 50 4F			POK2A	DB CR,LF,'PORT21A OK'	
535	22F7	52 54 32 31					
536	22FB	41 20 4F 40					
537	22FF	20 20 50 4F			POK2B	DB ' PORT21B OK'	
538	2303	52 54 32 31					
539	2307	42 20 4F 40					
540	230B	20 20 50 4F			POK2C	DB ' PORT21C OK'	

541	230F	52 54 32 31		
542	2313	43 20 4F 40		
543	2317	0D 0A 45 52	PBD2A	DB CR,LF,'ER PORT21A'
544	231B	20 50 4F 52		
545	231F	54 32 31 41		
546	2323	20 20 45 52	PBD2B	DB ' ER PORT21D'
547	2327	20 50 4F 52		
548	232B	54 32 31 42		
549	232F	20 20 45 52	PBD2C	DB ' ER PORT21C'
550	2333	20 50 4F 52		
551	2337	54 32 31 43		
552	233B	0D 0A 50 4F	POK3A	DB CR,LF,'PORT31A OK'
553	233F	52 54 33 31		
554	2343	41 20 4F 40		
555	2347	20 20 50 4F	POK3B	DB ' PORT31B OK'
556	234B	52 54 33 31		
557	234F	42 20 4F 40		
558	2353	20 20 50 4F	POK3C	DB ' PORT31C OK'
559	2357	52 54 33 31		
560	235B	43 20 4F 40		
561	235F	0D 0A 45 52	PBD3A	DB CR,LF,'ER PORT31A'
562	2363	20 50 4F 52		
563	2367	54 33 31 41		
564	236B	20 20 45 52	PBD3B	DB ' ER PORT31B'
565	236F	20 50 4F 52		
566	2373	54 33 31 42		
567	2377	20 20 45 52	PBD3C	DB ' ER PORT31C'
568	237B	20 50 4F 52		
569	237F	54 33 31 43		
570	2383	0D 0A 49 49	TURP	DB CR,LF,'HIT CARRIAGE RETURN TO START'
571	2387	54 20 43 41		
572	238B	52 52 49 41		
573	238F	47 45 20 52		
574	2393	45 54 55 52		
575	2397	4E 20 54 4F		
576	239B	20 53 54 41		
577	239F	52 54		
578	001E		TURPL	EQU \$-TURP LENGTH OF PROMPT
579	23A1	0D 0A 52 45	TRDP	DB CR,LF,'REWIND,SW TO LOCAL,READ,GISSP,ONLINE,CR TO START'
580	23A5	57 49 4E 44		
581	23A9	2C 53 57 20		
582	23AD	54 4F 20 4C		
583	23B1	4F 43 41 4C		
584	23B5	2C 52 45 41		
585	23B9	44 2C 47 31		
586	23BD	35 38 46 2C		
587	23C1	4F 4E 4C 49		
588	23C5	4E 45 2C 43		
589	23C9	52 20 54 4F		
590	23CD	20 53 54 41		
591	23D1	52 54		
592	0032		TRDPL	EQU \$-TRDP LENGTH OF PROMPT
593	23D3			END

