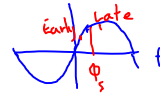


$L$  = distance between cavities



$$L = v_s \tilde{T}_s$$

$$\log L = \log v_s + \log \tilde{T}_s$$

$$\frac{\Delta L}{L} = \frac{\Delta v_s}{v_s} + \frac{\Delta \tilde{T}_s}{\tilde{T}_s}$$

$$\frac{\Delta v_s}{v_s} : p = \gamma m v$$

$$\Delta p = \Delta \gamma m v + \gamma m \Delta v$$

$$\gamma = (1 - \frac{v^2}{c^2})^{-1/2}$$

$$\Delta \gamma = -\frac{1}{2} \frac{-\frac{2v}{c^2} \Delta v}{(1 - \frac{v^2}{c^2})^{3/2}} = \frac{v/c}{c} \frac{\Delta v}{c} \gamma^3$$

$$\Delta p = m v \gamma^3 \frac{\Delta v}{c} + m \gamma \Delta v$$

$$= \gamma m \Delta v (1 + \gamma^2 \beta^2)$$

$$= \gamma^3 m \Delta v (1 + \gamma^2 (1 - \frac{1}{\gamma^2}))$$

$$\frac{\Delta p}{p_s} = \frac{\gamma m \Delta v \gamma^2}{\gamma m v_s} = \frac{\gamma^2 \Delta v}{v_s}$$

$$\frac{\Delta v}{v_s} = \frac{1}{\gamma^2} \frac{\Delta p}{p_s}$$

$$\frac{\Delta L}{L} = \frac{\Delta p}{\gamma^2 p_s} + \frac{\Delta \tilde{T}_s}{\tilde{T}_s}$$

Definition of  $\delta T$

$$\frac{\Delta L}{L} \equiv \frac{1}{\gamma^2} \frac{\Delta p}{p_s} \Rightarrow$$

$$\frac{\Delta \tilde{T}_s}{\tilde{T}_s} = (\frac{1}{\gamma^2} - \frac{1}{\gamma^2}) \frac{\Delta p}{p_s}$$

$$\equiv \eta \frac{\Delta p}{p_s} \quad \eta \equiv \text{Phase slip factor}$$

Linac:  $\gamma_T = \infty$  No path length change with  $\Delta p$ .

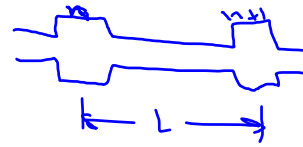
Fixed B:  $wp = qwrB$

$$p + \Delta p = qB(r + \Delta r)$$

$$p(1 + \frac{\Delta p}{p}) = qBr(1 + \frac{\Delta r}{r}) \Rightarrow 1 + \frac{\Delta p}{p} = 1 + \frac{\Delta r}{r}$$

$\frac{\Delta p}{p} = \frac{\Delta r}{r}$   
 $\frac{\Delta p}{p} = \frac{\Delta L}{L}$   
 $\gamma_T = 1$

$$\frac{\Delta T}{T} = \eta \frac{\Delta P}{P}$$



$$\phi_{n+1}^s = \phi_n^s = \phi^s$$

$$\phi_{n+1} = \phi_n + w_{rf} \Delta T$$

$$= \phi_n + w_{rf} \tilde{T}_s \frac{\Delta T}{T_s}$$

$$= \phi_n + w_{rf} \tilde{T}_s \eta \frac{\Delta P}{P_s}$$

$$= \phi_n + \frac{w_{rf} \tilde{T}_s \eta}{\beta^2 E_s} \Delta E$$



$$\frac{\Delta P}{P_s} = \frac{1}{\beta^2} \frac{\Delta E}{E_s}$$

$$\Delta \phi_{n+1} = \Delta \phi_n + \frac{w_{rf} \tilde{T}_s \eta}{\beta^2 E_s} \Delta E$$

$$\frac{d}{dn} (\Delta \phi) = \frac{w_{rf} \tilde{T}_s \eta}{\beta^2 E_s} \Delta E$$

$$E_{n+1}^s = E_n^s + e \tilde{V} \sin \phi_s$$

$$E_{n+1} = E_n + e \tilde{V} \sin \phi_{n+1}$$

$$E_{n+1} - E_n^s = \Delta E_{n+1}$$

$$\Delta E_{n+1} = \Delta E_n + e \tilde{V} (\sin \phi_{n+1} - \sin \phi_s)$$

$$\frac{d}{dn} (\Delta E) = e \tilde{V} (\sin \phi - \sin \phi_s)$$

$$\phi \equiv \phi_s + \Delta \phi$$

$$E \equiv E_s + \Delta E$$

$$\frac{d}{dn}(\Delta\phi) = \frac{\eta \omega_{rf} T_s}{\beta_s^2 E_s} \Delta E$$

$$\frac{d}{dn}(\Delta E) = eV(\sin\phi - \sin\phi_s)$$

Small  $\Delta\phi, \Delta E$ :

$$\begin{aligned} \sin\phi - \sin\phi_s &= \sin(\phi_s + \Delta\phi) - \sin\phi_s \\ &= \sin\phi_s \cos\Delta\phi + \cos\phi_s \sin\Delta\phi - \sin\phi_s \\ &= \sin\phi_s (\cos\Delta\phi - 1) + \cos\phi_s \sin\Delta\phi \end{aligned}$$

