

Dispersion: $x'' + Kx = f(s)$

Last time: $G(s, s') = S(s)C(s')$
 $- C(s)S(s')$

$S(s) = \delta/R$ for dispersion.

$$D(s) = \int_0^s G(s, s') f(s') ds'$$

$$D''(s) + K(s) D(s) = f(s)$$

$$D(0) = D'(0) = 0$$

D is one particular solution
of Hill's (Inhomogeneous) Eqn.

General Solution:

$$x = x_0 C(s) + x_0' S(s) + D(s)$$

Can find periodic solution:

$$x_L = x_0 = x_0 C(L) + x_0' S(L) + D(L)$$

$$x'_L = x_0' = x_0 C'(L) + x_0' S'(L) + D'(L)$$

If $x'' + Kx = \frac{1}{\rho}$ (set $\epsilon(s) = \frac{1}{\rho}$ with $\delta=1$)

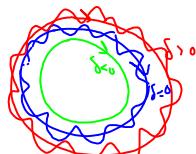
Then periodic solution is call $D(s)$

and is called dispersion function.

$$\text{Since } D'' + KD = \frac{1}{\rho}$$

can write any solution as

$$x = a C(s) + b S(s) + \delta D(s)$$



Remember in longitudinal motion:

$$\frac{\Delta L}{L} = \frac{1}{\gamma_T^2} \frac{\delta p}{p_0} = \frac{\delta}{\gamma_T^2}$$

$$C(\delta=0) = \oint ds$$

$$C(\delta) = \oint (1 + \frac{x}{R}) ds$$

$$= \oint ds + \int_R^x ds$$

$$= C(\delta=0) + \oint \underbrace{\left(\frac{\alpha C(s) + S(s)}{R} + \frac{D(s)}{R} \right)}_{\text{oscillatory - can ignore}} ds$$

$$C(\delta) - C(\delta=0) = \delta \oint \frac{D(s)}{R} ds$$

$$\frac{\Delta C}{C} = \frac{\delta \oint \frac{D(s)}{R} ds}{\oint ds} = \alpha \delta$$

$\underbrace{}$ momentum compactification factor

$$\frac{\Delta C}{C} = \frac{1}{\gamma_T^2} \delta \Rightarrow \frac{1}{\gamma_T^2} = \frac{\oint \frac{D(s)}{R} ds}{\oint ds}$$

$$\int n(x, x', \delta) dx' d\delta = 1$$

Say I have a function $h(x, x', \delta)$

Then I can talk about average

$$\langle h \rangle = \int h(x, x', \delta) n(x, x', \delta) dx dx' d\delta$$

$$x = x_\beta + \delta D \text{ where } x_\beta = \underbrace{a C(s)}_{+ b S(s)}$$

$$\text{Also } x_\beta = \sqrt{\frac{\epsilon \eta}{\pi}} \cos(\psi + \delta)$$

$$x_\beta^2 = \frac{\epsilon \eta}{\pi} \cos^2(\psi + \delta)$$

$$\langle x_\beta^2 \rangle = \frac{\epsilon \eta}{\pi} \langle \cos^2(\psi + \delta) \rangle$$

$$\langle \cos^2 \rangle = \frac{1}{2} \text{ most beams}$$

$$\langle x_p \rangle = \frac{q}{\pi} \langle \underbrace{\varepsilon \cos^2(\theta + \omega)}_{\sim L} \rangle$$

$$= \frac{q}{2\pi} \langle \varepsilon \rangle$$

$\int dx dr d\delta n(x, x', \delta) \varepsilon(x')$

$$\begin{aligned}\langle x^2 \rangle &= \langle (x_p + \delta D)^2 \rangle \\ &= \langle x_p^2 + 2\delta x_p D + \delta^2 D^2 \rangle \\ &= \langle x_p^2 \rangle + 2 \langle \delta x_p \rangle D + \langle \delta^2 \rangle D^2 \\ &= \frac{q}{2\pi} \langle \varepsilon \rangle + \langle \delta^2 \rangle D^2\end{aligned}$$