ASSEMBLER ERRORS = 0

SYMBOL TABLE

A	0007	ACOS	E 0000	ADROI	000E	ADRMD	00DC
ADRST	00DC	ADRTL	0005	ADDATA	00EE	APSTAT	00EF
APUER	21AA	ASIN	E 0001	ATAN	E 0002	ATANA	E 0003
AUXMD	00DD	AXRA	0000	AXRB	00A0	B	0000
BDECF	E 0004	BIDECF	E 0005	BIN	0001	BGM	0002
BDFCK	221E	BDFWCK	21D9	BUSIN	0000	BUSOUT	0000
BUSPRT	00D0	C	0001	CAHCY	0003	CARRET	2260
CHSD	E 0006	CHSDA	E 0007	CHSF	E 0008	CHSFA	E 0009
CHSS	E 000A	CHSSA	E 000B	CKPT1A	2000	CKPT1B	2020
CKPTIC	2040	CKPT2A	2060	CKPT2B	2080	CKPT2C	20A0
CLKRT	0022	CO	E 006A	COPT	E 0061	COS	E 000C
COSA	E 000D	CPT	0000	CPTEN	0001	CPTRG	00DD
CR	000D	CROUT	E 0060	D	0002	DADD	E 000E
DADDA	E 000F	DADD0	E 0010	DDIV	E 0011	DDIVA	E 0012
DDIVB	E 0013	DECHO	E 0014	DISBLK	0070	DMUL	E 0015
DMULA	E 0016	DMULB	E 0017	DMUJ	E 0018	DMUJR	E 0019
DMUJB	E 001A	DSUB	E 0019	DSUBA	E 001C	DSUBB	E 001D
DTDL1	0060	DTDL2	00E0	E	0003	E12A	2102
E12B	2160	E12C	2174	E21A	217D	E21B	2196
E21C	218F	E31A	2195	E31B	2198	E31C	21A1
ECHO	E 0050	EDEUS	0004	ENDMK	0010	EOIS	0000
EOIST	0020	EOSAC	0040	EOSR	00DF	EPKNT	E 0065
ERAPU	2275	ERRM	2290	EXP	E 001E	EXP10	E 0020
EXPA	E 001F	FADD	E 0021	FADDA	E 0022	FADD0	E 0023
FDIV	E 0024	FDIVA	E 0025	FDIVB	E 0026	FIXD	E 0027
FIXDA	E 0028	FIXS	E 0029	FIXSA	E 002A	FLYD	E 002B
FLTDA	E 002C	FLTS	E 002D	FLTSA	E 002E	FNUL	E 002F
FMULA	E 0030	FMULB	E 0031	FNHSK	0003	FRNT	E 0066
FSUB	E 0032	FSUBA	E 0033	FSUB0	E 0034	GETCH	E 0069
GETCH	E 0062	H	0004	HLTS	20E0	HOEND	0002
HOHSK	0001	INTE1	00D9	INTE2	00DA	L	0005
LA	0004	LF	000A	LN	E 0035	LNA	E 0036
LOG	E 0037	LOGA	E 0039	LOH	0040	LOP1	200C
LOP2	202C	LOP3	204C	LOP4	206C	LOP5	208C
LOP6	20AC	LOPN	20D3	M	0006	MATHC	20F4
MDAD	E 0039	MEMORY	M 0000	MERR	213A	MFM	0001
MNXT	20D1	MODE1	0001	NMDUT	E 0060	NOP	E 003A
NVCND	0007	NXTM	20DF	P0D1A	22CF	P0D1B	22D0
P0D1C	22E7	P0D2A	2317	P0D2B	2323	P0D2C	232F
P0D3A	239F	P0D3B	236D	P0D3C	2377	P0K1A	22A0
P0K1B	2207	P0K1C	22C3	P0K2A	22F3	P0K2B	22FF
P0K2C	230B	P0K3A	2330	P0K3B	2347	P0K3C	2353
POPD	E 0030	POPS	E 003C	PORT1	00CF	PORT1A	00CC
PORT1B	00CD	PORT1C	00CE	PORT2	00D7	PORT2A	00D4
PORT2B	00D5	PORT2C	00D6	PRINT	E 0063	PRINTF	E 0064
PRTOK	2150	PSW	0008	PT00	E 005D	PT05	E 003E
PUPI	E 003F	PUR	E 0040	PURA	E 0041	PUR0	E 0042
RAMCK	20C3	RAMCP	2205	R0TAP	0F60	RTCCT0	00E4
RTCCT1	00E5	RTCCT2	00E6	RTCCTL	00E7	S1	00D9
SADD	E 0043	SADDA	E 0044	SADD0	E 0045	S0501	0006
SDIV	E 0046	SDIVB	E 0047	SDIVB	E 0040	SIN	E 0049
SINA	E 004A	SMUL	E 0043	SMULA	E 004C	SNULB	E 004D
SMUJ	E 004E	SMUJA	E 004F	SMUJS	E 0050	SP	0006
SORT	E 0051	SQRTA	E 0052	SSUB	E 0053	SSUBA	E 0054
SSUB0	E 0055	STACK	S 0000	Ta	0002	TAN	E 0056
TANA	E 0057	TAP1	2100	TLOW	00C0	T0N	0000
T0S1	E 0050	T0S2	E 0050	T0S4	E 005A	TRDP	23A1
TRDPL	0032	TRLP	2230	TSTTAP	2105	TULP	21F7
TWRP	2303	TWRPL	001E	USSTS	0006	VSCND	000F
WRT1	E 005B	WRT2	E 005C	WRT4	E 005D	XCHD	E 005E
XCHS	E 005F	ZERO	E 0067	ZEROM	E 006C		