$\Delta\phi$  small:

$$\begin{aligned} \cos\Delta\phi - 1 &= -1 + 1 - \frac{1}{2}\Delta\phi^2 + \frac{1}{4!}\Delta\phi^4 + \dots \\ &= -\frac{1}{2}\Delta\phi^2 + \dots \end{aligned}$$

Ignore!

$$\sin\Delta\phi \approx \Delta\phi - \frac{1}{3!}\Delta\phi^3 + \dots \approx \Delta\phi$$

$$\frac{d\Delta E}{dn} \approx eV \cos\phi_s \Delta\phi$$

$$\frac{d\Delta\phi}{dn} = \frac{\eta \omega_{rf} T_s}{\beta_s^2 E_s} \Delta E$$

$$\frac{d^2 \Delta\phi}{dn^2} = \frac{\eta \omega_{rf} T_s}{\beta_s^2 E_s} \frac{d}{dn} \Delta E$$

$$= \frac{\eta \omega_{rf} T_s}{\beta_s^2 E_s} eV \cos\phi_s \Delta\phi$$

$$\equiv -(2\pi\nu_s)^2 \Delta\phi$$

$\nu_s \equiv$  Synchrotron tune

$$\Delta\phi \approx \cos(2\pi\nu_s n)$$

$$\frac{d}{dn} \Delta\phi = \frac{\eta W_{rf} T}{\beta_s^2 E_s} \Delta E$$

$$\begin{aligned} \frac{d}{dn} \Delta E &= e \tilde{v} (\sin\phi - \sin\phi_s) \\ &= e \tilde{v} (\sin(\phi_s + \Delta\phi) - \sin\phi_s) \end{aligned}$$

$$\begin{aligned} \frac{d^2 \Delta\phi}{dn^2} &= \frac{\eta W_{rf} T}{\beta_s^2 E_s} \frac{d}{dn} \Delta E \\ &= \frac{\eta W_{rf} T}{\beta_s^2 E_s} e \tilde{v} (\sin(\phi_s + \Delta\phi) - \sin\phi_s) \end{aligned}$$

$$\frac{d\Delta\phi}{dn} \frac{d^2 \Delta\phi}{dn^2} = \frac{\eta W_{rf} T}{\beta_s^2 E_s} e \tilde{v} (\sin(\phi_s + \Delta\phi) - \sin\phi_s)$$

$$\frac{d}{dn} \left[ \frac{1}{2} \left( \frac{d\Delta\phi}{dn} \right)^2 \right] = \frac{\eta W_{rf} T}{\beta_s^2 E_s} e \tilde{v} \frac{d}{dn} \left[ -\cos(\phi_s + \Delta\phi) - \sin\phi_s \Delta\phi \right]$$

$$\frac{d}{dn} \left[ \frac{1}{2} \left( \frac{d\Delta\phi}{dn} \right)^2 + \frac{\eta W_{rf} T}{\beta_s^2 E_s} e \tilde{v} (\cos(\phi_s + \Delta\phi) + \sin\phi_s \Delta\phi) \right]$$

$$\frac{1}{2} \left( \frac{d\Delta\phi}{dn} \right)^2 + \frac{\eta W_{rf} T}{\beta_s^2 E_s} e \tilde{v} (\cos(\phi_s + \Delta\phi) + \Delta\phi \sin\phi_s) = 0$$

= constant

$$\frac{\eta W_{rf} T}{\beta_s^2 E_s} \Delta E$$

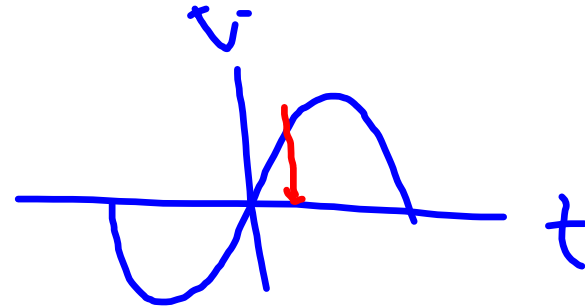
$$\frac{1}{2} \left( \frac{\eta W_{rf} T}{\beta_s^2 E_s} \right)^2 \Delta E^2 + \frac{\eta W_{rf} T}{\beta_s^2 E_s} e \tilde{v} (\cos(\phi_s + \Delta\phi) + \Delta\phi \sin\phi_s)$$

= const

$$\Delta E^2 + 2 \frac{\beta_s^2 E_s}{\eta W_{rf} T} e \tilde{v} (\cos(\phi_s + \Delta\phi) + \Delta\phi \sin\phi_s) = \text{const}$$

$$\Delta E^2 + \frac{2\beta_s^2 E_s e \dot{v}}{\eta W_{rf} T_s} (\cos\phi + \phi \sin\phi_s) = \text{const}$$

$$\Delta E^2 + \frac{2\beta_s^2 E_s e \dot{v}}{\eta W_{rf} T_s} \cos\phi$$



= constant

$$\text{constant} = \frac{2\beta_s^2 E_s e \dot{v}}{\eta W_{rf} T_s} (\cos\phi)_{\text{max}}$$

$$\Delta E^2 = \frac{2\beta_s^2 E_s e \dot{v}}{\eta W_{rf} T_s}$$