Errors Changing Closed Orbit:

- ① $\begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$
 - ② $\begin{pmatrix} x \\ x' \end{pmatrix} = M \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$
 - ③ $\begin{pmatrix} x \\ x' \end{pmatrix}_3 = \begin{pmatrix} x \\ x' \end{pmatrix}_2 + \begin{pmatrix} 0 \\ 0 \end{pmatrix}$
 $= M \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \end{pmatrix}$
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Closed Orbit: $\begin{pmatrix} x \\ x' \end{pmatrix}_3 = \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix} = M \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = (I - M) \begin{pmatrix} x_0 \\ x'_0 \end{pmatrix}$$

$$\begin{pmatrix} x_0 \\ x'_0 \end{pmatrix} = (I - M)^{-1} \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$e^{\mu_1 j} = I \cos \mu_1 + J \sin \mu_1$$

$$\begin{aligned}e^{\mu_1 j} e^{\mu_2 j} &= (I \cos \mu_1 + J \sin \mu_1) \\ &\quad \times (I \cos \mu_2 + J \sin \mu_2)\end{aligned}$$

$$= I (\cos \mu_1 \cos \mu_2 - \sin \mu_1 \sin \mu_2)$$

$$+ J (\cos \mu_1 \sin \mu_2 + \sin \mu_1 \cos \mu_2)$$

$$= I \cos(\mu_1 + \mu_2) + J \sin(\mu_1 + \mu_2) = e^{(M_1 + M_2)j}$$

$$\begin{aligned}M &= e^{Mj} \\ &= e^{2\pi i \nu j} \\ \text{where } &\nu = \frac{M}{2\pi} \\ j &= \text{Time}\end{aligned}$$

Example: Sector Bend

$$x'' + \frac{1}{R^2} x = \frac{\delta}{R}$$

$$y'' = 0$$

$$C(s) = \cos \frac{s}{R} \quad S = R \sin \frac{s}{R}$$

$$G(s, s') = S(s) C(s') - C(s) S(s')$$

$$= R \left(\sin \frac{s}{R} \cos \frac{s'}{R} - \cos \frac{s}{R} \sin \frac{s'}{R} \right)$$

$$\begin{aligned} D(s) &= \int_0^s R \left(\sin \frac{s}{R} \cos \frac{s'}{R} - \cos \frac{s}{R} \sin \frac{s'}{R} \right) \frac{ds'}{R} \\ &= \delta \sin \frac{s}{R} \int_0^s \cos \frac{s'}{R} ds' - \delta \cos \frac{s}{R} \int_0^s \sin \frac{s'}{R} ds' \\ &= \delta \underbrace{\sin \frac{s}{R}}_{R \sin \frac{s}{R}} \Big|_0^s + \delta \underbrace{\cos \frac{s}{R}}_{R \cos \frac{s}{R}} \Big|_0^s \\ &= \delta R \left(\underbrace{\sin^2 \frac{s}{R}}_{1} + \underbrace{\cos^2 \frac{s}{R}}_{1} - \cos \frac{s}{R} \right) \\ &= \delta R (1 - \cos \frac{s}{R}) \end{aligned}$$

$$x = x_0 \cos \frac{s}{R} + x'_0 R \sin \frac{s}{R} + \delta R (1 - \cos \frac{s}{R})$$

$$x' = -\frac{1}{R} x_0 \sin \frac{s}{R} + x'_0 \cos \frac{s}{R} + \delta R \sin \frac{s}{R}$$

$$\begin{pmatrix} x \\ x' \\ \delta \end{pmatrix} = \begin{pmatrix} \cos \frac{s}{R} & R \sin \frac{s}{R} & R(1 - \cos \frac{s}{R}) \\ -\frac{1}{R} \sin \frac{s}{R} & \cos \frac{s}{R} & \sin \frac{s}{R} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ x' \\ \delta \end{pmatrix}$$

matrix for hom. eqn. dispers.