Appendix I

PROCEDURE FOR PERFORMING THE MANUAL EDDY-CURRENT INSPECTION
OF THE SHEATH WELD ON THE SUPERCONDUCTOR CABLE

This procedure describes the techniques used to perform the manual eddy-current inspection of the sheath weld after the superconductor cable has been fabricated. The procedure provides guidelines for the necessary steps and the order of performance required to set up and calibrate the equipment, verify the test sensitivity, and perform the inspection to evaluate those areas on the sheath weld where indications were obtained during the on-line inspection. This procedure and technique can also be used to determine whether or not the weld repairs were successful. The procedure was written with the assumption that the operator is familiar with the test equipment and its operation.

1.0 EQUIPMENT

Multifrequency eddy-current instrument

Eddy-current probe and cable

Probe holder for manual scanning

Transceiver unit

Video terminal and keyboard

Remote control box (RCB)

Six-channel analog recorder

Assorted nonconducting shims in the 25 to 254 μm (0.001 to 0.010 in.) range

Reference standards

Isolation transformer

2. ELECTRICAL POWER

2.1 Before connecting power to the eddy-current instrument, make sure that the three toggle switches on the phase calibrator module are in the "down" position (i.e., "MAG-LO," "PH-LO," and "OPERATE" positions), and make sure that an eddy-current probe is connected to the correct jacks on the calibrator module.

2.2 Connect electrical power to *all* instruments [eddy current (only on isolation transformer), analog recorder, transceiver, and video terminal], turn the equipment on, and allow at least 4 h for the instruments to warm up and stabilize.

3. DURING THE WARM-UP PERIOD

3.1 Check all cables and electrical connections to make sure they are correct (see Fig. I.1).

3.2 Check the switches on all modules and instruments to assure they are in the normal position, per Tables I.1 and I.2.

3.3 *Check the analog recording system.* Set the RCB function switch to position 7. Press a chart speed switch to start the analog recorder chart drive. Use a slow chart speed (5 mm/s or less). Press the "interrupt" switch on the RCB, and set all recorder pens to the zero reference value on each chart scale using zero adjustments on the recorder. After zeroing all pens, press the "return" key on the keyboard. All recorder pens should step five minor chart divisions to the left on the respective chart scales, representing an increase of 0.25 mm (0.010 in.). Press the "return" key eight times, representing an increase of 2.03 mm (0.080 in.). If any of these recorder pens are not at the left margin, check the recorder sensitivity adjustments for that recorder

ORNL-DWG 85-1856

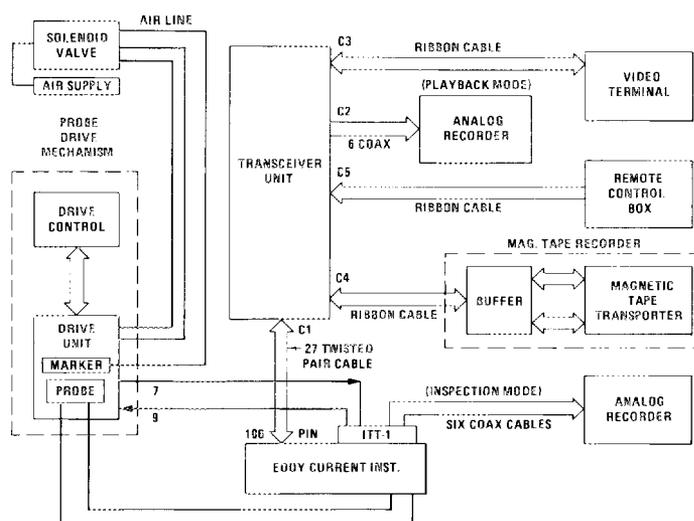


Fig. I.1. Block diagram of the digital recording system.

Table I.1. Normal instrument settings

Instrument	Modular ^a position	Switch identity	Correct switch setting
<u>Eddy-Current Instrument</u>		Power on-off	
Power Oscillator	M1	High frequency (top)	500 kHz
		Median frequency (middle)	100 kHz
		Low frequency (bottom)	20 kHz
Bandpass Amplifier	M4 M6 M8	Low frequency	20 kHz
		Mid frequency	100 kHz
		High frequency	500 kHz
Discriminators ^b	M3	Coarse lift-off	518
		Coarse balance	714
	M5	Coarse lift-off	512
		Coarse balance	682
	M7	Coarse lift-off	507
		Coarse balance	920
<u>Analog Recorder</u>		Power on-off	
		Sensitivity — coarse	100 mV/div
		Sensitivity — fine	Maximum CW
		Chart speed	5 mm/div
<u>Probe Drive Control</u>		Power on-off	
		Speed adjustment	124—128
		Scale selector (torque/speed)	Speed
		Direction (CW/stop/CCW)	CW

^aThe eddy-current instrument chassis has 10 modular positions. They are identified as M1 to M10 from right to left when facing the instrument. The computer module occupies two positions, M9 and M10.

^bAdjustments of the lift-off and balance controls on the discriminators may sometimes be necessary to calibrate the eddy-current instrument. These adjustments should be made by using only the fine controls (screwdriver adjustments). If a change in the coarse control setting becomes necessary, notify your supervisor.

Table I.2. Instrument switches and functions

Instrument	Switch	Position(s)	Function and comments
<u>Eddy Current Control Module</u>	Function	0-9	Selects correct PROM to match the eddy-current probe (00 for 454, 01 for 460, and 02 for 459)
	Interrupt		DO NOT USE
	Reset		DO NOT USE
<u>Magnetic Tape Recorder</u>			
Transporter	Power	On-Off	
Transporter	Load	On-Off	Used to load tape
Transporter	On-Line	On-Off	Use for recording and reading
Transporter	Rewind	On-Off	Used to rewind tape
Transporter	Write ring		See Appendix A
Buffer	Power	On-Off	
Buffer	EOF	On-Off	See Appendix A
Buffer	Mode	Record	Used to record data
Buffer	Mode	Read	Used to read tape
Buffer	Mode	Continuous	DO NOT USE
Buffer	Mode	Remote	DO NOT USE
<u>Transceiver</u>			
	Power	On-Off	
	Selector	DX	Select external computer, used to record data (in eddy-current instrument)
	Selector	Local	Select internal computer, used to read tape
	Function	0-9	Always set on 1
<u>Video Terminal</u>			
	Power	On-Off	Located in back of instrument
	Keyboard		Transmits information and commands to computer

channel (see Table I.1). Note that the variable sensitivity adjustment must be set at maximum (fully clockwise) for that recorder channel to be calibrated. Press the "return" key twice more to check the calibration on channels 1 through 4. [If the incremented steps between zero and maximum are not linear (i.e., five divisions per step), something is wrong with the recorder.] Press the "reset" switch on the RCB to stop this check and press the "STOP" switch on the analog recorder and go to the next step.

4. AFTER THE EDDY-CURRENT TEST SYSTEM HAS COMPLETED A 4-h WARM-UP PERIOD, COMPLETE THE FOLLOWING CHECKOUT SEQUENCE

4.1 Set the transceiver selector switch to "DX." Set the transceiver function switch to "1."

4.2 *Check the analog recording system.* Set the (RCB) function switch to position 7. Press a chart speed switch to start the analog recorder chart drive. Use a slow chart speed (5 mm/s or less). Press the "interrupt" switch on the RCB, and set all recorder pens to the zero reference value on each chart scale using zero adjustments on the recorder. After zeroing all pens, press the "return" key on the keyboard. All recorder pens should step five minor chart divisions to the left on the respective chart scales, representing an increase of 0.25 mm (0.010 in.). Press the "return" key eight times, representing an increase of 2.03 mm (0.080 in.). If any of these recorder pens are not at the left margin, check the recorder sensitivity adjustments for that recorder channel (see Table I.1). Note that the variable sensitivity adjustment must be set at maximum (fully clockwise) for that recorder channel to be calibrated. Press the "return" key twice more to check the calibration on channels 1 through 4. [If the incremented steps between zero and maximum are not linear (i.e., five divisions per step), something is wrong with the recorder.] Press the "reset" switch on the RCB to stop this check and press the "STOP" switch on the analog recorder and go to the next step.

4.3 *Perform and Display Calibration.* Set the RCB function switch to position 5. Press the "interrupt" switch on the RCB. You should hear relays clicking, and about 10 s later the computer will display four lines of data on the video monitor. Let the display repeat about four or five times and press the "reset" switch on the RCB to stop. Evaluate the data.

High magnitudes (columns 1, 3, and 5) should be 4.50 ± 0.02 V. High phases (even columns) should be 4.00 ± 0.02 V, except PH3 = 4.50 V. The phase difference between high-magnitude and low-magnitude readings on the first two lines of phase data should be less than ± 10 mV. *If not, refer to the instrument calibration procedure.*

(*Important:* Do not leave the calibration system running for long periods of time because the relays could be damaged.)

4.4 *Read Reference Standard.* [The probe should have the 88.9- μm -thick (0.0035 in.) Teflon tape on its face.] Using the square tube standard D, position the probe over the reference reading mark [centered over the weld and 7.62 cm (3 in.) from the end toward defect number 1]. Select a lift-off shim to obtain a Mag 2 reading within ± 0.1 V of the Mag 2 reading in Table I.3 (readings from nominal tube sample, third column) for the coil being used. This is done in the function 3 position of the RCB. Example: Probe 454-00 should read 3.6 V (3.5 ± 0.1 V) with a 101.6- μm (0.004-in.) shim. Press reset on RCB.

Select function 2 on the RCB. Using the shim size determined above, hold the probe over the reference reading mark with the shim between the probe face and sample. Press the "interrupt" switch on the RCB. One line of data should be printed out on the video display. Press the "interrupt" switch again and another line of data will appear. Repeat until at least five lines of data are obtained or until the last two lines of data agree to within ± 2 mV. Check the Mag 2 reading (third column) and compare with the Mag 2 reading for the nominal tube sample for the probe being used. See Table I.3.

5. INSPECTION

5.1 Set up eddy-current equipment as just described in steps 1.1 through 4.4 above.

5.2 Place the eddy-current probe in the manual scanning fixture. Adjust the probe position until the Mag 2 reading is the same as in step 4.4. Fix the probe at this lift-off. Press the "reset" switch on the RCB.

Table I.3. Eddy-current probe, PROM code, and calibration readings

Averages and standard deviations of calibration readings (V) for each frequency						
	20 kHz		100 kHz		500 kHz	
	MAG1	PHA1	MAG2	PHA2	MAG3	PHA3
Probe 454, code 00						
S.D.	4.5004	4.0004	4.5022	3.9945	4.5023	4.4958
	0.0000	0.0000	0.0000	0.0023	0.0000	0.0032
S.D.	2.4591	3.9989	2.3132	3.9933	2.4104	4.4956
	0.0023	0.0032	0.0000	0.0000	0.0016	0.0045
α	4.2220	2.5743	3.5361	2.8298	3.6230	1.0296
Probe 460, code 01						
S.D.	4.4977	4.0047	4.4985	4.0118	4.5007	4.4878
	0.0045	0.0032	0.0032	0.0032	0.0000	0.0064
S.D.	2.4601	4.0047	2.3095	4.0103	2.4042	4.4864
	0.0016	0.0032	0.0000	0.0045	0.0000	0.0064
α	4.3142	3.0158	3.8659	2.9747	3.7303	1.0510
Probe 459, code 02						
S.D.	4.4974	4.0006	4.4976	4.0110	4.5197	4.4953
	0.0045	0.0045	0.0000	0.0084	0.0032	0.0084
S.D.	2.4592	3.9997	2.3090	4.0176	2.4158	4.4947
	0.0000	0.0032	0.0016	0.0055	0.0016	0.0084
α	4.5155	2.9760	4.1346	2.9136	4.1158	0.9058

^aReadings from nominal tube sample.

5.3. *Display Raw Readings.* Set the RCB function switch to position 3. Press the "reset" switch on the RCB. The statement "NDT COMP9" should appear on the video display. Next, press the "interrupt" switch on the RCB, and the raw readings will be continuously displayed on the video terminal. Check the raw readings to see if any are either zero or 4.999. If so, a problem exists. Check the eddy-current probe to see if it is properly seated on the standard test tube. If it is, something is probably wrong with the eddy-current instrument, and it should be corrected before proceeding. If the readings are all right, press the "reset" switch on the RCB to stop the readings and go to the next step.

6. PRECALIBRATION

6.1 Place the manual scanning fixture on calibration standard D and position the probe over the weld centerline.

6.2 Operate the "reset" switch on the RCB.

6.3 Set the RCB function switch to 6 and check that the PROM setting on the control module is correct for square conductor testing (04 for eddy-current probes 454 and 459 and 05 for probe 460).

6.4 Operate the "interrupt" switch on the RCB. The instruction, "enter ID" will appear on the video display. Enter the following information from the keyboard: probe serial number and coding (e.g., 459-04).

6.5 Operate the 2-mm/s chart speed switch on the analog recorder.

6.6. Press the "return" key on the keyboard. The eddy-current computer will perform a recalibration and display the raw magnitude and phase readings along with the calculated coefficients on the video terminal. At the end of the display, the computer enters the "running" mode.

6.7 Using a slow and steady speed, move the manual scanning fixture and probe along the standard conductor. Maintain the alignment of the weld on top of the tube and centered under the eddy-current probe. Scan each defect by moving the probe back and forth across the defect at least three times.

6.8 Observe the analog recorder as you scan the square standard. The four-channel recorder pens from the left should write between 5 and 25

minor divisions -25 to $+76$ mm (-0.010 to $+0.030$ in.) to the left of the right-hand margin on the recorder chart except when defect indications are obtained. The four channels identified from left to right are outside surface defects, lift-off, inside surface defects, and lack of penetration or wall thickness.

6.9 When the calibration is complete, stop the analog chart recorder and identify the recording as the "Precalibration Test." Record the date, the examiner's initials, and the identification of the superconductor sheath being examined on the recording.

7. PERFORM THE TEST

7.1 The eddy-current system is now ready to manually scan conductors. The scanning of a conductor is performed by starting the chart recorder at 2 mm/s and slowly pulling the probe and fixture uniformly along the conductor. The fixture must be kept level with the conductor surface to avoid lift-off effects.

7.2 Three scans of a given area are required: one along the weld centerline, and one at 2.29 mm (0.090 in.) on either side of the weld in the heat-affected zone. Each scan is initiated by starting the chart recorder and terminated by stopping the chart recorder.

7.3. Indications obtained during manual scanning are to be compared with the indications obtained on the calibration standard. Indications of defects exceeding the tolerances defined in Westinghouse Specification 90P744, Spec. 1, Rev. 2, require repair. Areas needing repair are to be indicated on the multifrequency eddy-current report and noted on the conductor inspection follower sheet.

7.4 When all manual scanning has been completed, rescan the calibration standard according to steps 6.7 through 6.9 of this appendix and label as the "Postcalibration."

7.5 After all testing is completed, set the RCB function switch to 5. When the display on the video terminal is completed, press the reset button on the RCB.

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